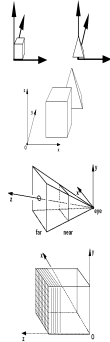


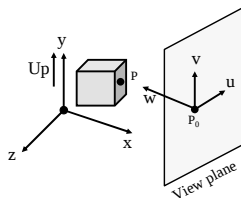
Common Coordinate Systems

- Object space
 - local to each object
- World space
 - common to all objects
- Eye space / Camera space
 - derived from view frustum
- Screen space
 - indexed according to hardware attributes



Viewing in 3D

(Chapt. 6 in FVD, Chapt. 12 in Hearn & Baker)

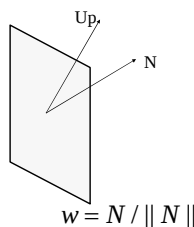


- $P_0 = (x_0, y_0, z_0)$ is a point where a camera is located.
- P is a point to look-at.
- $N = (P_0 - P) / |P_0 - P|$ is the view-plane normal vector.
- Up is the view up vector, whose projection onto the view-plane is directed up.

Specifying the Viewing Coordinates

- *Viewing Coordinates system*, $[u, v, w]$, describes 3D objects with respect to a viewer.
- A *viewing plane (projection plane)* is set up perpendicular to w and aligned with (u, v) .
- To set a view plane we have to specify a *view-plane normal vector*, N , and a *view-up vector*, Up , (both, in world coordinates):

How to form Viewing coordinate system



First, normalize the look-at vector to form the w-axis

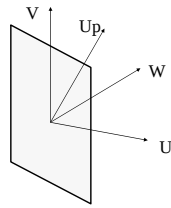
- How to form Viewing coordinate system :

$$w = \frac{N}{|N|} ; u = \frac{Up \times N}{|Up \times N|} ; v = w \times u$$

- The transformation, M , from world-coordinate into viewing-coordinates is:

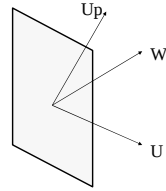
$$M = \begin{bmatrix} u_x & u_y & u_z & 0 \\ v_x & v_y & v_z & 0 \\ w_x & w_y & w_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -x_0 \\ 0 & 1 & 0 & -y_0 \\ 0 & 0 & 1 & -z_0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Create V perpendicular to U and W



$$V = W \times U$$

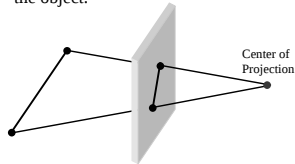
Create U perpendicular to Up and W



$$U = \frac{Up \times W}{|Up \times W|}$$

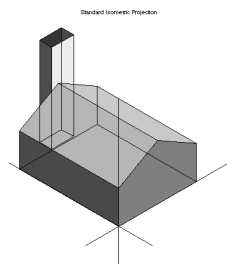
Projections

- Viewing 3D objects on a 2D display requires a mapping from 3D to 2D.
- A projection is formed by the intersection of certain lines (*projectors*) with the view plane.
- Projectors are lines from the *center of projection* through each point in the object.

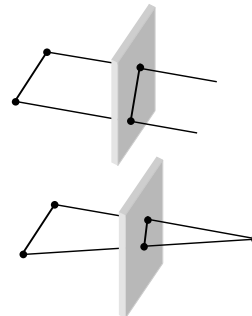


Parallel Projection

A parallel projection preserves relative proportions of objects, but does not give realistic appearance (commonly used in engineering drawing).

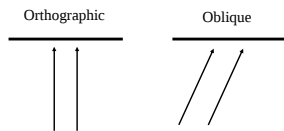


- Center of projection at infinity results with a parallel projection.
- A finite center of projection results with a perspective projection.



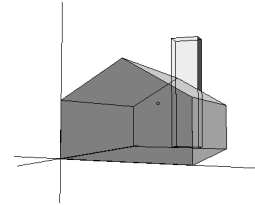
Parallel Projection

- Projectors are all parallel.
- Orthographic: Projectors are perpendicular to the projection plane.
- Oblique: Projectors are not necessarily perpendicular to the projection plane.

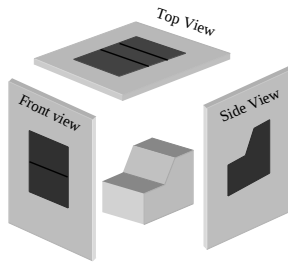


Perspective Projection

A perspective projection produces realistic appearance, but does not preserve relative proportions.



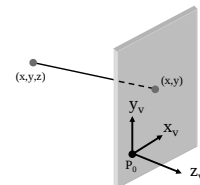
- Lengths and angles of faces parallel to the viewing planes are preserved.
- **Problem:** 3D nature of projected objects is difficult to deduce.



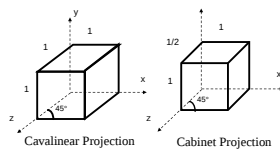
Orthographic Projection

- Since the viewing plane is aligned with (x_v, y_v) , orthographic projection is performed by:

$$\begin{bmatrix} x_p \\ y_p \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} x_v \\ y_v \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_v \\ y_v \\ z_v \\ 1 \end{bmatrix}$$

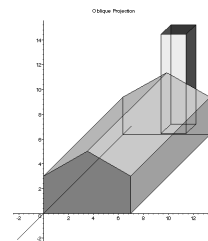


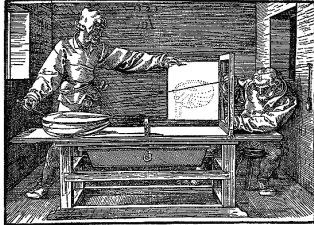
- Cavalinear projection :
 - Preserves lengths of lines perpendicular to the viewing plane.
 - 3D nature can be captured but shape seems distorted.
- Cabinet projection:
 - lines perpendicular to the viewing plane project at 1/2 of their length.
 - A more realistic view than the Cavalinear projection.



Oblique Projection

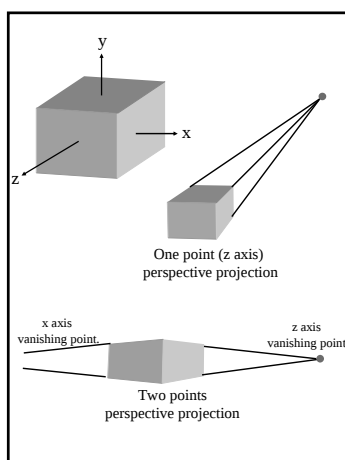
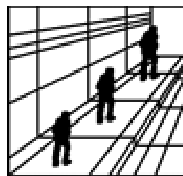
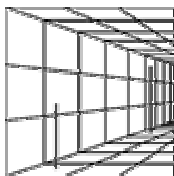
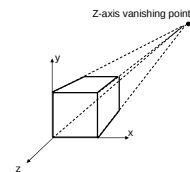
- Projectors are **not** perpendicular to the viewing plane.
- Angles and lengths are preserved for faces parallel to the plane of projection.
- Somewhat preserves 3D nature of an object.





Perspective Projection

- In a perspective projection, the center of projection is at a finite distance from the viewing plane.
 - Parallel lines that are not parallel to the viewing plane, converge to a *vanishing point*.
- ⇒ A vanishing point is the projection of a point at infinity.

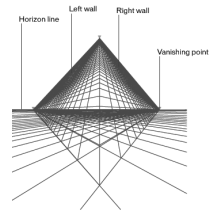
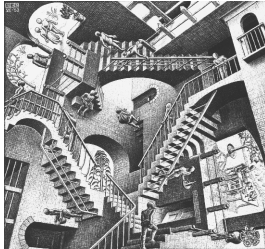


Vanishing Points

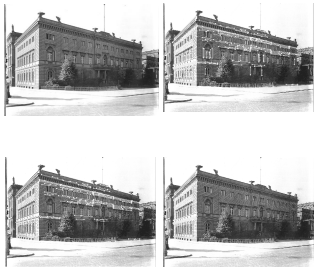
- There are infinitely many general vanishing points.
- There can be up to three *axis vanishing points* (principal vanishing points).
- Perspective projections are categorized by the number of principal vanishing points, equal to the number of principal axes intersected by the viewing plane.
- Most commonly used: one-point and two-points perspective.

3-point Perspective

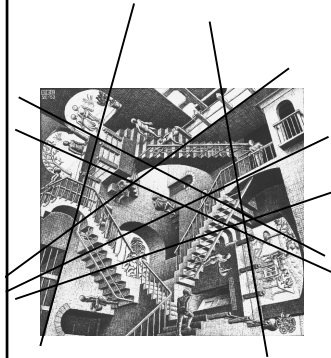
M.C. Escher's "*Relativity*" where 3 worlds co-exist thanks to 3-point perspective.



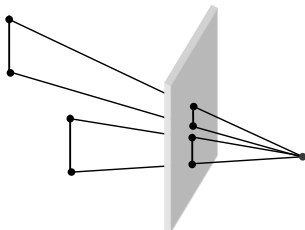
3-point Perspective



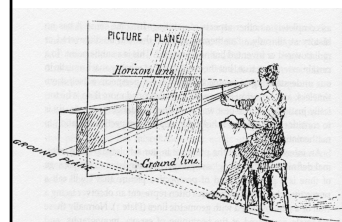
3-point Perspective



A perspective projection produces realistic appearance, but does not preserve relative proportions.



Perspective Projection

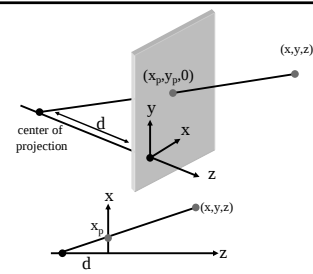


- Thus, a perspective projection matrix is defined:

$$M_{per} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{d} & 1 \end{bmatrix}$$

$$M_{per}P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{d} & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ 0 \\ \frac{z+d}{d} \end{bmatrix}$$

$$\Rightarrow x_p = \frac{d \cdot x}{z+d} ; y_p = \frac{d \cdot y}{z+d} ; z_p = 0$$



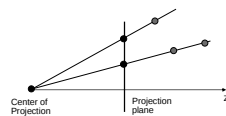
- Using similar triangles it follows:

$$\frac{x_p}{d} = \frac{x}{z+d} ; \frac{y_p}{d} = \frac{y}{z+d}$$

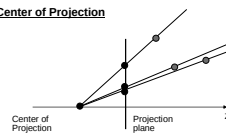
$$\Rightarrow x_p = \frac{d \cdot x}{z+d} ; y_p = \frac{d \cdot y}{z+d} ; z_p = 0$$

What is the difference between moving the center of projection and moving the projection plane?

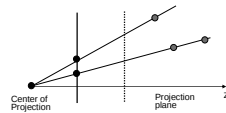
Original



Moving the Center of Projection



Moving the Projection Plane

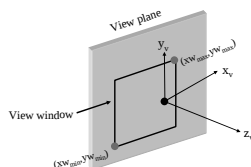


Observations

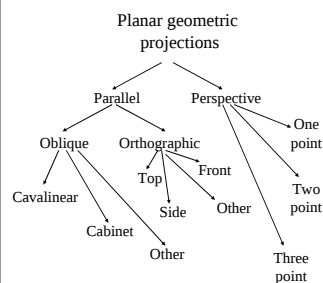
- M_{per} is singular ($|M_{per}|=0$), thus M_{per} is a many to one mapping
- Points on the viewing plane ($z=0$) do not change.
- The vanishing point of parallel lines directed to (U_x, U_y, U_z) is at $[dU_x/U_z, dU_y/U_z]$.
- When $d \rightarrow \infty$, $M_{per} \rightarrow M_{ort}$

View Window

- After objects were projected onto the viewing plane, an image is taken from a *View Window*.
- A view window can be placed *anywhere* on the view plane.
- In general the view window is aligned with the viewing coordinates and is defined by its extreme points: (xw_{min}, yw_{min}) and (xw_{max}, yw_{max})



Summary



- In order to limit the infinite view volume we define two additional planes: *Near Plane* and *Far Plane*.
- Only objects in the bounded view volume can appear.
- The near and far planes are parallel to the view plane and specified by z_{near} and z_{far} .
- A limited view volume is defined:
 - For orthographic: a rectangular parallelepiped.
 - For oblique: an oblique parallelepiped.
 - For perspective: a frustum.

View Volume

- Given the specification of the view *window*, we can set up a *View Volume*.
- Only objects inside the view volume might appear in the display, the rest are clipped.

Trivial Accept/Reject

Red polygons are rejected
Black are accepted
And
Blue are tagged for clipping

Canonical View Volumes

- In order to determine the objects that are seen in the view window we have to clip objects against six planes forming the view volume.
- Clipping against arbitrary 3D plane requires considerable computations.
- For fast clipping we transform the general view volume to a *canonical view volume* against which clipping is easy to apply.

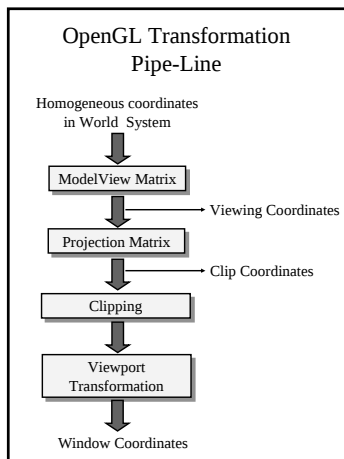
Affine Transformation: ↓

Classify the vertices of the polygons against each side S_i of the frustum in turn:

If all the vertices are on the outside of some S_i , then cull the polygon, otherwise,

Polygons with all its vertices inside all S_j are accepted.

All others are tagged.



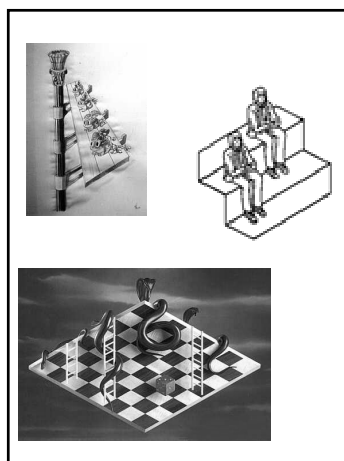
Perspective transformation:

$$\begin{bmatrix} x_c' \\ y_c' \\ z_c' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{f+n}{f-n} & -2\frac{fn}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_c \\ y_c \\ z_c \\ 1 \end{bmatrix}$$

$$\frac{x_c'}{1} = \frac{x_c}{-z_c} \Rightarrow x' = \frac{x_c}{-z_c}$$

$$\frac{y_c'}{1} = \frac{y_c}{-z_c} \Rightarrow y' = \frac{y_c}{-z_c}$$

$$[0 \ 0 \ -n \ 1] \rightarrow [0 \ 0 \ -1 \ 1]$$

$$[0 \ 0 \ -f \ 1] \rightarrow [0 \ 0 \ 1 \ 1]$$


Viewport Transformation

$$x_{win} = (x_c' + 1) \frac{width}{2} + x_0$$

$$y_{win} = (y_c' + 1) \frac{height}{2} + y_0$$
