Computer Graphics - TAU

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Rendering

- The process of turning 3D virtual world into 2D images:
 - Vidoe games
 - Animation Movies
- What rendering algorithms do you know ?
 - Ray Tracing and Ray Casting
- What are the advantages/disadvantages of Ray Tracing ?
- Today we are going to learn about Graphical Pipeline

Graphical Pipeline:

- Set of steps need to be taken in order to turn 3D scene into 2D image
 - The graphical pipeline is conceptual model
 - Highly dependent on the underlying available Software and Hardware accelerators
- The model of graphical pipeline is usually used in real-time rendering
 - Each step is backed with efficient algorithms that are usually hardware accelerated (e.g., using GPUs)

Motivation

- How do you represent 3D surfaces ?
- Maybe: using Implicit representation ?
 - Not tractable for complex shapes
- A 3D mesh (usually triangles):
 - Simple objects can be composed of thousands of triangles!



- Step 1 Modeling Transformation
 - 3D models (assets) are usually created spearatley.
 - Each model is designed in its local coordinate system – benefits:
 - Symmetry
 - Scale independent
 - Reusability
 - And more
 - 3D scences on the other hand are composed of many 3D objects:
 - Objects are located in the world coordinate system



- Step 1 Modeling Transformation
 - Each model is transformed from its local coordinate system to the world coordinate system:





- Step 1 Modeling Transformation
 - This step is implemented by multiplying each vertex of the 3D model by a (different) model transformation matrix (GPUs allow parallel compute of the matrix multiplication).



- Step 2 Lighting
 - Why lighting is important ? It is what helps us perceive depth in images





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- Step 2 Lighting
 - What do we need to support lighting (aka shading):
 - Light Properties:
 - What type of light sources exists (e.g. point light, directional light, spotlight)
 - Light entensity and color
 - Light location/direction
 - Material Properties
 - How light interacts with the 3D object (diffuse and specular reflection)



- Step 2 Lighting
 - Remember the Phong reflectance model from Ray-Tracing ?

$$I = I_{E} + K_{A}I_{AL} + \sum_{i}(K_{D}(N \bullet L_{i})I_{i} + K_{S}(V \bullet R_{i})^{n}I_{i})$$

 How can we use this Formula to determine the color of the triangle we want to draw (remember, objects are usually represented as triangle-meshes)



- Step 2 Lighting
 - There are three type of shading approcates:
 - Flat shading Fast and inaccurate
 - Phong shading Accurate but slow
 - Gouraud shading somehwere in the middle in terms of speed and accuracy



https://adambadke.com/portfolio-single/ray-tracing-3d-renderer/



- Step 2 Lighting
 - Flat Shading:
 - Each <u>"triangle"</u> is given a normal (the normal can be predefined or calculated using simple geometry).
 - The color of the triangle is determined using some reflection model (e.g Phong reflection model)
 - The color is uniform across each triangle (all points on each triangle have the same color)



- Step 2 Lighting
 - Gourouad Shading:
 - Each "triangle vertex" is given a normal.
 - The **vertex** color is determined using a reflection model (e.g phong reflection model)
 - The color of a point inside the triangle is an interpolation of the colors of the triangle vertices



- Step 2 Lighting
 - Phong Shading:
 - We define a normal for each triangle vertex
 - The normal of any point point inside the triangle is an interpolation between the triangle vertices' normal vectors.
 - The point color is determined using Phong reflection model with the interpolated normal.





- Step 3 Viewing Transformation
 - The final image is highly dependent on the camera location and view direction:
 - What we see is what we render





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- Step 3 Viewing Transformation
 - We therefore need to define the camera parameters:
 - Location
 - View direction
 - View volume (more later)



- Step 3 Viewing Transformation
 - In the graphical pipeline this is done slightly different
 - Instead of defining the camera parameters, we always assume the camera is in the origin and is looking in the negative z-direction
 - This is called the canonical camera parameters
 - This assumption is needed for efficient implementation of different algorhtms



- Step 3 Viewing Transformation
 - But how can we still support different camera views if the camera is always in the origin and looking in –z direction ?
 - Simple: transform the whole 3D scene to the camera coordinate system
 - Therefore, each vertex will be transformed by (at least) two transformation
 - The Model Transformation matrix (local -> world)
 - The Viewing Transformation Matrix (world -> camera)



- Step 3 Viewing Transformation
 - Example:
 - We want the camera to be at (0,8,10)
 - And looking in the $\left(0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right)$ direction:
 - (0,8,10)





- Step 3 Viewing Transformation
 - Example:
 - First: translate every vertex in the scene by (0,-8,-10)
 - Next: Rotate the whole scene by 45 degrees CCW in the x-direction
 - This can be done using one matrix (e.g. multiplication of the translation and rotation matrix)



- Step 4 Projection Transformation
 - Until this stage everything we work with is in 3D space
 - Images on the other hand are in 2D space
 - But how can we move from 3D to 2D space?
 - Use projection transformations:
 - Perspective and Orthographic transformation ?



- Step 4 Projection Transformation
 - Remember the canonical camera coordinates?
 - It simplifies the projection transformation matrix



- Step 4 Projection Transformation
 - Orthographic projection
 - Everything inside the "view volume" will be projected onto the XY plane
 - Everything else will be clipped





- Step 4 Projection Transformation
 - Perspective projection
 - Everything inside the "view frustum volume" will be projected onto the near frustum plane
 - Everything else will be clipped





- Step 5 Clipping
 - A 3D scene is composed of many objects
 - Each object is composed of thousands of triangles (even more)
 - But not everything is visible why bother and render everything if not everything is visible ?
 - Therefore we clip-out objects outside the view-frustum:
 - This is important process which is important for real-time rendering
 - Done for efficiency purposes







- Step 5 Clipping
 - Typically, triangles should not be rendered when their front sides do not face the viewpoint.
 - Such pieces of a surface are called *back faces*.





https://techpubs.jurassic.nl/manuals/0640/developer/Optimizer_PG/sgi_html/ch05. html

- Step 5 Clipping
 - **Back-face culling** keeps these triangles from being rendered (rasterized), thus saving on pixel fill time (later on rasterization).





https://techpubs.jurassic.nl/manuals/0640/developer/Optimizer_PG/sgi_html/ch05. html

- Step 5 Clipping
 - Face orientation is determined by the surface normal.
 - If the surface normal points towards the camera then the visible surface is the front face.





- Step 5 Clipping
 - This normal is not defined explicitly, but deduced by the order in which the vertices are processed in the pipeline (Counter-ClockWise or Clock-Wise)
 - Use right-hand rule to determine the normal direction
 - Note below, we use the vertex index to represent the order in which the vertices are processed in the pipeline





- Step 6 Scan Conversion
 - aka Rasterization
 - Images are represented in Discrete 2D space:
 - i.e., a grid of pixels
 - Until this stage everything was done in continous 2D stage.
 - In this stage we convert the vertex information output by the geometry pipeline into pixel information needed by the video display



- Step 6 Scan Conversion
 - In this stage we also determine the fill colors of each triangle
 - Remember the lighting stage ?
 - Everything we calculate in stage 2 will be used to determine the fill color: $_{\rm V}$

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- Step 6 Scan Conversion
 - Below there are two options for the same triangle rasterization
 - Aliasing: distortion artifacts produced when representing a high-resolution signal at a lower resolution.
 - In this stage we handle aliasing artifacts using anti-aliasing algorithms





- Step 6 Scan Conversion
 - What about hidden surfaces ?
 - We use the Z-buffer algorithm:
 - In addition to the frame buffer (keeping the pixel values), keep a Z-buffer containing the depth value of each pixel.
 - Surfaces are scan-converted in <u>an arbitrary order</u>. For each pixel (x,y), the Z-value is computed as well. The (x,y) pixel is overwritten only if its Z-values is closer to the viewing plane than the one already written at this location.



- Step 6 Scan Conversion
 - The Z-buffer algorithm example:







Graphical Pipeline - Summary



- Assume a scene with one light source
- How shadows are casted in ray-tracing ?
 - Shoot rays from the intersection point to the light source:
 - If the ray intersect another object the light is occluded by another object
 - There should be no light
 - Otherwise:
 - There is light calcuate the intersection point color using Phong reflectance model
- But how can we support shadows in the graphical pipeline ?
 - Solution: shadow mapping

- If you looked out from a source of light:
 - All of the visible objects appear in light.
 - Anything behind those objects, would be in shadow.

- Step (1) Check which objects are closest to the light source
 - For each vertex (x,y,z) in the scene calculate the coordinates in the "light" coordinate system
 - Simply multiply by the View transformation matrix in which the camera is located in the lightsource location
 - Project the vertex into 2D:
 - Perspective projection if spotlight is used (point light)
 - What is the center of projection ?
 - Orthographic projection if directional light is used
 - Whatis the direction of projection ?
 - Render the vertex*:
 - The z-buffer is extracted and saved in memory as shadow mapping
 - Avoid updating the color buffers and disable all lighting and texture calculations to save computation

- Step (2) Check whether a point (x,y,z) is shadowed ?
 - Render the vertex (x,y,z) from the usual camera view
 - In the shading stage:
 - Transform the vertex (x,y,z) to the light coordinate system.
 - (x,y,z) -> (x',y',z')
 - Calculate the pixel coordinate of the vertex as if rendered from the light-source view
 - (x',y',z') -> (x'', y'', z'')
 - Check the shadow mapping (z-buffer from previous step) at (x", y"):
 - The z-value stored in (x",y") is less than z':
 - The light source is occluded because the (x,y,z) is not closest to camera and shouldn't be included in the color calculation of (x,y,z)
 - Otherwise:
 - The light source is not occluded and can be considered in the color calculation of (x,y,z)

- In which stage shadow mapping should be considered ?
 - Lighting stage for Gouraud shading
 - Lighting and Rasterization stage in phong shading

- We are given a 3D scene that is composed of several objects built from triangles.
- After we are done rendering it from the point of view of the camera and get a final image, we find out that we forgot to render one object in the scene.
 - The naïve way to fix this would be to render all the scene from scratch, but we want to fix the image in a more efficient way.

- In each of the following algorithms explain if this is possible? If so, explain what is needed and if not explain why?
- a) We are using simple Ray Casting algorithm (without shadows) to create the image.
- Ray Casting means no reflections or transparencies.
- Since we're not using shadows, the new object can't affect other objects.
- The pixel color is determined by the first intersection point of the ray that goes through that pixel.
 - Therefore, only pixels that object will appear on may be affected.
- Possible solution:
 - find the axis-aligned bounding box of the object and project it onto the picture.
 - These are the pixels that may change color.

- In each of the following algorithms explain if this is possible? If so, explain what is needed and if not explain why?
- b) We are using Ray Tracing algorithm to create the image.
- In Ray Tracing the new object can:
 - Project shadows on the other objects
 - Can be seen through other (reflective) objects in the scene
 - Can be reflected off any surface in the scene.
- This means there may be changes in all pixels.
 - We must re-render it the scene completely.

- In each of the following algorithms explain if this is possible? If so, explain what is needed and if not explain why?
- c) We are using the simple graphical pipeline algorithm (without shadows and textures) that uses a z-buffer to create the image.
- In the graphical pipeline we can simply continue the rendering process by sending the object triangles to the pipeline:
 - Use the *z*-buffer (with values from the original rendering) to resolve any object collision