

Rolling backwards can move you forward: on embedding problems in sparse expanders

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Abstract

We develop a general embedding method based on the Friedman-Pippenger tree embedding technique and its algorithmic version, enhanced with a roll-back idea allowing a sequential retracing of previously performed embedding steps. We use this method to obtain the following results.

- We show that the size-Ramsey number of logarithmically long subdivisions of bounded degree graphs is linear in their number of vertices, settling a conjecture of Pak (2002).
- We give a deterministic, polynomial time online algorithm for finding vertex-disjoint paths of a prescribed length between given pairs of vertices in an expander graph. Our result answers a question of Alon and Capalbo (2007).
- We show that relatively weak bounds on the spectral ratio λ/d of d -regular graphs force the existence of a topological minor of K_t where $t = (1 - o(1))d$. We also exhibit a construction which shows that the theoretical maximum $t = d + 1$ cannot be attained even if $\lambda = O(\sqrt{d})$. This answers a question of Fountoulakis, Kühn and Osthus (2009).

1 Introduction

Given a graph H from some class of graphs and a graph G with specific properties, does H embed in G , that is, is there a copy of H in G ? This general question is one of the central settings of combinatorics. Embedding questions lie at the heart of many classic problems, in particular problems in graph Ramsey theory and Turán-type extremal theory.

The main topic of our study concerns embedding problems where the host graph G is a *sparse expander*: the number of edges in G is linear¹ in its number of vertices and all sets of vertices S of (up to) a certain size have a relatively large external neighborhood. This is a natural and important setup both for theoretical and practical reasons, and its potential applicability ranges from problems in extremal combinatorics such as Ramsey-type problems,

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¹Some of our results are also presented in the case where the number of edges is of order n^{1+c} for some (usually small) constant c .

to the construction of lean but resilient networks in computer networking. For a comprehensive source of information about expanders, see the survey of Hoory, Linial and Wigderson [35].

Closely related to expander graphs is the notion of *pseudo-random graphs*. Informally, a graph is pseudo-random if it behaves similarly to a random graph with respect to edge distribution. A prominent class of examples of such graphs are (n, d, λ) -graphs, introduced by Alon [2].

Definition 1.1. *A d -regular graph G on n vertices is an (n, d, λ) -graph if all of the eigenvalues of its adjacency matrix, except the largest one, are at most λ in absolute value.*

It is well known that the smaller λ is, the closer the graph resembles a random graph in terms of edge distribution (see Section 1.1.1 for details). A small λ also means that the graph has good expansion properties and we will use a few such results throughout the paper. For a survey on pseudo-random graphs, see the paper of Krivelevich and Sudakov [42].

For our embedding problems, usually the host graph G will be an (n, d, λ) -graph, for sufficiently small λ and a constant d . What kind of subgraphs can we hope to find in such graphs? One restriction is that the girth of the graph we embed is $\Omega(\log n)$, as there exist (n, d, λ) -graphs with small *spectral ratio* λ/d and of logarithmic girth, as shown in the seminal paper of Lubotzky, Phillips and Sarnak [45]. Thus we are naturally confined to embedding trees and graphs with large girth.

There is a large body of research devoted to finding (linear sized or spanning) bounded degree trees in sparse expanders and in sparse random graphs. Beck [10] used results about long paths in expanding graphs to argue that one can find monochromatic linear sized paths in 2-colored sparse random graphs. Friedman and Pippenger [28] proved an analogous statement for arbitrary bounded degree trees in sparse expanders, and a further improvement on the size of a tree one can embed was obtained by Haxell [32]. Alon, Krivelevich and Sudakov [6] proved the existence of every almost-spanning tree of bounded degree in both sparse random graphs and in appropriate (n, d, λ) -graphs, and the dependency of constants was later improved by Balogh, Csaba and Samotij and Pei [8]. A resilience version of this result was obtained in [9]. Finally, resolving an old conjecture of Kahn (see [37]), Montgomery [48] recently proved that a random graph $G(n, p)$, with $p = \frac{C \log n}{n}$, typically contains every spanning tree of maximum degree at most d , for a given constant d and sufficiently large $C = C(d)$. For results about finding minors in sparse expanders, see, e.g. [47, 55].

In this paper, we present three different results related to embedding into sparse expanders. The first deals with size-Ramsey numbers of logarithmic subdivisions of bounded degree graphs and resolves a conjecture of Pak from 2002 [49]. The second result is concerned with the classic problem of finding vertex-disjoint paths in graphs, and resolves a problem of Alon and Capalbo from 2007 [4]. Finally, the third concerns finding topological minors of complete graphs in (n, d, λ) -graphs, and is related to a question of Fountoulakis, Kühn and Osthus [27]. For those three problems we develop two variations of our embedding technique. Both are based on the result of Friedman and Pippenger [28] about embedding trees in expander graphs vertex by vertex and an idea by Daniel Johannsen [36], which allows us to successively remove vertices from the list of already embedded vertices. This *roll-back* result turns out to be very powerful for tackling such problems. One of the variants which we show is algorithmic and uses ideas by Dellamonica and Kohayakawa [18], who showed an algorithmic version of the original Friedman-Pippenger embedding result by reducing it to a certain online matching problem solved by Aggarwal et al. [1]. We now describe these results in details.

1.1 Size-Ramsey numbers of subdivided graphs

Given a graph H and an integer $k \geq 2$, a graph G is said to be k -Ramsey for H if every coloring of the edges of G with k colors contains a monochromatic copy of H . This notion was introduced by Ramsey [51], who proved that for every graph H there exists $N \in \mathbb{N}$ such that K_N is k -Ramsey for H . The smallest such N , denoted by $R_k(H)$, is called the *Ramsey number*. Determining the asymptotic order of $R_2(K_\ell)$ is one of the most important open problems in this area [15, 56]. We are concerned with the related notion of *size-Ramsey numbers*, introduced by Erdős, Faudree, Rousseau and Schelp [24]. Given a graph H and an integer $k \geq 2$, the *size-Ramsey number* $\hat{R}_k(H)$ is the smallest integer m such that there exists a graph G with m edges which is k -Ramsey for H . The existence of the Ramsey number immediately implies the upper bound $\hat{R}_k(H) \leq \binom{R_k(H)}{2}$. Other related notions include Folkman numbers, chromatic-Ramsey numbers, and degree-Ramsey numbers. We refer the reader to a survey by Conlon, Fox and Sudakov [16] for a thorough treatment of the topic.

Answering a \$100 question of Erdős [22], Beck [10] showed that paths have linear size-Ramsey number, that is $\hat{R}_2(P_n) \leq Cn$ for an absolute constant C . He also raised the question [11] of whether $\hat{R}_2(H)$ grows linearly for graphs with a bounded maximum degree. This was proven for trees by Friedman and Pippenger [28], for cycles by Haxell, Kohayakawa and Łuczak [33] and more recently, for powers of bounded-degree trees by Berger et al. [12], and more generally, by Letzter, Pokrovskiy and Yepremyan [43] for powers of hypergraph trees. However, the general case was settled in the negative by Rödl and Szemerédi [52], who showed that there exists a constant $c > 0$ such that for every sufficiently large n there is a graph H with n vertices and maximum degree 3 for which $\hat{R}_2(H) \geq n \log^c n$. In the same paper, they conjectured that $\log^c n$ can be improved to n^ε for some constant $\varepsilon > 0$, but this remains open.

1.1.1 Subdivisions of graphs

Since we are far from understanding size-Ramsey numbers of bounded degree graphs in general, one natural step in this direction is to consider subdivisions of those graphs. Given a graph H and a function $\sigma: E(H) \rightarrow \mathbb{N}$, the σ -subdivision H^σ of H is the graph obtained from H by replacing each edge $e \in E(H)$ with a path of length $\sigma(e)$ joining the endpoints of e , such that all these paths are mutually vertex-disjoint (except possibly at the endpoints). In other words, each edge $e \in E(H)$ is subdivided $\sigma(e) - 1$ times. If $\sigma(e) = q$ is a constant function, we simply write H^q to denote such graph H^σ .

Size-Ramsey numbers of ‘short’ subdivisions were first studied by Kohayakawa, Retter and Rödl [38]. In a recent paper [20] we improved their bounds by showing that $\hat{R}_k(H^q) \leq O(n^{1+1/q})$, for given constants q, k and any bounded degree graph H with n vertices, thus removing a polylogarithmic factor from their bound and answering their question. In general, subdivided graphs were considered in the context of Ramsey theory by Burr and Erdős [14] and by Alon [3], and more recently in the context of Ramsey theory in tournaments [21, 31].

In Section 3.1 (Theorem 1) we show that long subdivisions of bounded degree graphs have linear size-Ramsey numbers (in their order), answering the following conjecture by Pak [49].

Conjecture 1.2 ([49]). *For every $k, D \in \mathbb{N}$ there exist $C, L > 0$ such that if H is a graph with $\Delta(H) \leq D$ and $\sigma(e) = \ell \geq L \log(v(H^\sigma))$ for all $e \in E(H)$, then $\hat{R}_k(H^\sigma) \leq Cv(H^\sigma)$.*

Pak [49] showed $\hat{R}_k(H^\sigma) = O(v(H^\sigma) \log^3(v(H^\sigma)))$, and the special case where H is a fixed

(small) graph and $\sigma(e)$ grows was resolved by Donadelli, Haxell and Kohayakawa [19]. To state our result we recall the notion of η -uniform graphs.

Definition 1.3. *Given $0 < \eta \leq 1/2$, we say that a graph G with n vertices and density $p = e(G)/\binom{n}{2}$ is η -uniform if for every pair of disjoint subsets $U, W \subseteq V(G)$ of size $|U|, |W| \geq \eta n$, we have*

$$|e(U, W) - |U||W|p| \leq \eta|U||W|p.$$

We show that every η -uniform graph on n vertices is k -Ramsey for H^σ with $v(H^\sigma) \leq \alpha n$ and $\sigma(e) \geq \log n$, for some small $\alpha > 0$. As a typical random graph with n vertices and $m = Cn$ edges is η -uniform, for sufficiently large C , there are an abundance of η -uniform graphs with $O(n)$ edges, thus confirming Conjecture 1.2.

Theorem 1. *For every $k, D \in \mathbb{N}$ and for every $\delta > 0$, there exist $\eta, \alpha > 0$, such that the following holds for every η -uniform graph G with n vertices: every k -edge-coloring of G contains a monochromatic copy of every graph H^σ , where H is a graph with maximum degree at most D , $v(H^\sigma) \leq \alpha n$ and $\sigma(e) \geq \delta \log n$ for every $e \in E(H)$.*

At first it might seem suspicious that we are not posing any lower bound on the number of edges of G . However, the assumption that G is η -uniform comes with an implicit bound $e(G) \geq Cn$ for some constant $C = C(\eta)$, which can be made arbitrarily large by assuming η to be sufficiently small.

Besides random graphs, explicit constructions of η -uniform graphs of constant average degree are also known. One class of examples of such graphs are (n, d, λ) -graphs, for suitably chosen parameters. Indeed, the well known Expander Mixing Lemma [5] states that for every (n, d, λ) -graph G and for every $U, V \subseteq V(G)$ it holds:

$$\left| e_G(U, V) - \frac{d|U||V|}{n} \right| \leq \lambda \sqrt{|U||V|}. \quad (1)$$

From this, one can see that every (n, d, λ) -graph is η -uniform for $\eta = 2\sqrt{\frac{\lambda}{d}}$. Hence, for a fixed d , the parameter λ is accountable for the uniformity of the distribution of the edges of a d -regular graph. But how small can λ be in terms of d , so that there exists a (n, d, λ) -graph? One can show that $\lambda = \Omega(\sqrt{d})$ for every such graph whenever $d < 0.99n$, and there are known constructions of d -regular graphs for which λ attains this bound, and n is arbitrarily large. This provides us with examples of bounded degree graphs which are η -uniform (for $\eta \sim d^{-1/4}$). For several constructions of such graphs, see, e.g., [42]. As discussed above, there are known constructions of such graphs which have logarithmic girth, showing that our result is asymptotically tight with respect to the bound on σ . Indeed, if H is a triangle, and G is a graph with a girth strictly larger than $c \log n$, then G does not contain H^σ for any σ bounded from above uniformly by $c \log n/3$.

Note that Theorem 1 is in fact a *universality* result, meaning that the η -uniform graph in question is k -Ramsey for *all* graphs in the class we are interested in, hence our theorem confirms Pak's conjecture in a strong way. Furthermore, from our proof it can be seen that we actually find a monochromatic subgraph of the graph we color, which contains all described subdivided graphs. Extending the definition in [39], we say that a graph G is *k -partition universal* for a class of graphs \mathcal{F} if for every k -coloring of the edges of G , there exists a monochromatic

subgraph of G which contains a copy of every graph in \mathcal{F} . Under this framework, we actually prove that the graph we color is up to a constant factor the optimal k -partition universal graph for the class of all described subdivisions of graphs. For further universality-type results in Ramsey theory see for example [17, 20, 38, 39].

1.2 The vertex-disjoint paths problem

For a given graph G and a collection of k disjoint pairs of vertices (a_i, b_i) from G , can we find for each i a path from a_i to b_i , such that the found paths are all vertex-disjoint? This decision problem is \mathcal{NP} -complete [30] when G is allowed to be an arbitrary graph. Furthermore, it remains \mathcal{NP} -complete even when G is restricted to the class of planar graphs. For fixed k , it is shown to be in \mathcal{P} [53]. A variant of this problem in random graphs was studied independently by Hochbaum [34], and by Shamir and Upfal [54]. Both papers proved that for a fixed set of $O(\sqrt{n})$ disjoint pairs of vertices in the random graph $G(n, m)$, with high probability (whp) there exist vertex-disjoint paths between every pair if $m > Cn \log n$, for a constant $C > 1$. Subsequently, Broder, Frieze, Suen and Upfal [13] improved this result:

Theorem 1.4 ([13]). *There exist $\alpha, \beta > 0$, such that whp the following holds. Let $G = G(n, m)$ for $m = (\log n + \omega(1))\frac{n}{2}$, and let $d = 2m/n$. For every collection \mathcal{F} of at most $\alpha\frac{n \log d}{\log n}$ disjoint pairs of vertices (a_i, b_i) in G , there exists a path for every i connecting a_i to b_i , such that all paths are vertex-disjoint, if the following condition is satisfied for every vertex $v \in V(G)$:*

$$|N_G(v) \cap (A \cup B)| < \beta d_G(v) \quad \text{where} \quad A = \cup_i \{a_i\} \text{ and } B = \cup_i \{b_i\}.$$

This is an improvement over the aforementioned papers in several aspects. The number of pairs is optimal up to a constant factor — most pairs in $G(n, m)$ are at distance $\Omega(\log n / \log d)$, so in general one can hope to connect at most $O(\frac{n \log d}{\log n})$ pairs (a_i, b_i) in a graph on n vertices. Furthermore, the pairs (a_i, b_i) are not fixed before generating $G(n, m)$, but are rather chosen adversarially after having exposed a random graph $G \sim G(n, m)$. The last constraint is also optimal up to a constant factor — if the adversary chooses all neighbors of, say, a_1 to be contained in pairs from \mathcal{F} , then obviously one cannot find the requested disjoint paths. The bound on the number of edges m is also asymptotically optimal, as this many edges are needed for G to be connected whp.

Changing the focus to the sparse(r) setting, Alon and Capalbo [4] studied graphs with constant average degree with good expansion properties. In particular, they proved that for any graph G which is a d -blowup² of a (n, d, λ) -graph with a small spectral ratio, and any collection of $O\left(\frac{nd \log d}{\log n}\right)$ pairs of vertices in G which satisfy a similar local condition like in [13], one can connect those pairs with vertex-disjoint paths. The number of pairs is optimal up to a constant factor, and they provide an online polynomial time algorithm for finding them.

The argument of Alon and Capalbo does not allow the length of the paths found by the algorithm to be controlled. Accordingly, they ask for a similar result where the length of the paths between each pair is $\Theta(\log n)$. In Section 3.2, we prove such a result (Theorem 2). Furthermore, we do it not only for blowups, but directly for (n, d, λ) -graphs for $\lambda < d^{0.99}$. We

²The d -blowup of a graph G is the graph obtained from G by replacing each vertex v with an independent set I_v of size d , and replacing every edge (v, u) with a complete bipartite graph between I_v and I_u .

get the optimal dependency on n and d , both for the number of pairs and for the upper bound on the length of the paths. Finally, our algorithm is online in the sense that an adversary can choose the pairs one by one, where the next pair is given after the connection for the previous one is established.

Theorem 2. *Let $0 < \varepsilon < \frac{1}{4}$, and let G be an (n, d, λ) -graph, with $\lambda < d^{1-\varepsilon}/320$ and $d^\varepsilon \geq 5$. Let S be any set of vertices which satisfies $|N_G(x) \cap S| \leq \frac{d}{4}$ for every $x \in V(G)$. Let $P = \{a_i, b_i\}$ be a collection of at most $\frac{\varepsilon n \log d}{480 \log n}$ disjoint pairs of vertices from S . There exists a polynomial time algorithm to find vertex-disjoint paths in G between every pair of vertices $\{a_i, b_i\}$, such that the paths are of equal length which is less than $5 \frac{\log n}{\varepsilon \log d}$. Furthermore, the pairs (a_i, b_i) are given one by one, and the next pair is revealed when the previous connection is made; all established connections cannot be changed.*

Note that d can be large in the previous statement (even linear in n), but the most interesting case is when d is constant, as it is harder to make the connections in sparser regimes.

These results are closely related to the study of non-blocking networks which arise in a variety of applications, including construction of communication networks and distributed-memory architectures. For some results see, e.g., [25, 26, 50]. In contrast to our results, the graphs which are usually considered here have pre-determined sets of vertices ("inputs" and "outputs") from which the pairs are chosen, while the pairs in our result can be chosen by an adversary, but in such a way that they satisfy an essentially minimal local property. Besides that, the path lengths in some constructions of non-blocking networks are also of optimal $O(\log n)$ size [7]. Hence, in some sense our results are a common generalization of [7] and [4], as we both allow the adversary to choose the pairs, and our paths are logarithmic in size, although our algorithm is less efficient than the one in [7]. It can also be seen from our proof that we can allow the adversary to terminate arbitrarily previously established connections between pairs (and thus freeing the used vertices in the corresponding paths) a finite number of times during the mentioned online algorithm. This feature is related to the study of permutation networks [1].

A lot of attention has also been paid to the edge-disjoint paths problem. For a short survey, see [29], and for a result on edge-disjoint paths in sufficiently strong expander graphs see [4].

1.3 Topological minors

We will use the tools developed for proving Theorem 2 to derive results about topological minors in expander graphs. We say that a graph H is a *topological minor* of a graph G if there is a subdivision of H which is a subgraph in G ; the vertices in this subdivision which correspond to vertices of H we call *branching vertices*. Given an (n, d, λ) -graph G , how large can t be such that K_t is a topological minor of G ? Since G is d -regular, the best one could hope for is $t = d + 1$. We show that there is a topological minor of K_t in (n, d, λ) -graphs for $t = (1 - o(1))d$, assuming $\lambda = o(d)$. Furthermore, if $\lambda < d^{1-\varepsilon}$ we find a topological minor on the asymptotically smallest possible number of vertices $O(d^2 \frac{\log n}{\log d})$, where all the paths which connect the branching vertices are of the same length ℓ with $\ell = O(\frac{\log n}{\log d})$. Note that we also need a non-trivial upper bound on d , since using a well known argument of Erdős and Fajtlowitz [23], one can show that d can be at most of order \sqrt{n} , if we want to guarantee a topological minor of K_t with $t = (1 - o(1))d$; for our argument we take $d = O(n^{1/5})$.

Theorem 3. *Let G be a (n, d, λ) -graph with $240\lambda < d \leq n^{1/5}/2$, and let d_0 be such that $d_0 \geq 3$. Then G contains a topological minor of K_t for $t = \lfloor d - 80\lambda\sqrt{d_0} \rfloor$, the paths between branching vertices being of equal length ℓ , where $\ell = O\left(\frac{\log n}{\log d_0}\right)$.*

Theoretically, one might hope to find topological minors of K_{d+1} , but we show that there exist (n, d, λ) -graphs with $\lambda = O(\sqrt{d})$ which do not contain a topological minor of K_{d+1} . This is related to a question of Fountoulakis, Kühn and Osthus [27], for which we will need the following definition. We say that a graph G is (s, K) -*expanding* if for every subset $X \subseteq V(G)$ of size $|X| \leq s$ we have $|N_G(X)| \geq K|X|$. They ask to determine the parameters α, K such that every $(\alpha n, K)$ -expanding d -regular graph on n vertices contains a topological minor of K_{d+1} . In particular, they ask whether constant expansion not depending on d already forces a topological minor of K_{d+1} in a d -regular graph. We answer this question in the negative and show that there exist d -regular graphs with very strong expansion properties, but without a topological minor of K_{d+1} . In particular, for $\alpha = \alpha(d) > 0$, we show the existence of $(2d + 1)$ -regular $(\alpha n, d - 3)$ -expanding graphs without a topological minor of K_{2d+2} .

1.4 Outline of the paper and notation

In Section 2 we show two versions of our main embedding technique — in Section 2.1 we show the non-algorithmic version of it, and in Section 2.2 we give an algorithmic version of the technique. In Section 3, we prove our main results — Theorem 1 (the resolution of Pak’s conjecture) in Section 3.1, and Theorem 2 (vertex-disjoint paths in (n, d, λ) -graphs) in Section 3.2. Finally, in Section 3.3 we present results about topological minors in expander graphs and in particular prove Theorem 3.

Notation. We follow standard graph theoretic notation. In particular, given a graph G and a vertex $x \in V(G)$, we denote by $N_G(x)$ the neighborhood of x in G . For a subset of vertices $X \subseteq V(G)$ we denote by $\Gamma_G(X)$ the neighborhood of X , that is $\Gamma_G(X) = \bigcup_{x \in X} N_G(x)$, and we denote by $N_G(X)$ the external neighborhood of X , that is $N_G(X) = \Gamma_G(X) \setminus X$. By $\partial_G(x)$ we denote the set of edges incident with vertex x in G . Given disjoint subsets of vertices $A, B \subseteq V(G)$, we denote by $e_G(A, B)$ the number of edges with one endpoint in A and the other in B , and with $d_G(A, B) = e_G(A, B)/|A||B|$ the density of such an induced bipartite graph. We denote by $v(G)$ the number of vertices of G , and by $e(G)$ the number of edges of G . Given graphs G and H , we say that a mapping $\phi: V(H) \rightarrow V(G)$ is an *embedding*, with the notation $\phi: H \hookrightarrow G$, if it is injective and preserves the edges of H (i.e. if $\{v, w\} \in E(H)$ then $\{\phi(v), \phi(w)\} \in E(G)$). For an embedding $\phi: H \hookrightarrow G$ and subsets $S_1 \subseteq V(H), S_2 \subseteq V(G)$ we denote by $\phi(S_1)$ the image of S_1 under ϕ , and by $\phi^{-1}(S_2)$ the preimage of S_2 under ϕ , i.e. $\phi(S_1) = \{y \in V(G) \mid \exists x \in S_1: \phi(x) = y\}$, and $\phi^{-1}(S_2) = \{x \in V(H) \mid \phi(x) \in S_2\}$. We omit floors and ceilings whenever it is not crucial. Given two constants ε and α , we use somewhat informal notation $\varepsilon \ll \alpha$ to denote that ε is sufficiently small compared to α . We denote by $\log n$ the natural logarithm of n and by \mathbb{N} the set of positive integers.

2 Friedman-Pippenger type embedding theorems

Now we describe the main embedding machinery behind our proofs. It relies on the idea of Friedman and Pippenger, used for embedding trees in expanders vertex by vertex, by maintaining a certain invariant. An algorithmic version of this technique was presented by Dellamonica and Kohayakawa, based on a result about an online matching game by Aggarwal et al. [1]. In the following two subsections, we give two embedding theorems, non-algorithmic and algorithmic, enhanced with a roll-back idea which allows us to sequentially retrace previously performed embedding steps. While the algorithmic result requires the host graph to have stronger expansion properties, it also enables us to embed larger graphs than with the technique described in Section 2.1.

2.1 The original Friedman-Pippenger theorem with rollbacks

We start with a standard definition of expansion.

Definition 2.1. *Let $s \in \mathbb{N}$ and $K > 0$. We say that a graph G is (s, K) -expanding if for every subset $X \subseteq V(G)$ of size $|X| \leq s$ we have $|N_G(X)| \geq K|X|$.*

In order to develop our machinery, we define the notion of an (s, D) -good embedding.

Definition 2.2. *Let G be a graph and let $s, D \in \mathbb{N}$. Given a graph F with maximum degree at most D , we say that an embedding $\phi: F \hookrightarrow G$ is (s, D) -good if*

$$|\Gamma_G(X) \setminus \phi(F)| \geq \sum_{v \in X} [D - \deg_F(\phi^{-1}(v))] + |\phi(F) \cap X| \quad (2)$$

for every $X \subseteq V(G)$ of size $|X| \leq s$. Here we slightly abuse the notation by setting $\deg_F(\emptyset) := 0$, i.e. if a vertex $v \in V(G)$ is not used by ϕ to embed F , then we set $\deg_F(\phi^{-1}(v)) = 0$.

We remark that the notion of a good embedding is the same as the one used by Friedman and Pippenger [28] up to the last term on the right side of the inequality. The proof of the following theorem is almost identical to the one in [28], and we present it in the Appendix for completeness.

Theorem 2.3. *Let F be a graph with $\Delta(F) \leq D$ and $v(F) < s$, for some $D, s \in \mathbb{N}$. Suppose we are given a $(2s-2, D+2)$ -expanding graph G and a $(2s-2, D)$ -good embedding $\phi: F \hookrightarrow G$. Then for every graph F' with $v(F') \leq s$ and $\Delta(F') \leq D$ which can be obtained from F by successively adding a new vertex of degree 1, there exists a $(2s-2, D)$ -good embedding $\phi': F' \hookrightarrow G$ which extends ϕ .*

The second result we need is a simple corollary of the definition of (s, D) -goodness. While easy to prove, this observation [36] turns out to yield a powerful method for connecting vertices in expanding graphs. It has also been utilized in the recent paper by Montgomery [48] for embedding spanning trees in random graphs.

Lemma 2.4. *Suppose we are given graphs G and F with $\Delta(F) \leq D$, and an (s, D) -good embedding $\phi: F \hookrightarrow G$, for some $s, D \in \mathbb{N}$. Then for every graph F' obtained from F by successively removing a vertex of degree 1, the restriction ϕ' of ϕ to F' is also (s, D) -good.*

Proof. We show that the statement holds for the case where F' is obtained from F by removing a single vertex $v \in V(F)$ of degree 1. The lemma then follows by iterating it. Let ϕ' be a restriction of F to such F' , and let $w \in F'$ denote the unique neighbor of v . Let $X \subseteq V(G)$ with $|X| \leq s$.

Assume first that $\phi(v) \notin X$. If $\phi(w) \notin X$ then both the left hand side (LHS) and the right hand side (RHS) of (2) do not change. Otherwise (if $\phi(w) \in X$) the RHS of (2) increases by 1 (as the degree of w in F' is one less than it was in F). However, as $\phi(v)$ is no longer occupied (i.e. $\phi(v) \notin \phi'(F')$) and $\phi(v) \in N_G(\phi(w))$, the LHS also increases by one, hence the inequality again holds.

Now, let $\phi(v) \in X$. If $\phi(w) \in X$, then the LHS increases by one, the first term on the RHS increases by two, and the last term decreases by one. Finally, if $\phi(w) \notin X$, the LHS grows by one, while the first term on the RHS also grows by one, and the last term drops by one. Hence, in every case the inequality holds. \square

2.2 Algorithmic Friedman-Pippenger with roll-backs

In this section we prove an algorithmic version of the embedding technique provided by Theorem 2.3 and Lemma 2.4 from Section 2.1. We start with a description of an online matching game, to which we reduce our embedding problem.

Let $m \geq 0$ be an integer. The game is played on a bipartite graph $H = (U \cup V, E)$. In the beginning we set M (*the current matching*) to be empty. At each step an adversary chooses a vertex $x \in U$ which is not covered by M , and we match it to some free vertex in V to extend M . After each step the adversary is allowed to remove any number of edges from the current matching M , but at most m times in total during the game. In [1, Lemma 2.2.7], Aggarwal et al. describe a polynomial time algorithm which finds a matching of size n , against any adversary, if H satisfies the property that for each $X \subseteq U$ of size $|X| \leq n$, even if we remove at most half of the edges incident to every vertex in X , there are still at least $2|X|$ neighbors of X in the obtained graph (note that here n does not denote the number of the vertices of the given graph).

Theorem 2.5 ([1], Aggarwal et al.). *Let $H = (U \cup V, E)$ be a bipartite graph and let $n, m \in \mathbb{N}$, such that for every $X \subseteq U$ of size $|X| \leq n$ and for every $F \subseteq E$ such that $|F \cap \partial_H(x)| \leq d_H(x)/2$ for every $x \in X$, we have that $|N_{H-F}(X)| \geq 2|X|$. If $|U| \geq n$, then there is an algorithm which finds a matching of size n against any adversary, if the adversary is allowed to remove edges from the matching at most m times in total during the game. Furthermore, the number of operations which the algorithm performs is polynomial in $m + |V(H)|$.*

Note that m can be as large as one wants in the previous theorem without any influence on the required properties on H . The only ‘price’ we pay in terms of m is the running time of the algorithm.

Definition 2.6. *We say that a graph $G = (V, E)$ has property $P_\alpha(n, d)$ if for every $X \subseteq V$ of size $|X| \leq n$ and every $F \subseteq E$ such that $|F \cap \partial_G(x)| \leq \alpha \cdot d_G(x)$ for every $x \in X$, we have $|N_{G-F}(X)| \geq 2d|X|$.*

Definition 2.7. *Given a graph G , a subset of vertices $S \subseteq V(G)$, and natural numbers $n, m, d \in \mathbb{N}$, we define the following online game, which we call the (G, S, n, m, d) -forest building game. At each step there is a forest $T \subseteq G$ (initially $T := (S, \emptyset)$) with less than n edges in*

G , and the adversary requests a vertex $v \in T$ such that $d_T(v) < d$ and we are supposed to find a neighbor of v in $V(G) - V(T)$, hence extending T by a new leaf. The adversary is allowed to successively remove any number of vertices of degree 1 in T after every step, but he is allowed to do so at most m times in total, and none of the removed vertices are allowed to be in S . We win if at some point T has n edges.

The next theorem gives a handy tool for embedding forests algorithmically in a robust way. In comparison to the technique presented in Section 2.1, here we require a stronger notion of expansion (the $P_\alpha(n, d)$ -property) for the host graph, but the graphs we are embedding can have more vertices than before. The proof closely follows [18].

Theorem 2.8. *Let $\alpha, \beta > 0$ with $\beta < 2\alpha - 1$ and let G be a graph with property $P_\alpha(n, d)$. Let S be a non-empty subset of vertices $S \subseteq V(G)$, such that for every vertex $x \in V(G)$ it holds that $|N_G(x) \cap S| \leq \beta \cdot d_G(x)$. Then there is an algorithm which wins the (G, S, dn, m, d) -forest building game after performing a number of operations polynomial in $m + |V(G)|$.*

Proof. In order to use Theorem 2.5, we construct the following auxiliary graph. Let H be a bipartite graph with classes $U = V(G) \times [d]$ and $V = \{\bar{v} \mid v \in V(G) - S\}$. In other words, U consists of d copies of $V(G)$, and V is a copy of $V(G) - S$. Two vertices $(u, j) \in U$ and $\bar{v} \in V$ are adjacent iff $\{u, v\}$ is an edge in G . Now we show that H satisfies the condition of Theorem 2.5 (with dn having the role of n , and noting that $U = d|V(G)| \geq dn$ because G has property $P_\alpha(n, d)$).

Let $X \subseteq U$ be of size $|X| \leq dn$, and $F \subseteq E(H)$ be such that $|F \cap \partial_H(x)| \leq d_H(x)/2$ for every $x \in X$. We want to show that $|N_{H-F}(X)| \geq 2|X|$. By the pigeonhole principle, one of the d copies of $V(G)$ in U contains at least $|X|/d$ elements from X , or in other words, there is an $i \in [d]$ such that the set $X_i := \{(u, i) \mid (u, i) \in X\}$ is of size $|X_i| \geq |X|/d$. Let Y be an arbitrary subset of X_i of size exactly $\lceil |X|/d \rceil$, and let $Y' = \{u \mid (u, i) \in Y\} \subseteq V(G)$.

We also define $F' \subseteq E(G)$ as follows:

$$F' = \left\{ \{u, v\} \in E(G) \mid u \in Y', v \notin Y', \text{ and } \{(u, i), \bar{v}\} \in F \right\}.$$

Let G' be the graph obtained from G by deleting all edges in F' and by deleting all edges which have one vertex in Y' and the other in $S \setminus Y'$. Note the following facts:

- (i) $|N_{H-F}(Y)| \geq |N_{G'}(Y')|$,
- (ii) $d_{G'}(x) \geq (1 - \alpha)d_G(x)$ for all $x \in Y'$.

The first claim is true as for every vertex $v \in N_{G'}(Y')$ there is a vertex $(u, i) \in Y$ such that $\{(u, i), \bar{v}\}$ is an edge in $H - F$. For the second claim, notice that every vertex $x \in Y'$ after deleting the edges incident to $S \setminus Y'$ from G , loses at most $\beta \cdot d_G(x)$ edges, and after deleting F' from G it loses at most half of its remaining edges, which gives $d_{G'}(x) \geq \frac{1-\beta}{2}d_G(x) > (1 - \alpha)d_G(x)$ edges.

It follows from the second claim and from $|Y'| = \lceil |X|/d \rceil \leq \lceil nd/d \rceil = n$ (and from the assumption that G has the $P_\alpha(n, d)$ -property), that $|N_{G'}(Y')| \geq 2d|Y'| \geq 2|X|$. Together with (i) this implies $|N_{H-F}(X)| \geq |N_{H-F}(Y)| \geq 2|X|$.

Now we reduce our forest building game on the graph G to the matching game on the graph H . At the beginning our initial forest is set to be the empty graph on S , i.e. $T := (S, \emptyset) \subseteq G$.

We also set our auxiliary matching M in H to be empty in the beginning. During the game M and T will have the same number of edges. In each step the adversary requests a vertex $u \in T$ such that $d_T(u) < d$, and we want to find a vertex v in $N_G(u) \setminus V(T)$ which extends T , such that $\{u, v\}$ is a new leaf in T . In order to do this, we find a vertex (u, j) in H for some $j \leq d$, which is not covered by M (in the next paragraph we show that such a vertex exists), and we extend M by finding a match $\bar{v} \in V$ for (u, j) , using the algorithm from Theorem 2.5. Now we add the edge (u, v) (which is in G by the definition of H) to T . Note also that v was not in T before, as v certainly is not in S (by the definition of \bar{v}), and for every other vertex $x \in T$, the vertex \bar{x} is covered by M , as x has been added to T by the same procedure, so $\bar{x} \neq \bar{v}$.

When the adversary wants to delete an edge (u, v) (where v is of degree 1 in T) from T , then we also delete the corresponding edge $\{(u, j), \bar{v}\}$ from M . Note that if at any step the adversary requests a vertex u such that $d_T(u) < d$, then a vertex of the form (u, i) (for some $i \in [d]$) has been used only at most $d - 1$ times by the current matching M , so it is valid to assume that in each step we can find such a vertex which is not covered by M . Since the algorithm finds a forest T with dn edges at the same point when M contains dn edges, and we remove edges from the matching only at most m times in total, thanks to Theorem 2.5, we are done. \square

3 Applications

3.1 Size-Ramsey number of long subdivisions

Before we start with the proof of Theorem 1, we state a few preliminary results which will help us find a subgraph with good expansion properties in the edge colored graph in question.

3.1.1 Preliminaries

The following lemma tells us that if in a graph all sets of a specified size expand well, we can delete relatively few vertices, so that in the remaining graph all smaller sets also expand well. For related results see for example [40]. A similar statement appeared also in [46].

Lemma 3.1. *Let G be a graph such that $|N_G(X)| \geq 3Ks$ for every subset $X \subseteq V(G)$ of size $|X| = s$, for some $s \in \mathbb{N}$ and $K \geq 1$. Then there exists a subset $B \subseteq V(G)$ of size $|B| < s$ such that $G - B$ is (s, K) -expanding.*

Proof. Let $B \subset V(G)$ be a largest set such that $|N_G(B)| < K|B|$ and $|B| < s$ (or $B = \emptyset$ if no such set exists). We show that $H = G - B$ is (s, K) expanding. Let $X \subseteq V(H)$ be an arbitrary non-empty set of size $|X| \leq s$ and suppose $|N_H(X)| < K|X|$. Then $|N_G(X \cup B)| < K|X| + K|B| = K|X \cup B|$, so by assumption we have $|X \cup B| \geq s$; let $S \subseteq X \cup B$ be an arbitrary subset of size $|S| = s$, and set $R = (X \cup B) \setminus S$. Now, we have:

$$\begin{aligned} |N_H(X)| &\geq |N_G(X \cup B)| - |N_G(B \setminus X)| \geq |N_G(X \cup B)| - |N_G(B)| \\ &\geq |N_G(S \setminus R)| - Ks \geq 3Ks - |R| - Ks \geq Ks \geq K|X|, \end{aligned}$$

which contradicts the assumption that $|N_H(X)| < K|X|$. \square

The proof of Theorem 1 combines results from Section 2.1 with a sparse version of Szemerédi's regularity lemma for multicolored graphs (or rather its corollary given shortly).

Definition 3.2. Given a graph G and disjoint subsets $U, W \subseteq V(G)$, we say that the pair (U, W) is (G, ε, p) -regular for some $\varepsilon, p \in (0, 1)$ if

$$|d_G(U', W') - d_G(U, W)| \leq \varepsilon p$$

for every $U' \subseteq U$ of size $|U'| \geq \varepsilon|U|$, and $W' \subseteq W$ of size $|W'| \geq \varepsilon|W|$.

Note that the above definition is in some sense a bipartite version of Definition 1.3. Unlike in Definition 1.3 where p denotes the density of the whole graph, here p is a free parameter which controls the ‘error’ term. However, in the applications it is always set to be of the same order or even equal to the density of the whole graph.

Remark 3.3. If $U' \subseteq U$ and $W' \subseteq W$ are as above and $d_G(U, W) > \varepsilon p$, then there exists at least one edge between U' and W' in G , as otherwise $d_G(U', W') = 0$, which contradicts $|d_G(U', W') - d_G(U, W)| \leq \varepsilon p$. It follows that $|N_G(U')| > (1 - \varepsilon)|W|$.

The following corollary of Szemerédi’s regularity lemma was proven in [33, Lemma 3.4].

Lemma 3.4. For every $k \geq 2$ and $0 < \varepsilon < 1$, there exist $\mu, \eta > 0$ such that the following holds: Suppose $G = (V, E)$ is an η -uniform graph with n vertices and density $p = e(G)/\binom{n}{2} > 0$, and let $E = E_1 \cup E_2 \cup \dots \cup E_k$ be a k -edge-coloring of G . Then, for some color $1 \leq z \leq k$, there exist pairwise disjoint subsets $V_1, V_2, V_3 \subseteq V$ of size $|V_i| = \mu n$ such that

- (a) (V_i, V_j) is (G_z, ε, p) -regular, where $G_z = (V, E_z)$, and
- (b) $d_{G_z}(V_i, V_j) \geq p/2k$,

for every $1 \leq i < j \leq 3$.

3.1.2 Proof of Theorem 1

We are ready to prove Theorem 1, which we restate here for the convenience of the reader.

Theorem 1. For every $k, D \in \mathbb{N}$ and for every $\delta > 0$, there exist $\eta, \alpha > 0$, such that the following holds for every η -uniform graph G with n vertices: every k -edge-coloring of G contains a monochromatic copy of every graph H^σ , where H is a graph with maximum degree at most D , $v(H^\sigma) \leq \alpha n$ and $\sigma(e) \geq \delta \log n$ for every $e \in E(H)$.

Proof. Let $\mu = \mu(k, \varepsilon)$ and $\eta = \eta(k, \varepsilon) > 0$ be given by Lemma 3.4 for a sufficiently small constant $\varepsilon \ll D^{-1}, k^{-1}$. Also assume w.l.o.g. that $D \gg 1/\delta$. Suppose we are given an η -uniform graph G with n vertices and a k -edge-coloring $E(G) = E_1 \cup E_2 \cup \dots \cup E_k$, and let $1 \leq z \leq k$ and $V_1, V_2, V_3 \subseteq V(G)$ be obtained by applying Lemma 3.4. In the rest of the proof we show that $\Gamma = (V(G), E_z)$ contains H^σ for every H satisfying conditions of the theorem with $\alpha = \varepsilon\mu$.

Prepare Γ . Let $t = |V_i| = \mu n$. Let $\Gamma' = \Gamma[V_1, V_2]$ be the bipartite subgraph of Γ induced by V_1 and V_2 . From (Γ, ε, p) -regularity of (V_1, V_2) and from the assumption $\varepsilon \ll 1/k, 1/D$, we conclude (Remark 3.3) that for every subset $X \subseteq V(\Gamma')$ of size $|X| = 2s$, where

$$s = 2D^2\varepsilon t,$$

we have

$$|N_{\Gamma'}(X)| \geq t - \varepsilon t - |X| \geq t/2 \geq 3(D+3)|X|.$$

Therefore, by Lemma 3.1 there exists a subset $B \subseteq V(\Gamma')$ of size $|B| < 2s$ such that $\Gamma_B = \Gamma' \setminus B$ is $(2s, D+3)$ -expanding. Let $V'_1 = V_1 \setminus B$ and $V'_2 = V_2 \setminus B$, so that $\Gamma_B = \Gamma_B[V'_1, V'_2]$. Most of H^σ will be embedded using Γ_B and the machinery from Section 2.1, with occasional help from the set V_3 .

Embed H^σ . Consider a graph H with maximum degree D and let $\sigma: E(H) \rightarrow \mathbb{N}$ be a function such that $v(H^\sigma) = v(H) + \sum_{e \in E(H)} \sigma(e) < \varepsilon t$ and $\sigma(e) \geq \delta \log n$ for every $e \in E(H)$. Let (e_1, \dots, e_h) be an arbitrary ordering of the edges of H , and for each $0 \leq i \leq h$ set $H_i = (V(H), \{e_1, \dots, e_i\})$. Note that H_0 is just an empty graph on the vertex set $V(H)$. We inductively show that for each $0 \leq i \leq h$ there exists an embedding $\phi_i: H_i^\sigma \hookrightarrow \Gamma$ such that the following holds:

- (1) $\phi_i(V(H)) \subseteq V'_1$, and
- (2) the restriction of ϕ_i to $F_i = \phi_i^{-1}(V(\Gamma_B))$, denoted by $f_i: F_i \hookrightarrow \Gamma_B$, is $(2s-2, D)$ -good.

Let us first prove the base case $i = 0$. Note that $H_0^\sigma = H_0$ is an empty graph on the vertex set $V(H)$. Choose an arbitrary $a \in H_0$ and $v \in V'_1$, and set $\phi'_0(a) = v$. As Γ_B is $(2s, D+3)$ -expanding, it is easy to see that ϕ'_0 is a $(2s, D+2)$ -good embedding of a graph consisting of a single vertex. Let us extend such a one-vertex graph to a path P of length $2\varepsilon t$. By Theorem 2.3, there exists an $(2s, D+2)$ -good embedding $\phi'_0: P \hookrightarrow \Gamma_B$. Consider an arbitrary bijection between $V(H)$ and the set of *odd* vertices in P (i.e. the first vertex, third vertex, etc.). As $\phi'_0(a)$ is mapped into V'_1 , all these vertices are also necessarily mapped into V'_1 . Together with ϕ'_0 , such a bijection gives an embedding $\phi_0: H_0 \hookrightarrow \Gamma_B$ with $\phi_0(V(H)) \subseteq V'_1$. As ϕ'_0 was a $(2s, D+2)$ -good embedding, it is easy to verify that ϕ_0 is a $(2s, D)$ -good embedding, hence also a $(2s-2, D)$ -good embedding.

Suppose the induction holds for some $i < h$ and let $e_{i+1} = \{a, b\}$. It suffices to find a path from $\phi_i(a)$ to $\phi_i(b)$ of length $\sigma(e_{i+1})$, such that the part of it that goes through Γ_B maintains $(2s-2, D)$ -goodness. In the proof we use auxiliary parameters $\ell_1, \ell_2, r \in \mathbb{N}$, defined as follows: choose $r \in \mathbb{N}$ to be the smallest integer such that $(D-1)^r \geq \varepsilon t$, and set $\ell_1 = \lfloor \sigma(e_{i+1})/2 \rfloor - r - 1$ and $\ell_2 = \lceil \sigma(e_{i+1})/2 \rceil - r - 1$. Note that $\ell_1, \ell_2 > 1$ since $\lfloor \sigma(e_{i+1})/2 \rfloor \geq \lfloor \delta \log n/2 \rfloor \geq \log_{D-1} n > r + 2$, where we used $1/\varepsilon \gg D \gg 1/\delta$.

Let $F_i = \phi_i^{-1}(\Gamma_B)$ be the part of H_i^σ embedded into Γ_B , and f_i be the restriction of ϕ_i to F_i . We start by constructing the graph F'_i in two steps: First attach to F_i two paths of lengths ℓ_1 and ℓ_2 , one rooted in a and the other in b , and let a' and b' denote the other ends of such paths. Then attach two complete $(D-1)$ -ary trees of depth r , one rooted in a' and the other in b' . Let us denote the set of leaves of these trees by L_a and L_b , respectively, and note that

$|L_a| = |L_b| = (D-1)^r \geq \varepsilon t$ by the choice of h . Such trees have less than $(D-1)^{r+1} \leq (D-1)^2 \varepsilon t$ vertices each, which together with a trivial bound $\ell_1 \leq \ell_2 < \sigma(e_{i+1}) < v(H^\sigma)$ implies

$$\begin{aligned} v(F'_i) &\leq v(F_i) + 2(\ell_2 - 1) + 2 \cdot ((D-1)^2 \varepsilon t - 1) \\ &\leq v(H^\sigma) + 2v(H^\sigma) + 2(D-1)^2 \varepsilon t < s. \end{aligned}$$

Assuming $D \geq 3$, each vertex has degree at most D in F'_i and, by its definition, F'_i can be constructed from F_i by successively adding a vertex of degree 1. Therefore, we can apply Theorem 2.3 to obtain a $(2s-2, D)$ -good embedding $f'_i: F'_i \hookrightarrow \Gamma_B$ which extends f_i .

Every vertex in L_a is at distance exactly $\ell_1 + r$ from a , and every vertex in L_b is at distance exactly $\ell_2 + r$ from b . Thus $f'_i(L_a) \subseteq V'_{j_1}$ and $f'_i(L_b) \subseteq V'_{j_2}$ for some $j_1, j_2 \in \{1, 2\}$. Next, we find a path of length 2 from $f'_i(L_a)$ to $f'_i(L_b)$ with the internal vertex lying in V_3 . From (Γ, ε, p) -regularity of the pairs (V_1, V_3) and (V_2, V_3) , and $|f'_i(L_a)|, |f'_i(L_b)| \geq \varepsilon t$, we know that all but at most $2\varepsilon t$ vertices in $V_3 \setminus \phi_i(H_i^\sigma)$ are adjacent to both $f'_i(L_a)$ and $f'_i(L_b)$. As $|V_3| = t$ and $v(H^\sigma) < \varepsilon t$, this implies that there exists a free vertex in V_3 adjacent both to $f'_i(L_a)$ and $f'_i(L_b)$, which gives a desired path of length 2.

To summarize, we have found a path $P(x, y)$ of length 2 from $f'_i(x)$ to $f'_i(y)$, for some $x \in L_a$ and $y \in L_b$, with the internal vertex avoiding $V_1 \cup V_2$ and $\phi_i(H_i^\sigma)$. By Lemma 2.4, the restriction of f'_i to the graph obtained by removing all newly added vertices to F_i which do not lie either on the path from x to a or from y to b is $(2s-2, D)$ -good. Together with the path $P(x, y)$, this defines an embedding ϕ_{i+1} of H_{i+1}^σ into Γ . \square

3.2 Vertex-disjoint paths in expanding graphs

Theorem 2.8 provides a framework for embedding forests (in polynomial time) into graphs with certain expansion properties, while allowing arbitrary leaf deletions along the way. We present an application of this result to the classic problem of finding vertex-disjoint paths between given pairs of vertices in graphs.

Now we state the key result of this subsection. Theorem 2 (stated in the introduction) will then follow directly from the properties of (n, d, λ) -graphs.

Theorem 3.5. *Let G be a graph with the $P_\alpha(n, d)$ property for some $3 \leq d < n$, such that for every two disjoint $U, V \subseteq V(G)$ of sizes $|U|, |V| \geq n(d-1)/16$ there exists an edge between U and V . Let S be any set of vertices such that $|N_G(x) \cap S| \leq \beta d_G(x)$ for every $x \in V(G)$, where $\beta < 2\alpha - 1$, and let $P = \{a_i, b_i\}$ be a collection of at most $\frac{dn \log d}{15 \log n}$ disjoint pairs from S . Then there exists a polynomial time algorithm which finds vertex-disjoint paths in G between every pair of vertices $\{a_i, b_i\}$, such that the length of each path is $2 \left\lceil \frac{\log(n/16)}{\log(d-1)} \right\rceil + 3$. Furthermore, the pairs (a_i, b_i) are given one by one, and the next pair is revealed when the previous connection is made; all established connections cannot be changed.*

Proof. By Theorem 2.8, there is an algorithm which works in time polynomial in $V(G)$, and wins the $(G, S, nd, n^2 d^3, d)$ -forest building game. We construct the required disjoint paths one by one as follows. Let h be the smallest integer such that $(d-1)^h \geq \frac{n}{16}$.

For the first pair $\{a_1, b_1\}$ we find two disjoint complete $(d-1)$ -ary trees of depth h in G , rooted at a_1 and b_1 , using the algorithm for winning the forest building game. The sets of leaves of those trees are then of size at least $n/16$ each. To each leaf of each tree we then attach

at least one but at most $d - 1$ new edges, so that the resulting trees are of depth $h + 1$, and have exactly $\frac{n(d-1)}{16}$ leaves. Therefore, by assumption, there is an edge connecting these sets of leaves, thus creating a path (between a_1 and b_1) of length $2h + 3$. Remove from our current forest all other edges which do not lie on this path. We continue in the same fashion, by finding two complete $(d - 1)$ -ary trees rooted at a_2 and b_2 (disjoint from the path connecting a_1 and b_1), then finding a connecting edge between the sets of leaves, and removing all edges from the $(d - 1)$ -ary trees, which do not lie on the found path. We delete the edges successively, by always removing the edges which are incident with vertices of degree 1, just like in the forest building game.

We do this procedure for every pair of vertices, and note that we can do this as at any given point the current forest which we use for our argument has at most

$$\frac{dn \log d}{15 \log n} \cdot (2h + 3) + 2 \cdot 4 \cdot \frac{(d - 1)n}{16} < \frac{dn}{2} + \frac{dn}{2} < dn$$

edges, where the first term is a bound on the total number of edges used in previous paths, and the second one bounds the number of edges in the current $(d - 1)$ -ary trees we use. Furthermore we delete vertices of degree 1 at most $2|P| \cdot dn < n^2 d^3$ times. This completes the proof. \square

The following result can be derived from the Expander Mixing Lemma through rather routine calculations.

Lemma 3.6 ([18], Lemma 2.7). *Let G be an (n, d, λ) -graph and let d_0, n_0 be positive integers. G has property $P_\alpha(n_0, d_0)$ for $\alpha > 0$ if the following holds:*

$$1 - \alpha > \frac{n_0(1 + 4d_0)}{2n} + \frac{\lambda}{d}(1 + \sqrt{2d_0}).$$

We are ready to give the promised proof of Theorem 2, restated below for the convenience of the reader.

Theorem 2. *Let $0 < \varepsilon < \frac{1}{4}$, and let G be an (n, d, λ) -graph, with $\lambda < d^{1-\varepsilon}/320$ and $d^\varepsilon \geq 5$. Let S be any set of vertices which satisfies $|N_G(x) \cap S| \leq \frac{d}{4}$ for every $x \in V(G)$. Let $P = \{a_i, b_i\}$ be a collection of at most $\frac{\varepsilon n \log d}{480 \log n}$ disjoint pairs of vertices from S . There exists a polynomial time algorithm to find vertex-disjoint paths in G between every pair of vertices $\{a_i, b_i\}$, such that the paths are of equal length which is less than $5 \frac{\log n}{\varepsilon \log d}$. Furthermore, the pairs (a_i, b_i) are given one by one, and the next pair is revealed when the previous connection is made; all established connections cannot be changed.*

Proof. Let $d_0 = d^\varepsilon$ and $n_0 = n/16d_0$. From Lemma 3.6 we see that G has the $P_{3/4}(n_0, d_0)$ -property. Furthermore, by the Expander Mixing Lemma (1), we have that for sets $U, V \subseteq V(G)$ of size at least $\frac{(d_0-1)n_0}{16}$ it holds:

$$e_G(U, V) \geq \frac{d|U||V|}{n} - \lambda\sqrt{|U||V|} \geq \sqrt{|U||V|} \left(\frac{d(d_0 - 1)n_0}{16n} - \lambda \right) \geq \frac{(d_0 - 1)d}{256d_0} - \lambda$$

which, together with $\lambda < d/320$ and $d_0 \geq 5$ gives $e_G(U, V) > 0$. Applying Theorem 3.5 to G completes the proof; here are the final calculations.

- Number of pairs:

$$\frac{d_0 n_0 \log d_0}{15 \log n_0} = \frac{n \log d^{\varepsilon/2}}{16 \cdot 15 \log(n/16d_0)} = \frac{\varepsilon n \log d}{480 \log(n/16d_0)} > \frac{\varepsilon n \log d}{480 \log n};$$

- Length of paths:

$$2 \left\lceil \frac{\log(n_0/16)}{\log(d_0 - 1)} \right\rceil + 3 = 2 \left\lceil \frac{\log(n/256d_0)}{\log(d^{\varepsilon/2} - 1)} \right\rceil + 3 \leq 5 \frac{\log n}{\varepsilon \log d}.$$

□

3.3 Topological minors in (n, d, λ) -graphs

Now we use Theorem 3.5 from the previous subsection to prove Theorem 3, restated here for the reader's convenience.

Theorem 3. *Let G be a (n, d, λ) -graph with $240\lambda < d \leq n^{1/5}/2$, and let d_0 be such that $d_0 \geq 3$. Then G contains a topological minor of K_t for $t = \lfloor d - 80\lambda\sqrt{d_0} \rfloor$, the paths between branching vertices being of equal length ℓ , where $\ell = O\left(\frac{\log n}{\log d_0}\right)$.*

Proof. Let $T = \{v_1, \dots, v_t\}$ be a set of t vertices with pairwise distances at least four in G ; one can find such a set by putting a vertex from G into T and removing all vertices at distance at most four from G , and repeating this process. For each vertex $v_i \in T$, let $S_i = \{v_i^j \mid 1 \leq j \leq t, i \neq j\}$ be an arbitrary set of neighbors of v_i of size $|S_i| = t - 1$. Now consider the following set of pairs

$$P = \{(v_i^j, v_j^i) \mid 1 \leq i < j \leq t\},$$

and note that for every two distinct S_i and S_j there is exactly one pair from $S_i \times S_j$ in P . We want to use Theorem 3.5 to link the pairs in P , which evidently gives a topological minor of K_t in G .

First, by Lemma 3.6, G has the $P_\alpha(n_0, d_0)$ property for $\alpha = 1 - \frac{40\lambda}{d}\sqrt{d_0}$ and $n_0 = \frac{25\lambda n}{d_0 d}$. Indeed, this follows from:

$$\frac{n_0(1 + 4d_0)}{2n} + \frac{\lambda}{d}(1 + \sqrt{2 \cdot d_0}) < 60\frac{\lambda}{d} + 2\frac{\lambda}{d}\sqrt{d_0} < 40\frac{\lambda}{d}\sqrt{d_0} = 1 - \alpha.$$

Next, for every $x \in V(G)$ we have

$$|N_G(x) \cap (P \cup T)| < \beta d,$$

for $\beta = 1 - \frac{80\lambda\sqrt{d_0} + 1}{d}$. The choice of β also implies $\beta < 2\alpha - 1$ holds. Finally, every two disjoint sets in G of size $n_0(d_0 - 1)/16$ have an edge between them by (1), thus we can indeed apply Theorem 3.5 and get a topological minor of K_t such that the constructed paths between vertices in each pair in P are of length $2 \left\lceil \frac{\log(n_0/16)}{\log(d_0 - 1)} \right\rceil + 3 = O\left(\frac{\log n}{\log d_0}\right)$, completing the proof. □

By assuming that $\lambda < d/240$ and setting $d_0 = 3$ in the theorem above, one can get a topological minor of K_t for $t = d - O(\lambda)$. Can we do better? If λ is small, can we find a topological minor of K_{d+1} in an (n, d, λ) -graph? In the rest of the section we show that the answer to the latter question is negative; we give constructions of graphs which show that one cannot do much better than what is given in Theorem 3. This is related to the following question of Fountoulakis, Kühn and Osthus [27]. For which values α, k, d does every $(\alpha n, k)$ -expanding d -regular graph on n vertices contain a topological minor of K_{d+1} ? We will show that even if we assume strong expansion properties, this still does not force a topological minor of K_{d+1} ; in particular, for $d \geq 7$ and infinitely many values of n we show that there is an $(\alpha n, d - 3)$ -expanding $(2d + 1)$ -regular graph, where $\alpha = \alpha(d)$, with no subdivision of K_{2d+2} . First, we need the following definition.

Definition 3.7. *The strong product of two graphs G_1 and G_2 is the graph $G_1 \boxtimes G_2$ on the vertex set $V(G_1) \times V(G_2)$, where (u_1, u_2) is adjacent to (v_1, v_2) if and only if one of the following holds:*

- $u_1 = v_1$ and $u_2 \sim v_2$ in G_2 ;
- $u_2 = v_2$ and $v_1 \sim u_1$ in G_1 ;
- $u_1 \sim v_1$ in G_1 and $v_2 \sim u_2$ in G_2 .

Given a graph G , we denote by $G^{(k)}$ the strong product of G and K_k , that is $G^{(k)} = G \boxtimes K_k$.

Lemma 3.8. *Let G be a triangle-free d -regular graph for $d \geq 7$, and let $k \geq 2$. Then $G^{(k)}$ does not contain a topological minor of K_t for $t = kd + 2$.*

Proof. Observe that $G^{(k)}$ can be obtained from G by replacing each vertex v in G by a clique C_v of order k , and then making all vertices in C_v adjacent to all vertices in C_u if $v \sim u$ in G . Hence, $G^{(k)}$ is $(kd + k - 1)$ -regular. With slight abuse of notation, for a vertex $v \in G^{(k)}$ we let C_v denote such a clique which contains v . Suppose to the contrary that there is a topological minor T of K_t in $G^{(k)}$.

Let $v \in V(G^{(k)})$ be one of its branch vertices. We show that there is at least another vertex $w \in C_v$ which is a branch vertex in T . If this is not the case, then every vertex w in C_v is either not a neighbor of v in T , or it is one of the internal vertices in T adjacent to v . In the latter case, this means that the path in T , starting at v and continuing with w , at some point leaves C_v and lands in one of the kd other neighbors w' of v in $G^{(k)}$. This implies that vw' is not an edge in T , since every cycle in a topological minor contains at least 3 branching vertices. Note also that for distinct vertices $w_1, w_2 \in C_v$ in the latter case, w'_1, w'_2 are also distinct, as otherwise we again get a cycle with less than 3 branching vertices. In both cases, for every vertex in $w \in C_v - v$, one of the $kd + k - 1$ neighbors of v in $G^{(k)}$ is not its neighbor in T and for each w such a neighbor is distinct. Thus v has at most $kd + k - 1 - (|C_v| - 1) = kd = t - 2$ neighbors in T , a contradiction. Therefore, we may assume that there is another branching vertex $w \in C_v - v$.

Consider the (common) neighborhood in $G^{(k)} - C_v$ of v and w . Note it is of size kd and it induces a disjoint union of cliques of order k , since by assumption G does not contain triangles. Since both v and w have at least $(t - 1) - (k - 1) > kd - k$ neighbors in $T - C_v$ each, it means they have at least $kd - 2k > d$ common neighbors in $T - C_v$. Let us denote such common neighbors by N . Note that all vertices in N are also necessarily branching vertices. Now, by

the pigeonhole principle, there exist two vertices x, x' in N from the same k -clique in $G^{(k)}$. In order to get to the other at least $|N| - |C_x| > kd - 3k$ branching vertices in $N \setminus C_x$, x and x' must use internally vertex disjoint paths of length at least two (indeed, recall that no vertex in C_x is adjacent to any vertex in $N \setminus C_x$ in the graph $G^{(k)}$). This is in turn not possible, since x and x' have an identical neighborhood (up to x, x'), which is of size $kd + k - 1$, so one of them will use less than half of those to get to each vertex in $N \setminus C_x$, which is a contradiction since $|N \setminus C_x| > kd - 3k > \frac{kd+k-1}{2}$, for $d \geq 7$. This completes the proof. \square

The next lemma is a standard exercise in spectral graph theory (see for example Problem 11.7 in [44]).

Lemma 3.9. *Let $\{\lambda_i\}_{i \in I}$ be the eigenvalues of graph G_1 , and $\{\mu_j\}_{j \in J}$ be the eigenvalues of graph G_2 . Then the eigenvalues of $G_1 \boxtimes G_2$ are $\lambda_i \mu_j + \lambda_i + \mu_j$, for $(i, j) \in I \times J$.*

Using Lemmas 3.8 and 3.9, we get the following result.

Theorem 3.10. *Let G be a triangle-free (n, d, λ) -graph with $7 \leq d \leq n - 1$ and let $k \geq 2$. Then $G^{(k)}$ is a $(kn, kd + k - 1, k\lambda + k - 1)$ -graph without a topological minor of K_t for $t = kd + 2$.*

Proof. By Lemma 3.8 the graph $G^{(k)}$ does not contain a topological minor of K_t . It is left to prove that the second largest eigenvalue in absolute value of $G^{(k)}$ is at most $k\lambda + k - 1$. First, it is an easy exercise to show that the eigenvalues of K_k are $k - 1$ with multiplicity 1, and -1 with multiplicity $k - 1$. On the other hand, the largest eigenvalue of G is d while the other eigenvalues are by assumption at most λ in absolute value. By applying Lemma 3.9, one can see that all except the largest eigenvalue of $G^{(k)}$ are at most $\lambda(k - 1) + \lambda + (k - 1)$ in absolute value, so we are done. \square

Remark 3.11. *Recall that we mentioned in the introduction that there exist triangle-free (n, d, λ) -graphs with $\lambda = O(\sqrt{d})$. By assuming that $\lambda = O(\sqrt{d})$ in the previous theorem, one gets an (n_1, d_1, λ_1) -graph where $n_1 = kn$, $d_1 = kd + k - 1$ and $\lambda_1 = k\lambda + k - 1$, with no topological minor of K_t with $t = d_1 - (k - 3) = d_1 - \Theta\left(\frac{\lambda_1^2}{d_1}\right)$. Recall that by Theorem 3 one is guaranteed to find a topological minor of K_t for $t = d_1 - \Theta(\lambda_1)$ whenever $\lambda_1 < d_1/240$; by fixing d and λ , and choosing k to be large in the previous theorem, one gets $t = d_1 - \Theta(\lambda_1)$, matching the mentioned lower bound for t .*

Finally, we have the following corollary of Lemma 3.8, which gives a concrete bound for the parameters in the abovementioned question of Fountoulakis, Kühn and Osthus, putting an emphasis on the expansion ratio, which is close to half of the degree of the constructed regular graph.

Corollary 3.12. *For every $d \geq 7$ there exists a constant $\alpha > 0$, such that for infinitely many values of n there is a $(\alpha n, d - 3)$ -expanding $(2d + 1)$ -regular graph on n vertices without a topological minor of K_{2d+2} .*

Proof. Let G be a random bipartite d -regular graph on an even number $n/2$ of vertices; such a graph is whp $(\alpha n, d - 3)$ -expanding for constant $\alpha = \alpha(d)$ (see, for example, Theorem 4.16 in [35]). By Lemma 3.8, the graph $G^{(2)}$ does not contain a K_{d+1} -topological minor; furthermore, one can easily see that $G^{(2)}$ is also $(\alpha n, d - 3)$ -expanding, so we are done. \square

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4 Appendix

Proof of Theorem 2.3. Let F' be a graph obtained from F by adding a leaf v to a vertex $w \in V(F)$ such that $d_F(w) \leq D - 1$ and $v(F') \leq s$, and let us show that an embedding ϕ' as described exists; the theorem then follows by induction. For a set $X \subset V(G)$ and an embedding $f : H \hookrightarrow G$ let

$$R(X, f) = |\Gamma_G(X) \setminus f(H)| - \sum_{v \in X} [D - \deg_H(f^{-1}(v))] - |f(H) \cap X|.$$

Let $Y = \Gamma_G(\phi(w)) \setminus \phi(F)$; for every $a \in Y$ we can extend ϕ to an embedding ϕ_a of F' by letting $\phi_a(v) = a$. We need to show that there is an $a \in Y$ such that $R(X, \phi_a) \geq 0$ for all X with $|X| \leq 2s - 2$. Suppose to the contrary that for every $a \in Y$ there exists a set X_a with $|X_a| \leq 2s - 2$ such that $R(X_a, \phi_a) < 0$. By assumption ϕ is $(2s - 2, D)$ -good, so it holds that $R(X, \phi) \geq 0$ for all sets X with $|X| \leq 2s - 2$. Note that for every $a \in Y$ we have:

$$\begin{aligned} R(X_a, \phi_a) - R(X_a, \phi) &= -\mathbf{1}[a \in \Gamma_G(X_a)] + \mathbf{1}[a \in X_a] + \mathbf{1}[\phi(w) \in X_a] - \mathbf{1}[a \in X_a] \\ &= \mathbf{1}[\phi(w) \in X_a] - \mathbf{1}[a \in \Gamma_G(X_a)] \end{aligned}$$

Hence, in order to have $R(X_a, \phi_a) < 0$, we may assume that $R(X_a, \phi) = 0$, $\phi(w) \notin X_a$ and $a \in \Gamma_G(X_a)$. We will also need the following claims.

Claim 4.1. *If $X \subseteq V(G)$ is such that $R(X, \phi) = 0$ and $|X| \leq 2s - 2$ then $|X| \leq s - 1$.*

Proof. Since G is $(2s - 2, D + 2)$ -expanding, we have that $|\Gamma_G(X)| \geq (D + 2)|X|$; we also know that $v(F) \leq s - 1$. Thus we have

$$0 = R(X, \phi) \geq (D + 2)|X| - (s - 1) - |X|D - |X| = |X| - (s - 1),$$

so the claim follows. \square

Claim 4.2. *The function $R(\cdot, \phi)$ is submodular, i.e., for all sets of vertices A, B it holds that $R(A \cup B, \phi) + R(A \cap B, \phi) \leq R(A, \phi) + R(B, \phi)$.*

Proof. The first term of $R(X, \phi)$ is a submodular function of X , and the other two are modular, so the claim follows. \square

Claim 4.3. *If for $A, B \subseteq V(G)$ it holds that $R(A, \phi) = R(B, \phi) = 0$, and $|A|, |B| \leq s - 1$, then $R(A \cup B, \phi) = 0$ and $|A \cup B| \leq s - 1$.*

Proof. Since ϕ is $(2s - 2, D + 2)$ -good and $|A \cup B|, |A \cap B| \leq 2s - 2$, we have that $R(A \cup B, \phi), R(A \cap B, \phi) \geq 0$. Now it follows by Claim 4.2 that $R(A \cup B, \phi) = 0$, and in turn, by Claim 4.1 we have $|A \cup B| \leq s - 1$. \square

Now we are ready to finish the proof. Recall that for every $a \in Y$ it holds that $|X_a| \leq 2s - 2$ and $R(X_a, \phi) = 0$. Let $X^* = \bigcup_{a \in Y} X_a$ and let us show that $R(X^*, \phi) = 0$, and thus by Claim 4.1 we will have $|X^*| \leq s - 1$. If $Y = \emptyset$, we are done, and otherwise we get by induction and Claim 4.3 that $R(X^*, \phi) = 0$. Now we consider the set $X' = X^* \cup \{\phi(w)\}$, and notice that $X^* \subsetneq X'$ since we assumed that $\phi(w) \notin X_a$ for every $a \in Y$, so $\phi(w) \notin X^*$. Since $a \in \Gamma_G(X_a)$ for every $a \in Y$, this means that $\Gamma_G(\phi(w)) \setminus \phi(F) = Y \subseteq \Gamma_G(X^*)$, hence the first term in $R(X^*, \phi)$ and the first term in $R(X', \phi)$ are the same. Furthermore, because of the second term, we have $R(X', \phi) \leq R(X^*, \phi) - (D - \deg_F(w)) \leq R(X^*, \phi) - 1 < 0$ as $\phi(w) \in X'$ and $\phi(w) \notin X^*$, a contradiction with $R(X', \phi) \geq 0$. \square