# Non Deterministic Tree Automata

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#### Word automata -

Consume infinite sequences of alphabet symbols (ω-words)



### Today

Tree automata -

Finite-state automata

which process infinite trees



#### Outline

- Motivation
- Infinite binary tree
- Finite-State Tree Automata
- Examples
- Buchi tree automata Vs. Muller tree automata
- The Complementation Problem for Automata on Infinite Trees
  - Game theoretical approach
  - Complementation proof

#### First of all - WHY?

• Tree automata are similar to logical theories  $\rightarrow$ 

Reduce problems in logic to problems for automata.

• Tree automata are more suitable than words when non-determinism needs to be modeled.

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- $T\omega = \{0, 1\}^*$  of all finite words on  $\{0, 1\}$
- Elements  $u \in T_{\omega}$  are the nodes of  $T_{\omega}$ :
  - ο ε root
  - $\circ$  u<sub>0</sub>, u<sub>1</sub> immediate successors of node u

- Again :)
  - $\circ$  Left U0
  - Right U1



- Path  $\omega$ -word  $\pi \in \{0,1\}^{\omega}$
- Set  $Pre < (\pi) \subseteq \{0,1\}^*$  of all prefixes of path  $\pi$ 
  - Describes the set of nodes which occur in  $\pi$

- Example:
  - The rightmost path in the tree is  $\pi = 1\omega$
  - All the prefixes of this path are:
  - $\circ \quad \operatorname{Pre}_{(\pi)} = \{\epsilon, 1, 11, 111, 1111, ...\} = \{1\}^{*}$



- Let  $u,v \in T\omega$ , then v is a **successor** of u, if there exists  $w \in T\omega$  such that v = uw
- Denoted by u < v

- Example:
  - 01 is successor of 0
  - $\circ$  101 is successor of 1 \ 10



- Our tree can be **labeled**
- $\Sigma$  is alphabet
- A mapping t:  $T\omega \rightarrow \Sigma$ 
  - Maps each node of  $T\omega$  to a symbol in  $\Sigma$

*Example* 8.1. Let  $\Sigma = \{a, b\}, t(\varepsilon) = a, t(w0) = a$  and  $t(w1) = b, w \in \{0, 1\}^*$ .



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# **Definitions - Finite-State Tree Automata**

- Until now, automata consume one input symbol at a time
  - Enter a successor state determined by a transition relation
  - $\circ \quad \delta: \mathbf{Q} \times \Sigma \to \mathbf{Q}$

- Now, we want to run automata on infinite trees
- The transition function:
  - $\circ \quad \delta: Q \times \Sigma \to Q \ge Q$

# **Definitions - Finite-State Tree Automata**

Tree automaton is of the form A = (Q, $\Sigma$ , $\delta$ ,q<sub>0</sub>,F), where:

- Q is finite set of states
- $\Sigma$  is a finite alphabet
- $\delta \subseteq (Q \times \Sigma) \times (Q \times Q)$  is the transition function
- $q_0$  is the initial state
- F is the acceptance component

# **Definitions - Finite-State Tree Automata**

• Computations start at the root of an input tree and work through the input on each path in parallel

• A transition  $(q_{,a},q_{_1},q_{_2})$  allows to pass from state q at node u with label a i.e. t(u) = a, to the states  $q_{_1},q_{_2}$  at the successor nodes  $u_{_0},u_{_1}$ 

# **Definitions** - **RUN**

Assignment of states to the tree nodes

- $\rho: \{0,1\}^* \to Q$  with:
  - $\rho(\epsilon) = q_0$
  - $\circ \quad (\rho(u),t(u),\rho(u_{_0}),\rho(u_{_1})) \in \delta \text{ for all } u \in \{0,1\}^*$
- Example:
  - $\circ$  (q<sub>0</sub>,a,q<sub>0</sub>,q<sub>0</sub>)
  - $\circ \quad (\mathsf{q}_0,\mathsf{b},\mathsf{q}_1,\mathsf{q}_0)$
  - ( $q_1, a, q_1, q_1$ )
  - $\circ \quad (\mathbf{q}_1, \mathbf{b}, \mathbf{q}_1, \mathbf{q}_1)$



#### Definitions - run

- Successful run
  - **Each path** of the  $\rho$  is successful with respect to acceptance condition
- Acceptance conditions:
  - o Buchi
  - $\circ$  Muller
  - Rabin
  - Parity
- Language of an automaton A with alphabet Σ, is the set of Σ-trees which are accepted by A
  - Denoted L(A)

#### **Buchi Tree Automaton**

• Tree automaton A =  $(Q,\Sigma,\delta,q_0,F)$  accepts tree t if there exists a run  $\rho$  of A on t, such that on **EACH PATH** of  $\rho$ , a state from F occurs infinitely times

What about Muller?

• For each path  $\pi \in \{0,1\}^{\omega}$  the Muller acceptance condition is satisfied  $\circ$  Inf  $(\rho|\pi) \in F$ 

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#### Starting Windows

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#### Examples (1)

L(A) is the set of all  $\Sigma$ -trees having at least one b on every branch

Let's look on every path separately

- $F = \{q_1\}$
- Transition function
  - $\circ$  (q<sub>0</sub>,a,q<sub>0</sub>,q<sub>0</sub>)
  - $\circ \quad (\mathsf{q}_0,\mathsf{b},\mathsf{q}_1,\mathsf{q}_1)$
  - $\circ$  (q<sub>1</sub>,a,q<sub>1</sub>,q<sub>1</sub>)
  - $\circ \quad (\mathbf{q}_1, \mathbf{b}, \mathbf{q}_1, \mathbf{q}_1)$



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#### Examples (2)

L(A2) is the set of all  $\Sigma$ -trees which have at least one branch with infinitely many b's

- $Q = \{q_a, q_b, q_+\}$  $F = \{q_b, q_+\}$
- ullet
- Transition relation:





#### Examples (2)

L(A2) is the set of all  $\Sigma$ -trees which have at least one branch with infinitely many b's

- Non deterministic
- $Q = \{q_a, q_b, q_+\}$
- $F = \{q_b, q_+\}$
- Transition relation:





#### Examples (3)

L(A3) is the set of all  $\Sigma$ -trees having infinitely many a's on every branch

Buchi tree automata A3:

- $Q = \{q_a, q_b\}$
- Initial state q<sub>a</sub>
- $F = \{q_a\}$
- Transition function
  - $\circ \quad (\mathbf{q}_{\mathbf{a}}, \mathbf{a}, \mathbf{q}_{\mathbf{a}}, \mathbf{q}_{\mathbf{a}})$
  - $\circ \quad (\mathbf{q}_{\mathrm{b}}, \mathrm{a}, \mathbf{q}_{\mathrm{a}}, \mathbf{q}_{\mathrm{a}})$
  - $\circ \quad (\mathbf{q}_{a}, \mathbf{b}, \mathbf{q}_{b}, \mathbf{q}_{b})$
  - $\circ \quad (\mathbf{q}_{\mathrm{b}},\mathbf{b},\mathbf{q}_{\mathrm{b}},\mathbf{q}_{\mathrm{b}})$

#### Examples (4)

L(A4) is the set of  $\Sigma$ -trees in which every branch contains only finitely many b's

Muller tree automata A4:

- $Q = \{q_a, q_b\}$
- Initial state q<sub>a</sub>
- $F = \{\{q_a\}\}$
- Transition function (the same as Example 3)
  - $\circ \quad (\mathbf{q}_{\mathbf{a}}, \mathbf{a}, \mathbf{q}_{\mathbf{a}}, \mathbf{q}_{\mathbf{a}})$
  - $\circ \quad (\mathbf{q}_{\mathrm{b}}, \mathrm{a}, \mathbf{q}_{\mathrm{a}}, \mathbf{q}_{\mathrm{a}})$
  - $\circ \quad (\mathbf{q}_{a}, \mathbf{b}, \mathbf{q}_{b}, \mathbf{q}_{b})$
  - $\circ \quad (\mathbf{q}_{\mathrm{b}}, \mathbf{b}, \mathbf{q}_{\mathrm{b}}, \mathbf{q}_{\mathrm{b}})$
- Is it the same as Example 3?

#### Examples (5)

L(A5) is the set of all  $\Sigma$ -trees having at least one path  $\pi$  through t such that  $t|\pi \in (a + b)^*(ab)^{\omega}$ 

- We will use muller
- A5 memorizes in its state the last read input symbol
- A5 switches back to the initial state  $q_T$  if he get unexpected symbol
- Infinite alternation between a state q<sub>a</sub> memorizing input symbol a and a state q<sub>b</sub> memorizing b
- A will guess a path through t and checks, if the label of this path belongs to (a+b)\* (ab)<sup>ω</sup>

#### Examples (5)

- **Guess** decide whether the left or the right successor node of the input tree belongs to the path
- q<sub>d</sub> signals that we are outside the guessed path
- $A = (\{q_I, q_a, q_b, q_d\}, \{a, b\}, \delta, q_I, \{\{q_a, q_b\}, \{q_d\}\})$

#### • δ:

- $\circ \quad \text{Initial} (q_{I}, a, q_{a}, q_{d}) \setminus (q_{I}, a, q_{d}, q_{a}) \setminus (q_{I}, b, q_{b}, q_{d}) \setminus (q_{I}, b, q_{d}, q_{b})$
- For  $q_d$  ( $q_d$ , a,  $q_d$ ,  $q_d$ ) \ ( $q_d$ , b,  $q_d$ ,  $q_d$ )
- $\circ \quad \text{Change letter } (q_a, b, q_b, q_d) \setminus (q_a, b, q_d, q_b) \setminus (q_b, a, q_a, q_d) \setminus (q_b, a, q_d, q_a)$
- Same letter  $(q_a, a, q_I, q_d) \setminus (q_a, a, q_d, q_I) \setminus (q_b, b, q_I, q_d) \setminus (q_b, b, q_d, q_I)$

#### Examples (5)

There is no situation where  $Inf(\rho|\pi) =$ 

- $\{\{q_d\}\}$
- {{ $q_a$ }} \ {{ $q_a$ },{ $q_d$ }}
- $[{q_b}]$  \  $[{q_b}, {q_d}]$



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#### Theorem 1

Buchi tree automata are strictly weaker than Muller tree automata

• **In Hebrew:** There exists a Muller tree automaton recognizable language which is not Buchi tree automaton recognizable

#### <u>Proof</u>

- The language
  - $T = \{t \in T\{a,b\} \mid any \text{ path through t carries only finitely many b} \}$

can obviously be recognized by a Muller tree automaton (example 4)

#### Theorem 1 (proof)

- Assume for contradiction that T is recognized by a Buchi tree automaton  $B = (Q, \Sigma, \delta, q_I, F)$
- Let n = |F| + 1
- Consider the following tree:



#### Theorem 1 (proof)

....

• Because the automata accepts t:

- Path  $1^{\omega}$  a final state is visited say at  $1^{m0}$
- Path  $1^{m0}01^{\omega}$  a final state is visited say at  $1^{m0}01^{m1}$
- Proceeding in this way we obtain n + 1 positions -
- $V_0 = 1^{m0}$ ,  $V_2 = 1^{m0} 01^{m1}$ , ...,  $V_n = 1^{m0} 01^{m1} 0...1^{mn}$  that get to final state
- For certain i < j, the same state appears at  $V_i$  and  $V_j$
- Between  $V_i$  and  $V_i$  at least one label b (by our construction)

### Theorem 1 (proof)

We now construct another input tree t' by infinite repetition of the path from  $V^{}_{\rm i}$  to  $V^{}_{\rm j}$  ( $\pi$ )

- This tree contains an infinite path which carries infinitely many b's, thus t'  $\notin$  T
- We can easily construct a successful run on t' by copying the actions of  $\pi$  infinitely often  $\Rightarrow$  t'  $\in$  T
- Contradiction

#### Theorem 2

Muller, parity, Rabin and Streett tree automata all recognize the same tree languages

#### **Parity Tree Automaton**

- Tree automaton A =  $(Q, \Sigma, \delta, q_0, C)$
- Coloring C: Q -> {0,....,k}
- Accepts tree t if there exists a run ρ of A on t such that on EACH PATH of ρ, the maximal color assumed infinitely often is even
- Example:
  - Automata that recognize trees that each path of them has only finitely many b
  - Use  $q_a$  and  $q_b$  to signal the letters a,b
  - $C(q_a) = 0, C(q_b) = 1$
  - The maximal color is even  $\Leftarrow$ > the letter b occurs finitely often on the path

lime for a break!

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#### **Closure under complementation**

- We will now show closure under complementation for tree languages acceptable by parity tree automata
  - $\circ$  and hence acceptable by Muller tree automata
- For every automata  $A = (S, T, T_0, \mathcal{F})$ , there is an automata  $A' = (S', T', T_0', \mathcal{F}')$  such that:

 $v \in L(A') \Leftrightarrow v \notin L(A)$ 

We identify a parity tree automaton A = (Q,Σ,δ,q<sub>I</sub>,c) and an input tree t with an infinite two-person game G<sub>A,t</sub>

#### Rules

- The players move alternately
- Player 0 (Automaton): picking transition from  $\Delta$  such that the alphabet symbol of this transition equals that at the current node
- Player 1 (Pathfinder): determines whether to proceed with the left or the right successor
- Example

#### Run Example

#### $\Delta$ :

- $(q_I, b, q_b, q_b)$
- $(q_I, a, q_I, q_I)$
- $(q_b, b, q_b, q_b)$
- $(q_b, a, q_a, q_a)$
- $(q_a, a, q_a, q_a)$
- $(q_a, b, q_b, q_b)$



### Winning

- Play single sequence of actions  $\circ \pi = s_0, d_1, s_1, d_2, \dots$
- $In(\pi) = \{s \in S | s = s_n \text{ for infinitely many } n\}$
- Player 0 wins the play if this infinite state sequence satisfies the acceptance condition of A
  - $\circ \quad In(\pi) \in \mathcal{F}$
- Otherwise Player 1 wins
- Game = set of plays



### Winning strategy

- Automaton all paths of the corresponding run meet the acceptance condition -> A accepts the tree
- Pathfinder if there exists a path which violates the acceptance condition for every state sequence chosen by player 0 -> A rejects the tree

In other words:

- Automaton has winning strategy in  $G_{A,t} \Leftrightarrow t \in L(A)$
- Pathfinder has winning strategy in  $G_{A,t} \Leftrightarrow t \notin L(A)$



#### **Game Positions**

- A play is an infinite sequence of game positions which alternately belong to player 0 or player 1
- A game can be considered as a graph which consists of all game positions as vertices
- Edges between different positions indicate that the succeeding position is reachable from the preceding one by a valid action

#### **Definitions - Game Positions**

• Player 0 (should decide on transition):

 $V_0 = \{(w,q) | w \in \{0,1\}^*, q \in Q\}$ 

• Player 1 (should decide on state):

 $V_1 = \{(w,\delta) | w \in \{0,1\}^*, \delta \in \Delta_{t(w)}\}$ 

#### min-parity game

Game  $G_{A,\alpha}$  for a parity automata  $A = (Q, \Sigma, \delta, q_I, c)$  and  $\alpha \in \Sigma^{\omega}$  is a graph (V, E,C) that serves as an arena for the two players 0 and 1.

The graph (V, E,C) is defined as follows:

- The set of vertices V can be partitioned into the two sets V0 and V1
  - $\circ V_0 = Q \times \omega$
  - $\circ V_1 = Q \times P(Q) \times \omega$
- The edge relation  $E \subseteq (V0 \times V1) \cup (V1 \times V0)$  is defined by
  - $\circ \quad ((q,i),(q,M,j)) \in E \Leftrightarrow j = i+1 \text{ and } M \in Mod(\delta(q,\alpha(i)))$
  - $\circ \quad ((p,M,i),(q,j)) \in E \Leftrightarrow j = i, q \in M, \text{ and } c(q) \in C$

#### Graph example

- Game position u = (w,q) of player 0
- Player 0 chooses a transition  $\tau = (q,t(w),q_0,q_1)$
- Game position  $v = (w,\tau)$  of player 1
- Edge (u,v) then represents a valid move of player 0
- Player 1 chooses a direction  $i \in \{0,1\}$
- Game position  $u' = (w_i, q'_i)$  of player 0
- Edge (v,u') represents a valid move of player 1

#### Definition

We need to color the vertices (since it is a parity game):

The coloring function C:  $V_0 \cup V_1 \rightarrow \{0,1,...,k\}$ 

• 
$$\forall$$
 (w,q)  $\in$  V<sub>0</sub>, C((w,q)) = c(q)

•  $\forall$  (w,(q,t(w),q\_0,q\_1))  $\in$  V<sub>1</sub>, C((w,(q,t(w),q\_0,q\_1))) = c(q)

Why are we doing all of this?

- The game  $G_{A_t}$  meet exactly the definition of min-parity game
- The notions of a **strategy**, a **memoryless strategy** and a **winning strategy**, as defined last lecture apply to the games G<sub>A,t</sub> as well



A tree automaton A accepts an input tree t  $\Leftrightarrow$ 

There is a winning strategy for Player 0 from position ( $\epsilon$ ,  $q_I$ ) in the game  $G_{A,t}$ 

#### **Proof** - 1'st Direction

- A accepts the input tree t  $\Rightarrow$  there exists an accepted run  $\rho$
- The run ρ keeps track of all transitions that have to be chosen in order to accept the input tree t
- For any of the nodes  $(w,q) \in V_0$ , where  $(w_0,q_0)$  and  $(w_1,q_1)$  are the immediate successors, we can derive the corresponding transition

 $\circ \quad \delta = (q,t(w),q_0,q_1) \subseteq \Delta$ 

- Since ρ determines for each node and each path the correct transition, Player 0 can always choose the right transition, independently of Player 1's decisions
- He will always win
- (Player 1's decide on the direction, but A accepts all the paths of t)

#### **Proof - 2'nd Direction**

- We can use the winning strategy f<sub>0</sub> for player 0 in G<sub>A,t</sub> to construct a successful run of A on t
- For each game position (w,q)  $\in$  V<sub>0</sub>, f<sub>0</sub> determines the correct transition  $\delta = (q,t(w),q_0,q_1) \in \Delta$
- Player 0 must be prepared to proceed from both  $(w_0,q_0)$  and  $(w_1,q_1)$  since he cannot predict player 1's decision
- However, for both positions the winning strategy can determine correct transitions
- Hence we label w by q,  $w_0$  by  $q_0$  and  $w_1$  by  $q_1 =>$  obtain the entire run  $\rho$
- $\rho$  is successful since it is determined by a winning strategy  $f_0$

### Winning Strategy

Known facts about parity games:

- Parity games are determined
  - One of the players has a memoryless winning strategies
- Memoryless winning strategies are enough to win a game

#### In other words -

From any game position in  $G_{A,t}$ , either Player 0 or Player 1 has a memoryless winning strategy

#### The Complementation of Finite Tree Automata Languages

- Outline:
- Given a parity tree automaton A, we have to specify a tree automaton B that accepts all input trees rejected by A
- Rejecting means that there is no winning strategy for player 0 from position (ε,q<sub>i</sub>) in the game G<sub>A,t</sub>
- This guarantees the existence of a memoryless winning strategy starting at (ε,q<sub>i</sub>) for player 1
- We will construct an automaton that checks exactly this

#### Memoryless Strategy of Player 1

- Function f1 : {0,1}\* X △ → {0,1} determining a direction 0 (left successor) or 1 (right successor)
- There is a natural isomorphism between such functions and functions of the type  $f1 : \{0,1\}^* \to (\Delta \to \{0,1\})$
- fl is a tree (with functions as labels)
- We call such trees strategy trees
- If the corresponding strategy is winning for player 1 in the game G<sub>A,t</sub>, we say it is a winning tree for t



From the previous definitions:

Let A be a parity tree automaton and t be an input tree.

There exists a winning tree s for player 1 <=> if A does not accept t

#### First step -

- ω-automaton M will decide if each path of t, using the strategy for player 1 defined by s (tree), will be accepted by A. If yes it accepts.
- M will need to check all the possible strategies for player 0
- As we saw -
  - At least once A's acceptance condition is met  $\Leftrightarrow$  s cannot be a winning tree for t
- M needs to handle all  $\omega$ -words of the form u = (s( $\varepsilon$ ), t( $\varepsilon$ ),  $\pi_1$ )(s( $\pi_1$ ), t( $\pi_1$ ),  $\pi_2$ )....

#### Example

• Path  $\pi$  = 0110... on t



- $f: \Delta \rightarrow \{0, 1\}$  (from s)
- $a \in \Sigma$
- $i \in \{0, 1\}$  (f( $\tau$ ) = i)

#### **M** - definitions

- $M = (Q, \Sigma', \Lambda, q_I, c)$
- $\Sigma' = \{(f, a, i) \mid f : \Delta \rightarrow \{0, 1\}, a \in \Sigma, i \in \{0, 1\}\}$
- A and M have the same acceptance conditions
- $\Lambda$  (transitions):
- For (f,a,i)  $\in \Sigma$ '
  - map<sub>a</sub> denotes the set of all mappings from  $\Delta_a$  to {0, 1}
  - $f \in \operatorname{map}_{a}$ , and  $\tau = (q,a,q'_{0},q'_{1}) \in \Delta_{a}$  such that  $f(\tau) = i$
  - $\circ$  M has a transition (q, (f, a, i), q'\_i)

#### **M** - informally

- The automaton M has to check for each possible move of Player 0 if the outcome is winning for Player 0
- M uses the same acceptance condition as A
  - It will accept if the run on a path is consistent with s and will be accepted by A
- If M won't accept an  $\omega$ -word u it means that player 1 win
  - $\circ$  ~ Since M checked all the options for player 0 and non of them worked

#### Lemma

The tree s is a winning tree for t  $\Leftrightarrow$  L(s,t)  $\cap$  L(M) =  $\emptyset$ 

- Language of L(s,t) all the possible paths that player 1 can choose, while using strategy s
- Language of L(M) all the paths which are good for player 0 and consistent with player 1's strategy

- If  $L(s,t) \cap L(M) = \emptyset$  then all the paths in t which are consistent with s will make player 1 win
  - $\circ$  ~ i.e., s is a winning strategy for player 1  $\,$

#### Why is M usefull?

- The word automaton M accepts all sequences over  $\Sigma$  which satisfy A's acceptance condition
- In order to construct B, we first of all generate a word automaton S such that  $L(S) = \Sigma' \setminus L(M)$
- We'll use Safra's construction (chapter 3)

#### **Building S**

- We can transform M to a Buchi-automaton
- By Safra, we can build deterministic Rabin automaton that accepts L(M)
- The Streett condition is the negation of the Rabin condition
- Finally
  - Word automaton S = (Q', $\Sigma$ ',  $\delta$ ,  $q'_{I'}\Omega$ )
  - $\circ \quad L(S) = \Sigma' \setminus L(M)$

#### **Building B from S**

- B will run S in parallel along each path of an input tree
- The transition relation of B is defined by
- $(q,a,q_0,q_1) \in \Delta' \Leftrightarrow$  there exist transitions in S
  - $\circ \quad \delta(q,(f,a,0)) = q_0$
  - $\circ \quad \delta(q,(f,a,1)) = q_1$

#### **Final Theorem:**

The class of languages recognized by finite-state tree automata is closed under complementation

It remains to be shown that indeed  $T(B) = T^{\omega}_{\Sigma'} \setminus T(A)$ 

#### **Proof - 1'st Direction**

- We assume  $t \in T$  (B)
- There exists an accepting run ρ of B on t
- For each path  $\pi = \pi_1 \pi_2 = \{0,1\}^{\circ}$  the corresponding state sequence satisfies B's acceptance condition
- There are transitions of S
  - $\circ \quad \delta(q, (s(w), t(w), 0)) = q_1$
  - $\circ \quad \delta(q, (s(w), t(w), 1)) = q_2$
- And the corresponding transition of B (q, t(w),  $q_1, q_2$ )
- Player 1 is the winner  $\Rightarrow$  all words  $u \in L(s, t)$  are accepted by S
- Since  $L(S) = \Sigma' \setminus L(M) \Rightarrow L(s, t) \cap L(M) = \emptyset$
- By the previous lemma s is a winning tree for Player 1
- A does not accept t

#### **Proof - 2'st Direction**

- We assume  $t \notin T(A)$
- There exists a winning tree s for tree t of player 1
- $L(s, t) \cap L(M) = \emptyset$
- $L(s,t) \subseteq L(S)$  (since  $L(S) = \Sigma' \setminus L(M)$ )
- For each path π = π<sub>1</sub>π<sub>2</sub> · · · ∈ {0, 1}<sup>∞</sup> there exists a run on the ω-word u = (s(ε), t(ε), π<sub>1</sub>)(s(π1), t(π1), π2) · · · ∈ L(s, t) that satisfies Ω (of automata S)
- By construction of B there exists an accepting run of B on t
  t ∈ T (B)



- 1. From A (tree automaton) we built M (words automaton)
- 2. From M we built S such that  $L(S) = \Sigma' \setminus L(M)$
- 3. From S we built B



#### Outline

- Motivation
- Infinite binary tree
- Finite-State Tree Automata
- Examples
- Buchi tree automata Vs. Muller tree automata
- The Complementation Problem for Automata on Infinite Trees
  - Game theoretical approach
  - Complementation proof

