# Data Structures 

## Hashing

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## Dictionaries

$\mathrm{D} \leftarrow$ Dictionary() - Create an empty dictionary
Insert( $D, x$ ) - Insert item $x$ into $D$
Find $(D, k)$ - Find an item with key $k$ in $D$
Delete $(D, k)$ - Delete item with key $k$ from $D$
(Predecessors and successors, etc., not supported)

## Can use balanced search trees <br> $\mathrm{O}(\log \mathrm{n})$ time per operation

Can we do better?
YES !!!

## Dictionaries with "small keys"

Suppose all keys are in $[m]=\{0,1, \ldots, m-1\}$, where $m=O(n)$
Can implement a dictionary using an array $D$ of length $m$.

$\operatorname{Insert}(D, x): D[x . k e y] \leftarrow x$
Find $(D, k)$ : return $D[k]$
Delete $(D, k): D[k] \leftarrow$ null

Special case: Sets
$D$ is a bit vector

O(1) time per operation (after initialization)
(Assume different items have different keys.)
What if $m \gg n$ ? Use a hash function

## Hashing

## Huge

## universe $U$



## Hashing with chaining [Luhn (1953)] [Dumey (1956)]

## Each cell points to a linked list of items



# Hashing with chaining with a random hash function 

## Balls in Bins

Throw $n$ balls randomly into $m$ bins

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All throws are uniform and independent

## Balls in Bins

Throw $n$ balls randomly into $m$ bins

## Expected number of balls in each bin is $n / m$

When $n=\Theta(m)$, with probability of at least $1-1 / n$, all bins contain at most $\mathrm{O}(\log n /(\log \log n))$ balls

## What makes a hash function good?



Behaves like a "random function" Has a succinct representation Easy to compute

A single hash function cannot satisfy the first condition

## Families of hash functions

We cannot choose a "truly random" hash function Using a fixed hash function is usually not a good idea

## Compromise:

Choose a random hash function $h$ from a carefully chosen family $H$ of hash functions
Each function $h$ from $H$ should have a succinct representation and should be easy to compute

## Goal:

For every sequence of operations, the running time of the data structure, when a random hash function $h$ from $H$ is chosen, is expected to be small

## Modular hash functions [Carter-Wegman (1979)]

$$
\begin{gathered}
h(x)=x \bmod m \\
x \bmod 2^{k}=x \operatorname{and}\left(2^{k}-1\right) \\
h_{a, b}(x)=((a x+b) \bmod p) \bmod m \\
h_{a, b}: U=[p] \rightarrow[m] \\
p-\text { prime number }
\end{gathered}
$$

Form a "Universal Family" (see below) Require (slow) divisions

## Multiplicative hash functions

## [Dietzfelbinger-Hagerup-Katajainen-Penttonen (1997)]

$$
h_{a}: U=\left[2^{w}\right] \rightarrow\left[2^{k}\right] \quad h_{a}(x)=\left\lfloor\frac{a x \bmod 2^{w}}{2^{w-k}}\right\rfloor
$$

Typically, $w$ is the number of bits in a machine word


$$
h_{a}(x)=(\mathrm{a} * \mathrm{x}) \gg(\mathrm{w}-\mathrm{k})
$$

Form an "almost-universal" family (see below)
Extremely fast in practice!

## Tabulation based hash functions [Patrascu-Thorup (2012)]



A variant can also be used to hash strings

$h_{i}$ can be stored in a small table

Very efficient in practice
Very good theoretical properties

## Universal families of hash functions

 [Carter-Wegman (1979)]A family $H$ of hash functions from $U$ to [ $m$ ] is said to be universal if and only if for every $k_{1} \neq k_{2} \in U$ we have

$$
\operatorname{Pr}_{h \in H}\left[h\left(k_{1}\right)=h\left(k_{2}\right)\right] \leq \frac{1}{m}
$$

A family $H$ of hash functions from $U$ to [ $m$ ] is said to be almost universal if and only if

$$
\begin{aligned}
& \text { for every } k_{1} \neq k_{2} \in U \text { we have } \\
& \operatorname{Pr}_{h \in H}\left[h\left(k_{1}\right)=h\left(k_{2}\right)\right] \leq \frac{2}{m}
\end{aligned}
$$

## k-independent families of hash functions

A family $H$ of hash functions from $U$ to $[m]$ is said to be $k$-independent if and only if for every distinct $x_{1}, x_{2}, \ldots, x_{k} \in U$ and $y_{1}, y_{2}, \ldots, y_{k} \in[m]$

$$
\operatorname{Pr}_{h \in H}\left[h\left(x_{1}\right)=y_{1}, h\left(x_{2}\right)=y_{2}, \ldots, h\left(x_{k}\right)=y_{k}\right]=\frac{1}{m^{k}}
$$

A family $H$ of hash functions from $U$ to $[m]$ is said to be almost $k$-independent if and only if for every distinct $x_{1}, x_{2}, \ldots, x_{k} \in U$ and $y_{1}, y_{2}, \ldots, y_{k} \in[m]$

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$$

## A simple universal family [Carter-Wegman (1979)]

$$
\begin{gathered}
U=[p]=\{0,1, \ldots, p-1\}, \text { where } p \text { is prime } \\
H_{p, m}=\left\{h_{a, b} \mid 1 \leq a<p, 0 \leq b<p\right\} \\
h_{a, b}(x)=((a x+b) \bmod p) \bmod m \\
h_{a, b}:[p] \rightarrow[m]
\end{gathered}
$$

Theorem: $H_{p, m}$ is a universal family
To represent a function from the family we only need two numbers, $a$ and $b$.

The size $m$ of the hash table can be arbitrary.

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h_{a, b}:[p] \rightarrow[m]
\end{gathered}
$$

Theorem: $H_{p, m}$ is a universal family
Let $x_{1} \neq x_{2} \in[p]$. For every $y_{1} \neq y_{2} \in[p]$ there are unique $a, b \in[p], a \neq 0$, such that $y_{1} \equiv_{p} a x_{1}+b$ and $y_{2} \equiv_{p} a x_{2}+b$.
Thus, $\mathbb{P}\left[y_{1} \equiv_{m} y_{2}\right] \leq \frac{\left\lceil\frac{p}{m}\right\rceil-1}{p-1} \leq \frac{\frac{p+m-1}{m}-1}{p-1}=\frac{1}{m}$

## Probabilistic analysis of chaining

$n$ - number of elements in dictionary $D$

$$
m \text { - size of hash table }
$$

$$
\alpha=n / m-\operatorname{load} \text { factor }
$$

Assume that $h$ is randomly chosen from a universal family $H$

$$
\begin{array}{c|c}
\text { If } k \notin D, \text { then } & \text { If } k \in D, \text { then } \\
E[|\operatorname{List}(h(k))|] \leq \frac{n}{m}=\alpha & E[|\operatorname{List}(h(k))|] \leq 1+\frac{n-1}{m} \leq 1+\alpha
\end{array}
$$

|  | Expected | Worst-case |
| :---: | :---: | :---: |
| Successful Search <br> Delete | $1+\frac{\alpha}{2}$ | $n$ |
| Unsuccessful Search <br> (Verified) Insert | $1+\alpha$ | $n$ |

## Chaining: pros and cons

## Pros:

Simple to implement (and analyze)
Constant time per operation $(\mathrm{O}(1+\alpha))$
Fairly insensitive to table size
Simple hash functions suffice

## Cons:

Space wasted on pointers
Dynamic allocations required
Many cache misses

## Hashing with open addressing

## Hashing without pointers

$$
\text { Assume that } h: U \times[m] \rightarrow[m]
$$

Insert key $k$ in the first free position among $\underbrace{h(k, 0), h(k, 1), h(k, 2), \ldots, h(k, m-1)}$

Assumed to be a permutation


No room found $\rightarrow$ Table is full
To search, follow the same order

## Hashing with open addressing



## How do we delete elements?

Caution: When we delete elements, do not set the corresponding cells to null!


Problematic solution...

## Probabilistic analysis of open addressing

$n$ - number of elements in dictionary $D$ $m$ - size of hash table $\alpha=n / m-\operatorname{load}$ factor (Note: $\alpha \leq 1$ )

Uniform probing: Assume that for every $k$, $h(k, 0), \ldots, h(k, m-1)$ is random permutation

Expected time for unsuccessful search

$$
\frac{1}{1-\alpha}
$$

Expected time for successful search

$$
\frac{1}{\alpha} \ln \frac{1}{1-\alpha}
$$

## Probabilistic analysis of open addressing

Claim: Expected no. of probes for an unsuccessful search is at most:


If we probe a random cell in the table, the probability that it is full is $\alpha$.

The probability that the first $i$ cells probed are all occupied is at most $\alpha^{i}$.

$$
1+\alpha+\alpha^{2}+\ldots=\frac{1}{1-\alpha}
$$

## Open addressing variants

How do we define $h(k, i)$ ?

$$
\begin{gathered}
\text { Linear probing: } \\
h(k, i)=\left(h^{\prime}(k)+i\right) \bmod m
\end{gathered}
$$

Quadratic probing:

$$
h(k, i)=\left(h^{\prime}(k)+c_{1} i+c_{2} i^{2}\right) \bmod m
$$

Double hashing:

$$
h(k, i)=\left(h_{1}(k)+i h_{2}(k)\right) \bmod m
$$

## Linear probing

"The most important hashing technique"


More probes than uniform probing, as probe sequences "merge"

But, much less cache misses
Extremely efficient in practice
More complicated analysis
(Requires 5-independence or tabulation hashing)

## Linear probing - Deletions



Can the key in cell $j$ be moved to cell $i$ ?


## Linear probing - Deletions



When an item is deleted, the hash table is in exactly the state it would have been if the item were not inserted!

## Expected number of probes Assuming random hash functions


[Knuth (1962)]
When, say, $\alpha \leq 0.6$, all small constants

## Expected number of probes



## Perfect hashing

## Suppose that $D$ is static.

We want to implement Find is $\mathrm{O}(1)$ worst case time.


## Perfect hashing: No collisions

Can we achieve it?

## Expected no. of collisions

Suppose that $|D|=n$ and that $h$ is randomly chosen from a universal family

$$
\begin{gathered}
\text { Collisions: } \\
\text { Col }=\left\{\left\{k_{1}, k_{2}\right\} \subseteq D \mid k_{1} \neq k_{2}, h\left(k_{1}\right)=h\left(k_{2}\right)\right\} \\
E[|C o l|]=\sum_{\substack{\left\{k_{1}, k_{2}\right\} \subseteq D \\
k_{1} \neq k_{2}}} \operatorname{Pr}\left[h\left(k_{1}\right)=h\left(k_{2}\right)\right] \leq \frac{\binom{n}{2}}{m}
\end{gathered}
$$

Corollary 1: If $m=n$, then $E[|C o l|]<\frac{n}{2}$
Corollary 2: If $m=n^{2}$, then $E[|C o l|]<\frac{1}{2}$

## Expected no. of collisions

Markov's inequality: $\operatorname{Pr}[X \leq 2 E[X]] \geq \frac{1}{2}$
Corollary 1: If $m=n$, then $E[|C o l|]<\frac{n}{2}$
Corollary 1': If $m=n$, then $\operatorname{Pr}[|\operatorname{Col}|<n] \geq \frac{1}{2}$
Corollary 2: If $m=n^{2}$, then $E[|C o l|]<\frac{1}{2}$
Corollary 2': If $m=n^{2}$, then $\operatorname{Pr}[|C o l|<1] \geq \frac{1}{2}$
If we are willing to use $m=n^{2}$, then any universal family contains a

No collisions! perfect hash function.

## Two level hashing

[Fredman, Komlós, Szemerédi (1984)]


## Two level hashing

[Fredman, Komlós, Szemerédi (1984)]


Choose $m=n$ and $h$ such that $|C o l|<n$
Store the $n_{i}$ elements hashed to $i$ in a small hash table of size $n_{i}^{2}$ using a perfect hash function $h_{i}$

## Two level hashing

[Fredman, Komlós, Szemerédi (1984)]


Assume that each $h_{i}$ can be represented using 2 words

$$
\begin{aligned}
& 3+n+3 n+\sum_{i} n_{i}^{2} \\
= & 4 n+3+\sum_{i}\left(2\binom{n_{i}}{2}+n_{i}\right) \\
= & 5 n+3+2|C o l|
\end{aligned}
$$

Total size:

# A randomized algorithm for constructing 

 a perfect two level hash table:Choose a random $h$ from $H(p, n)$ and compute the number of collisions. If there are more than $n$ collisions, repeat.

For each cell $i$, if $n_{i}>1$, choose a random hash function $h_{i}$ from $H\left(\mathrm{p}, n_{i}^{2}\right)$. If there are any collisions, repeat.

Expected construction time $-\mathrm{O}(n)$
Worst case search time - O(1)

## Cuckoo Hashing [Pagh-Rodler (2004)]



# Cuckoo Hashing [Pagh-Rodler (2004)] 

```
Function Cuckoo-Search \((T, k)\)
    \(i_{1} \leftarrow h_{1}(k)\)
    if \(T_{1}\left[i_{1}\right] . k e y=k\) then return \(T_{1}\left[i_{1}\right]\)
    \(i_{2} \leftarrow h_{2}(k)\)
    if \(T_{2}\left[i_{2}\right] . k e y=k\) then return \(T_{2}\left[i_{2}\right]\)
    return null
```

O(1) worst case search time! What is the (expected) insert time?

# Cuckoo Hashing [Pagh-Rodler (2004)] 

Difficult insertion


How likely are difficult insertion?

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# Cuckoo Hashing [Pagh-Rodler (2004)] 

A failed insertion


If Insertion takes more than MAX steps, rehash

# Cuckoo Hashing [Pagh-Rodler (2004)] 

```
Function Cuckoo-Insert(T, x)
    for}i\leftarrow1\mathrm{ to MAX do
        x}\leftrightarrow\mp@subsup{T}{1}{}[\mp@subsup{h}{1}{}(x.key)
        if x= null then return
        x}\leftrightarrow\mp@subsup{T}{2}{[}[\mp@subsup{h}{2}{(x.key)]
        if x= null then return
    Rehash(T)
    Cucko-Insert(T, 位
```

With hash functions chosen at random from an appropriate family of hash functions, the amortized expected insert time is $\mathrm{O}(1)$

