

Balanced Families of Perfect Hash Functions and Their Applications

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Abstract. The construction of perfect hash functions is a well-studied topic. In this paper, this concept is generalized with the following definition. We say that a family of functions from $[n]$ to $[k]$ is a δ -balanced (n, k) -family of perfect hash functions if for every $S \subseteq [n]$, $|S| = k$, the number of functions that are 1-1 on S is between T/δ and δT for some constant $T > 0$. The standard definition of a family of perfect hash functions requires that there will be at least one function that is 1-1 on S , for each S of size k . In the new notion of balanced families, we require the number of 1-1 functions to be almost the same (taking δ to be close to 1) for every such S . Our main result is that for any constant $\delta > 1$, a δ -balanced (n, k) -family of perfect hash functions of size $2^{O(k \log \log k)} \log n$ can be constructed in time $2^{O(k \log \log k)} n \log n$. Using the technique of color-coding we can apply our explicit constructions to devise approximation algorithms for various counting problems in graphs. In particular, we exhibit a deterministic polynomial time algorithm for approximating both the number of simple paths of length k and the number of simple cycles of size k for any $k \leq O(\frac{\log n}{\log \log \log n})$ in a graph with n vertices. The approximation is up to any fixed desirable relative error.

Keywords: approximate counting of subgraphs, color-coding, perfect hashing.

1 Introduction

This paper deals with explicit constructions of balanced families of perfect hash functions. The topic of perfect hash functions has been widely studied under the more general framework of k -restriction problems (see, e.g., [3],[13]). These problems have an existential nature of requiring a set of conditions to hold at least once for any choice of k elements out of the problem domain. We generalize the definition of perfect hash functions, and introduce a new, simple, and

* Research supported in part by a grant from the Israel Science Foundation, and by the Hermann Minkowski Minerva Center for Geometry at Tel Aviv University.

** This paper forms part of a Ph.D. thesis written by the author under the supervision of Prof. N. Alon and Prof. Y. Azar in Tel Aviv University.

yet useful notion which we call balanced families of perfect hash functions. The purpose of our new definition is to incorporate more structure into the constructions. Our explicit constructions together with the method of color-coding from [5] are applied for problems of approximating the number of times that some fixed subgraph appears within a large graph. We focus on counting simple paths and simple cycles. Recently, the method of color-coding has found interesting applications in computational biology ([17],[18],[19],[12]), specifically in detecting signaling pathways within protein interaction. This problem is formalized using an undirected edge-weighted graph, where the task is to find a minimum weight path of length k . The application of our results in this case is for approximating deterministically the number of minimum weight paths of length k .

Perfect Hash Functions. An (n, k) -family of perfect hash functions is a family of functions from $[n]$ to $[k]$ such that for every $S \subseteq [n]$, $|S| = k$, there exists a function in the family that is 1-1 on S . There is an extensive literature dealing with explicit constructions of perfect hash functions. The construction described in [5] (following [11] and [16]) is of size $2^{O(k)} \log n$. The best known explicit construction is of size $e^k k^{O(\log k)} \log n$, which closely matches the known lower bound of $\Omega(e^k \log n / \sqrt{k})$ [15].

Finding and Counting Paths and Cycles. The foundations for the graph algorithms presented in this paper have been laid in [5]. Two main randomized algorithms are presented there, as follows. A simple directed or undirected path of length $k - 1$ in a graph $G = (V, E)$ that contains such a path can be found in $2^{O(k)}|E|$ expected time in the directed case and in $2^{O(k)}|V|$ expected time in the undirected case. A simple directed or undirected cycle of size k in a graph $G = (V, E)$ that contains such a cycle can be found in either $2^{O(k)}|V||E|$ or $2^{O(k)}|V|^\omega$ expected time, where $\omega < 2.376$ is the exponent of matrix multiplication. The derandomization of these algorithms incur an extra $\log |V|$ factor. As for the case of even cycles, it is shown in [20] that for every fixed $k \geq 2$, there is an $O(|V|^2)$ algorithm for finding a simple cycle of size $2k$ in an undirected graph. Improved algorithms for detecting given length cycles have been presented in [6] and [21]. An interesting result from [6], related to the questions addressed in the present paper, is an $O(|V|^\omega)$ algorithm for counting the number of cycles of size at most 7. Flum and Grohe proved that the problem of counting *exactly* the number of paths and cycles of length k in both directed and undirected graphs, parameterized by k , is $\#W[1]$ -complete [10]. Their result implies that most likely there is no $f(k) \cdot n^c$ -algorithm for counting the precise number of paths or cycles of length k in a graph of size n for any computable function $f : \mathbb{N} \rightarrow \mathbb{N}$ and constant c . This suggests the problem of approximating these quantities. Arvind and Raman obtained a *randomized* fixed-parameter tractable algorithm to approximately count the number of copies of a fixed subgraph with bounded treewidth within a large graph [7]. We settle in the affirmative the open question they raise concerning the existence of a *deterministic* approximate counting algorithm for this problem. For simplicity, we give algorithms for approximately counting paths and cycles. These results can be easily extended to the problem

of approximately counting bounded treewidth subgraphs, combining the same approach with the method of [5]. The main new ingredient in our deterministic algorithms is the application of balanced families of perfect hash functions- a combinatorial notion introduced here which, while simple, appears to be very useful.

Balanced Families of Perfect Hash Functions. We say that a family of functions from $[n]$ to $[k]$ is a δ -balanced (n, k) -family of perfect hash functions if for every $S \subseteq [n]$, $|S| = k$, the number of functions that are 1-1 on S is between T/δ and δT for some constant $T > 0$. Balanced families of perfect hash functions are a natural generalization of the usual concept of perfect hash functions. To assist with our explicit constructions, we define also the even more generalized notion of balanced splitters. (See section 2 for the definition. This is a generalization of an ordinary splitter defined in [15].)

Our Results. The main focus of the paper is on explicit constructions of balanced families of perfect hash functions and their applications. First, we give non-constructive upper bounds on the size of different types of balanced splitters. Then, we compare these bounds with those achieved by constructive algorithms. Our main result is an explicit construction, for every $1 < \delta \leq 2$, of a δ -balanced (n, k) -family of perfect hash functions of size $2^{O(k \log \log k)} (\delta - 1)^{-O(\log k)} \log n$. The running time of the procedure that provides the construction is $2^{O(k \log \log k)} (\delta - 1)^{-O(\log k)} n \log n + (\delta - 1)^{-O(k/\log k)}$.

Constructions of balanced families of perfect hash functions can be applied to various counting problems in graphs. In particular, we describe deterministic algorithms that approximate the number of times that a small subgraph appears within a large graph. The approximation is always up to some multiplicative factor, that can be made arbitrarily close to 1. For any $1 < \delta \leq 2$, the number of simple paths of length $k - 1$ in a graph $G = (V, E)$ can be approximated up to a multiplicative factor of δ in time $2^{O(k \log \log k)} (\delta - 1)^{-O(\log k)} |E| \log |V| + (\delta - 1)^{-O(k/\log k)}$. The number of simple cycles of size k can be approximated up to a multiplicative factor of δ in time $2^{O(k \log \log k)} (\delta - 1)^{-O(\log k)} |E| |V| \log |V| + (\delta - 1)^{-O(k/\log k)}$.

Techniques. We use probabilistic arguments in order to prove the existence of different types of small size balanced splitters (whose precise definition is given in the next section). To construct a balanced splitter, a natural randomized algorithm is to choose a large enough number of independent random functions. We show that in some cases, the method of conditional probabilities, when applied on a proper choice of a potential function, can derandomize this process in an efficient way. Constructions of small probability spaces that admit k -wise independent random variables are also a natural tool for achieving good splitting properties. The use of error correcting codes is shown to be useful when we want to find a family of functions from $[n]$ to $[l]$, where l is much bigger than k^2 , such that for every $S \subseteq [n]$, $|S| = k$, almost all of the functions should be 1-1 on S . Balanced splitters can be composed in different ways and our main construction is achieved by composing three types of splitters. We apply the

explicit constructions of balanced families of perfect hash functions together with the color-coding technique to get our approximate counting algorithms.

2 Balanced Families of Perfect Hash Functions

In this section we formally define the new notions of balanced families of perfect hash functions and balanced splitters. Here are a few basics first. Denote by $[n]$ the set $\{1, \dots, n\}$. For any k , $1 \leq k \leq n$, the family of k -sized subsets of $[n]$ is denoted by $\binom{[n]}{k}$. We denote by $k \bmod l$ the unique integer $0 \leq r < l$ for which $k = ql + r$, for some integer q . We now introduce the new notion of balanced families of perfect hash functions.

Definition 1. *Suppose that $1 \leq k \leq n$ and $\delta \geq 1$. We say that a family of functions from $[n]$ to $[k]$ is a δ -balanced (n, k) -family of perfect hash functions if there exists a constant real number $T > 0$, such that for every $S \in \binom{[n]}{k}$, the number of functions that are 1-1 on S , which we denote by $\text{inj}(S)$, satisfies the relation $T/\delta \leq \text{inj}(S) \leq \delta T$.*

The following definition generalizes both the last definition and the definition of a splitter from [15].

Definition 2. *Suppose that $1 \leq k \leq n$ and $\delta \geq 1$, and let H be a family of functions from $[n]$ to $[l]$. For a set $S \in \binom{[n]}{k}$ we denote by $\text{split}(S)$ the number of functions $h \in H$ that split S into equal-sized parts $h^{-1}(j) \cap S$, $j = 1, \dots, l$. In case l does not divide k we separate between two cases. If $k \leq l$, then $\text{split}(S)$ is defined to be the number of functions that are 1-1 on S . Otherwise, $k > l$ and we require the first $k \bmod l$ parts to be of size $\lceil k/l \rceil$ and the remaining parts to be of size $\lfloor k/l \rfloor$. We say that H is a δ -balanced (n, k, l) -splitter if there exists a constant real number $T > 0$, such that for every $S \in \binom{[n]}{k}$ we have $T/\delta \leq \text{split}(S) \leq \delta T$.*

The definitions of balanced families of perfect hash functions and balanced splitters given above enable us to state the following easy composition lemmas.

Lemma 1. *For any $k < l$, let H be an explicit δ -balanced (n, k, l) -splitter of size N and let G be an explicit γ -balanced (l, k) -family of perfect hash functions of size M . We can use H and G to get an explicit $\delta\gamma$ -balanced (n, k) -family of perfect hash functions of size NM .*

Proof. We compose every function of H with every function of G and get the needed result. \square

Lemma 2. *For any $k > l$, let H be an explicit δ -balanced (n, k, l) -splitter of size N . For every j , $j = 1, \dots, l$, let G_j be an explicit γ_j -balanced (n, k_j) -family of perfect hash functions of size M_j , where $k_j = \lceil k/l \rceil$ for every $j \leq k \bmod l$ and $k_j = \lfloor k/l \rfloor$ otherwise. We can use these constructions to get an explicit $(\delta \prod_{j=1}^l \gamma_j)$ -balanced (n, k) -family of perfect hash functions of size $N \prod_{j=1}^l M_j$.*

Proof. We divide the set $[k]$ into l disjoint intervals I_1, \dots, I_l , where the size of I_j is k_j for every $j = 1, \dots, l$. We think of G_j as a family of functions from $[n]$ to I_j . For every combination of $h \in H$ and $g_j \in G_j, j = 1, \dots, l$, we create a new function that maps an element $x \in [n]$ to $g_{h(x)}(x)$. \square

3 Probabilistic Constructions

We will use the following two claims: a variant of the Chernoff bound (c.f., e.g., [4]) and Robbins' formula [9] (a tight version of Stirling's formula).

Claim. Let Y be the sum of mutually independent indicator random variables, $\mu = E[Y]$. For all $1 \leq \delta \leq 2$,

$$Pr\left[\frac{\mu}{\delta} \leq Y \leq \delta\mu\right] > 1 - 2e^{-(\delta-1)^2\mu/8}.$$

Claim. For every integer $n \geq 1$,

$$\sqrt{2\pi}n^{n+1/2}e^{-n+1/(12n+1)} < n! < \sqrt{2\pi}n^{n+1/2}e^{-n+1/(12n)}.$$

Now we state the results for δ -balanced (n, k, l) -splitters of the three types: $k = l$, $k < l$ and $k > l$.

Theorem 1. For any $1 < \delta \leq 2$, there exists a δ -balanced (n, k) -family of perfect hash functions of size $O\left(\frac{e^k \sqrt{k} \log n}{(\delta-1)^2}\right)$.

Proof. (sketch) Set $p = k!/k^k$ and $M = \lceil \frac{8(k \ln n + 1)}{p(\delta-1)^2} \rceil$. We choose M independent random functions. For a specific set $S \in \binom{[n]}{k}$, the expected number of functions that are 1-1 on S is exactly pM . By the Chernoff bound, the probability that for at least one set $S \in \binom{[n]}{k}$, the number of functions that are 1-1 on S will not be as needed is at most

$$\binom{n}{k} 2e^{-(\delta-1)^2 pM/8} \leq 2 \binom{n}{k} e^{-(k \ln n + 1)} < 1. \quad \square$$

Theorem 2. For any $k < l$ and $1 < \delta \leq 2$, there exists a δ -balanced (n, k, l) -splitter of size $O\left(\frac{e^{k^2/l} k \log n}{(\delta-1)^2}\right)$.

Proof. (sketch) We set $p = \frac{l!}{(l-k)l^k}$ and $M = \lceil \frac{8(k \ln n + 1)}{p(\delta-1)^2} \rceil$. Using Robbins' formula, we get

$$\frac{1}{p} \leq e^{k+1/12} \left(1 - \frac{k}{l}\right)^{l-k+1/2} \leq e^{k+1/12} e^{-\frac{k}{l}(l-k+1/2)} = e^{\frac{k^2-k/2}{l} + 1/12}.$$

We choose M independent random functions and proceed as in the proof of Theorem 1. \square

For the case $k > l$, the probabilistic arguments from [15] can be generalized to prove existence of balanced (n, k, l) -splitters. Here we focus on the special case of balanced $(n, k, 2)$ -splitters, which will be of interest later.

Theorem 3. *For any $k \geq 2$ and $1 < \delta \leq 2$, there exists a δ -balanced $(n, k, 2)$ -splitter of size $O(\frac{k\sqrt{k} \log n}{(\delta-1)^2})$.*

Proof. (sketch) Set $M = \lceil \frac{8(k \ln n + 1)}{p(\delta-1)^2} \rceil$, where p denotes the probability to get the needed split in a random function. It follows easily from Robbins' formula that $1/p = O(\sqrt{k})$. We choose M independent random functions and proceed as in the proof of Theorem 1. \square

4 Explicit Constructions

In this paper, we use the term explicit construction for an algorithm that lists all the elements of the required family of functions in time which is polynomial in the total size of the functions. For a discussion on other definitions for this term, the reader is referred to [15]. We state our results for δ -balanced (n, k, l) -splitters of the three types: $k = l$, $k < l$ and $k > l$.

Theorem 4. *For any $1 < \delta \leq 2$, a δ -balanced (n, k) -family of perfect hash functions of size $O(\frac{e^k \sqrt{k} \log n}{(\delta-1)^2})$ can be constructed deterministically within time $\binom{n}{k} \frac{e^k k^{O(1)} n \log n}{(\delta-1)^2}$.*

Proof. We set $p = k!/k^k$ and $M = \lceil \frac{16(k \ln n + 1)}{p(\delta-1)^2} \rceil$. Denote $\lambda = (\delta - 1)/4$, so obviously $0 < \lambda \leq 1/4$. Consider a choice of M independent random functions from $[n]$ to $[k]$. This choice will be derandomized in the course of the algorithm. For every $S \in \binom{[n]}{k}$, we define $X_S = \sum_{i=1}^M X_{S,i}$, where $X_{S,i}$ is the indicator random variable that is equal to 1 iff the i th function is 1-1 on S . Consider the following potential function:

$$\Phi = \sum_{S \in \binom{[n]}{k}} e^{\lambda(X_S - pM)} + e^{\lambda(pM - X_S)}.$$

Its expectation can be calculated as follows:

$$\begin{aligned} E[\Phi] &= \binom{n}{k} (e^{-\lambda pM} \prod_{i=1}^M E[e^{\lambda X_{S,i}}] + e^{\lambda pM} \prod_{i=1}^M E[e^{-\lambda X_{S,i}}]) = \\ &= \binom{n}{k} (e^{-\lambda pM} [pe^\lambda + (1-p)]^M + e^{\lambda pM} [pe^{-\lambda} + (1-p)]^M). \end{aligned}$$

We now give an upper bound for $E[\Phi]$. Since $1 + u \leq e^u$ for all u and $e^{-u} \leq 1 - u + u^2/2$ for all $u \geq 0$, we get that $pe^{-\lambda} + (1-p) \leq e^{p(e^{-\lambda} - 1)} \leq e^{p(-\lambda + \lambda^2/2)}$.

Define $\epsilon = e^\lambda - 1$, that is $\lambda = \ln(1 + \epsilon)$. Thus $pe^\lambda + (1 - p) = 1 + \epsilon p \leq e^{\epsilon p}$. This implies that

$$E[\Phi] \leq n^k \left(\left(\frac{e^\epsilon}{1 + \epsilon} \right)^{pM} + e^{\lambda^2 pM/2} \right).$$

Since $e^u \leq 1 + u + u^2$ for all $0 \leq u \leq 1$, we have that $\frac{e^\epsilon}{1 + \epsilon} = e^{e^\lambda - 1 - \lambda} \leq e^{\lambda^2}$. We conclude that

$$E[\Phi] \leq 2n^k e^{\lambda^2 pM} \leq e^{2(k \ln n + 1)}.$$

We now describe a deterministic algorithm for finding M functions, so that $E[\Phi]$ will still obey the last upper bound. This is performed using the method of conditional probabilities (c.f., e.g., [4], chapter 15). The algorithm will have M phases, where each phase will consist of n steps. In step i of phase j the algorithm will determine the i th value of the j th function. Out of the k possible values, we greedily choose the value that will decrease $E[\Phi]$ as much as possible. We note that at any specific step of the algorithm, the exact value of the conditional expectation of the potential function can be easily computed in time $\binom{n}{k} k^{O(1)}$.

After all the M functions have been determined, every set $S \in \binom{[n]}{k}$ satisfies the following:

$$e^{\lambda(X_S - pM)} + e^{\lambda(pM - X_S)} \leq e^{2(k \ln n + 1)}.$$

This implies that

$$-2(k \ln n + 1) \leq \lambda(X_S - pM) \leq 2(k \ln n + 1).$$

Recall that $\lambda = (\delta - 1)/4$, and therefore

$$\left(1 - \frac{8(k \ln n + 1)}{(\delta - 1)pM}\right)pM \leq X_S \leq \left(1 + \frac{8(k \ln n + 1)}{(\delta - 1)pM}\right)pM.$$

Plugging in the values of M and p we get that

$$\left(1 - \frac{\delta - 1}{2}\right)pM \leq X_S \leq \left(1 + \frac{\delta - 1}{2}\right)pM.$$

Using the fact that $1/u \leq 1 - (u - 1)/2$ for all $1 \leq u \leq 2$, we get the desired result

$$pM/\delta \leq X_S \leq \delta pM.$$

□

Theorem 5. For any $1 < \delta \leq 2$, a δ -balanced $(n, k, \lceil \frac{2k^2}{\delta - 1} \rceil)$ -splitter of size $\frac{k^{O(1)} \log n}{(\delta - 1)^{O(1)}}$ can be constructed in time $\frac{k^{O(1)} n \log n}{(\delta - 1)^{O(1)}}$.

Proof. Denote $q = \lceil \frac{2k^2}{\delta - 1} \rceil$. Consider an explicit construction of an error correcting code with n codewords over alphabet $[q]$ whose normalized Hamming distance is at least $1 - \frac{2}{q}$. Such explicit codes of length $O(q^2 \log n)$ exist [1]. Now let every index of the code corresponds to a function from $[n]$ to $[q]$. If we denote by M

the length of the code, which is in fact the size of the splitter, then for every $S \in \binom{[n]}{k}$, the number of good splits is at least

$$\left(1 - \binom{k}{2} \frac{2}{q}\right)M \geq \left(1 - \frac{\delta - 1}{2}\right)M \geq M/\delta,$$

where the last inequality follows from the fact that $1 - (u - 1)/2 \geq 1/u$ for all $1 \leq u \leq 2$. □

For our next construction we use small probability spaces that support a sequence of almost k -size independent random variables. A sequence X_1, \dots, X_n of random Boolean variables is (ϵ, k) -independent if for any k positions $i_1 < \dots < i_k$ and any k bits $\alpha_1, \dots, \alpha_k$ we have

$$|Pr[X_{i_1} = \alpha_1, \dots, X_{i_k} = \alpha_k] - 2^{-k}| < \epsilon.$$

It is known ([14],[2],[1]) that sample spaces of size $2^{O(k+\log \frac{1}{\epsilon})} \log n$ that support n random variables that are (ϵ, k) -independent can be constructed in time $2^{O(k+\log \frac{1}{\epsilon})} n \log n$.

Theorem 6. *For any $k \geq l$ and $1 < \delta \leq 2$, a δ -balanced (n, k, l) -splitter of size $2^{O(k \log l - \log(\delta-1))} n \log n$ can be constructed in time $2^{O(k \log l - \log(\delta-1))} n \log n$.*

Proof. We use an explicit probability space of size $2^{O(k \log l - \log(\delta-1))} \log n$ that supports $n \lceil \log_2 l \rceil$ random variables that are $(\epsilon, k \lceil \log_2 l \rceil)$ -independent where $\epsilon = 2^{-k \lceil \log_2 l \rceil - 1} (\delta - 1)$. We attach $\lceil \log_2 l \rceil$ random variables to each element of $[n]$, thereby assigning it a value from $[2^{\lceil \log_2 l \rceil}]$. In case l is not a power of 2, all elements of $[2^{\lceil \log_2 l \rceil}] - [l]$ can be mapped to $[l]$ by some arbitrary fixed function. It follows from the construction that there exists a constant $T > 0$ so that for every $S \in \binom{[n]}{k}$, the number of good splits satisfies

$$\frac{T}{\delta} \leq \left(1 - \frac{\delta - 1}{2}\right)T \leq split(S) \leq \left(1 + \frac{\delta - 1}{2}\right)T \leq \delta T.$$

□

Corollary 1. *For any fixed $c > 0$, a $(1 + c^{-k})$ -balanced $(n, k, 2)$ -splitter of size $2^{O(k)} \log n$ can be constructed in time $2^{O(k)} n \log n$.*

Setting $l = k$ in Theorem 6, we get that a δ -balanced (n, k) -family of perfect hash functions of size $2^{O(k \log k - \log(\delta-1))} \log n$ can be constructed in time $2^{O(k \log k - \log(\delta-1))} n \log n$. Note that if k is small enough with respect to n , say $k = O(\log n / \log \log n)$, then for any fixed $1 < \delta \leq 2$, this already gives a family of functions of size polynomial in n . We improve upon this last result in the following Theorem, which is our main construction.

Theorem 7. *For $1 < \delta \leq 2$, a δ -balanced (n, k) -family of perfect hash functions of size $\frac{2^{O(k \log \log k)}}{(\delta-1)^{O(\log k)}} \log n$ can be constructed in time $\frac{2^{O(k \log \log k)}}{(\delta-1)^{O(\log k)}} n \log n + (\delta - 1)^{-O(k/\log k)}$. In particular, for any fixed $1 < \delta \leq 2$, the size is $2^{O(k \log \log k)} \log n$ and the time is $2^{O(k \log \log k)} n \log n$.*

Proof. (sketch) Denote $l = \lceil \log_2 k \rceil$, $\delta' = \delta^{1/3}$, $\delta'' = \delta^{1/(3l)}$, and $q = \lceil \frac{2k^2}{\delta'^2 - 1} \rceil$. Let H be a δ' -balanced (q, k, l) -splitter of size $2^{O(k \log \log k)} (\delta' - 1)^{-O(1)}$ constructed using Theorem 6. For every j , $j = 1, \dots, l$, let B_j be a δ'' -balanced (q, k_j) -family of perfect hash functions of size $O(e^{k/\log k} k) (\delta'' - 1)^{-O(1)}$ constructed using Theorem 4, where $k_j = \lceil k/l \rceil$ for every $j \leq k \bmod l$ and $k_j = \lfloor k/l \rfloor$ otherwise. Using Lemma 2 for composing H and $\{B_j\}_{j=1}^l$, we get a δ'^2 -balanced (q, k) -family D' of perfect hash functions.

Now let D'' be a δ' -balanced (n, k, q) -splitter of size $k^{O(1)} (\delta' - 1)^{-O(1)} \log n$ constructed using Theorem 5. Using Lemma 1 for composing D' and D'' , we get a δ -balanced (n, k) -family of perfect hash functions, as needed. Note that for calculating the size of each B_j , we use the fact that $e^{u/2} \leq 1 + u \leq e^u$ for all $0 \leq u \leq 1$, and get the following:

$$\delta'' - 1 = (1 + (\delta - 1))^{\frac{1}{3l}} - 1 \geq e^{\frac{\delta - 1}{6l}} - 1 \geq \frac{\delta - 1}{6l}.$$

The time needed to construct each B_j is $2^{O(k)} (\delta' - 1)^{-O(k/\log k)}$. The $2^{O(k)}$ term is omitted in the final result, as it is negligible in respect to the other terms. \square

5 Approximate Counting of Paths and Cycles

We now state what it means for an algorithm to approximate a counting problem.

Definition 3. *We say that an algorithm approximates a counting problem by a multiplicative factor $\delta \geq 1$ if for every input x , the output $ALG(x)$ of the algorithm satisfies $N(x)/\delta \leq ALG(x) \leq \delta N(x)$, where $N(x)$ is the exact output of the counting problem for input x .*

The technique of color-coding is used for approximate counting of paths and cycles. Let $G = (V, E)$ be a directed or undirected graph. In our algorithms we will use constructions of balanced $(|V|, k)$ -families of perfect hash functions. Each such function defines a coloring of the vertices of the graph. A path is said to be *colorful* if each vertex on it is colored by a distinct color. Our goal is to count the exact number of colorful paths in each of these colorings.

Theorem 8. *For any $1 < \delta \leq 2$, the number of simple (directed or undirected) paths of length $k - 1$ in a (directed or undirected) graph $G = (V, E)$ can be approximated up to a multiplicative factor of δ in time $\frac{2^{O(k \log \log k)}}{(\delta - 1)^{O(k/\log k)}} |E| \log |V| + (\delta - 1)^{-O(k/\log k)}$.*

Proof. (sketch) We use the δ -balanced $(|V|, k)$ -family of perfect hash functions constructed using Theorem 7. Each function of the family defines a coloring of the vertices in k colors. We know that there exists a constant $T > 0$, so that for each set $S \subseteq V$ of k vertices, the number of functions that are 1-1 on S is between T/δ and δT . The exact value of T can be easily calculated in all of our explicit constructions.

For each coloring, we use a dynamic programming approach in order to calculate the exact number of colorful paths. We do this in k phases. In the i th phase, for each vertex $v \in V$ and for each subset $C \subseteq \{1, \dots, k\}$ of i colors, we calculate the number of colorful paths of length $i - 1$ that end at v and use the colors of C . To do so, for every edge $(u, v) \in E$, we check whether it can be the last edge of a colorful path of length $i - 1$ ending at either u or v . Its contribution to the number of paths of length $i - 1$ is calculated using our knowledge on the number of paths of length $i - 2$. The initialization of phase 1 is easy and after performing phase k we know the exact number of paths of length $k - 1$ that end at each vertex $v \in V$. The time to process each coloring is therefore $2^{O(k)}|E|$.

We sum the results over all colorings and all ending vertices $v \in V$. The result is divided by T . In case the graph is undirected, we further divide by 2. This is guaranteed to be the needed approximation. \square

Theorem 9. *For any $1 < \delta \leq 2$, the number of simple (directed or undirected) cycles of size k in a (directed or undirected) graph $G = (V, E)$ can be approximated up to a multiplicative factor of δ in time $\frac{2^{O(k \log \log k)}}{(\delta - 1)^{O(\log k)}}|E||V| \log |V| + (\delta - 1)^{-O(k/\log k)}$.*

Proof. (sketch) We use the δ -balanced $(|V|, k)$ -family of perfect hash functions constructed using Theorem 7. For every set S of k vertices, the number of functions that are 1-1 on S is between T/δ and δT . Every function defines a coloring and for each such coloring we proceed as follows. For every vertex $s \in V$ we run the algorithm described in the proof of Theorem 8 in order to calculate for each vertex $v \in V$ the exact number of colorful paths of length $k - 1$ from s to v . In case there is an edge (v, s) that completes a cycle, we add the result to our count.

We sum the results over all the colorings and all pairs of vertices s and v as described above. The result is divided by kT . In case the graph is undirected, we further divide by 2. The needed approximation is achieved. \square

Corollary 2. *For any constant $c > 0$, there is a deterministic polynomial time algorithm for approximating both the number of simple paths of length k and the number of simple cycles of size k for every $k \leq O(\frac{\log n}{\log \log \log n})$ in a graph with n vertices, where the approximation is up to a multiplicative factor of $1 + (\ln \ln n)^{-c \ln \ln n}$.*

6 Concluding Remarks

- An interesting open problem is whether for every fixed $\delta > 1$, there exists an explicit δ -balanced (n, k) -family of perfect hash functions of size $2^{O(k)} \log n$. The key ingredient needed is an improved construction of balanced $(n, k, 2)$ -splitters. Such splitters can be applied successively to get the balanced $(n, k, \lceil \log_2 k \rceil)$ -splitter needed in Theorem 7. It seems that the constructions presented in [2] could be good candidates for balanced $(n, k, 2)$ -splitters, although the Fourier analysis in this case (along the lines of [8]) seems elusive.

- Other algorithms from [5] can be generalized to deal with counting problems. In particular it is possible to combine our approach here with the ideas of [5] based on fast matrix multiplication in order to approximate the number of cycles of a given length. Given a forest F on k vertices, the number of subgraphs of G isomorphic to F can be approximated using a recursive algorithm similar to the one in [5]. For a weighted graph, we can approximate, for example, both the number of minimum (maximum) weight paths of length $k - 1$ and the number of minimum (maximum) weight cycles of size k . Finally, all the results can be readily extended from paths and cycles to arbitrary small subgraphs of bounded tree-width. We omit the details.
- In the definition of a balanced (n, k) -family of perfect hash functions, there is some constant $T > 0$, such that for every $S \subseteq [n]$, $|S| = k$, the number of functions that are 1-1 on S is close to T . We note that the value of T need not be equal to the expected number of 1-1 functions on a set of size k , for the case that the functions were chosen independently according to a uniform distribution. For example, the value of T in the construction of Theorem 7 is not even asymptotically equal to what one would expect in a uniform distribution.

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