

# Memory Management

## Chapter 5

### Mooly Sagiv

<http://www.cs.tau.ac.il/~msagiv/courses/wcc12-13.html>

# Topics

- Heap allocation
- Manuel heap allocation
- Automatic memory reallocation (GC)

# Limitations of Stack Frames

- A local variable of P cannot be stored in the activation record of P if its duration exceeds the duration of P

- Example: Dynamic allocation

```
int * f() { return (int *) malloc(sizeof(int));  
}
```

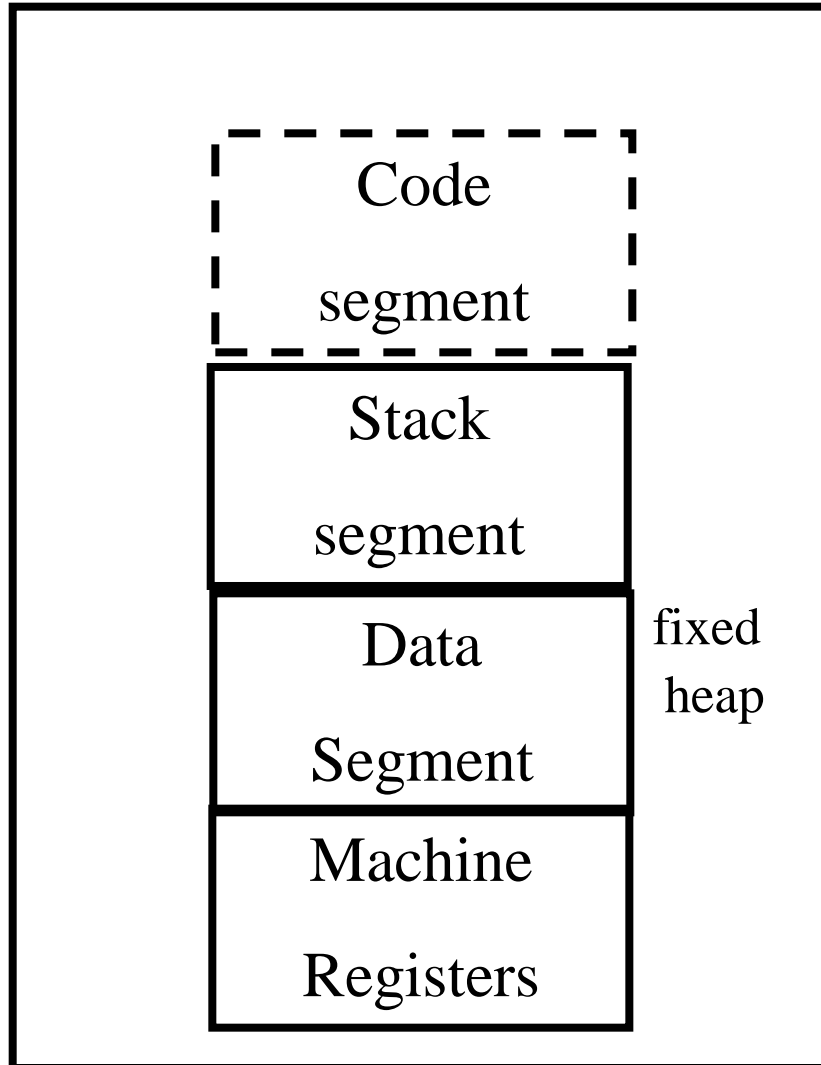
# Currying Functions

```
int (*)(int) f(int x)
{
    int g(int y)
    {
        return x + y;
    }
    return g ;
}
```

```
int (*h)() = f(3);
int (*j)() = f(4);
```

```
int z = h(5);
int w = j(7);
```

# Program Runtime State



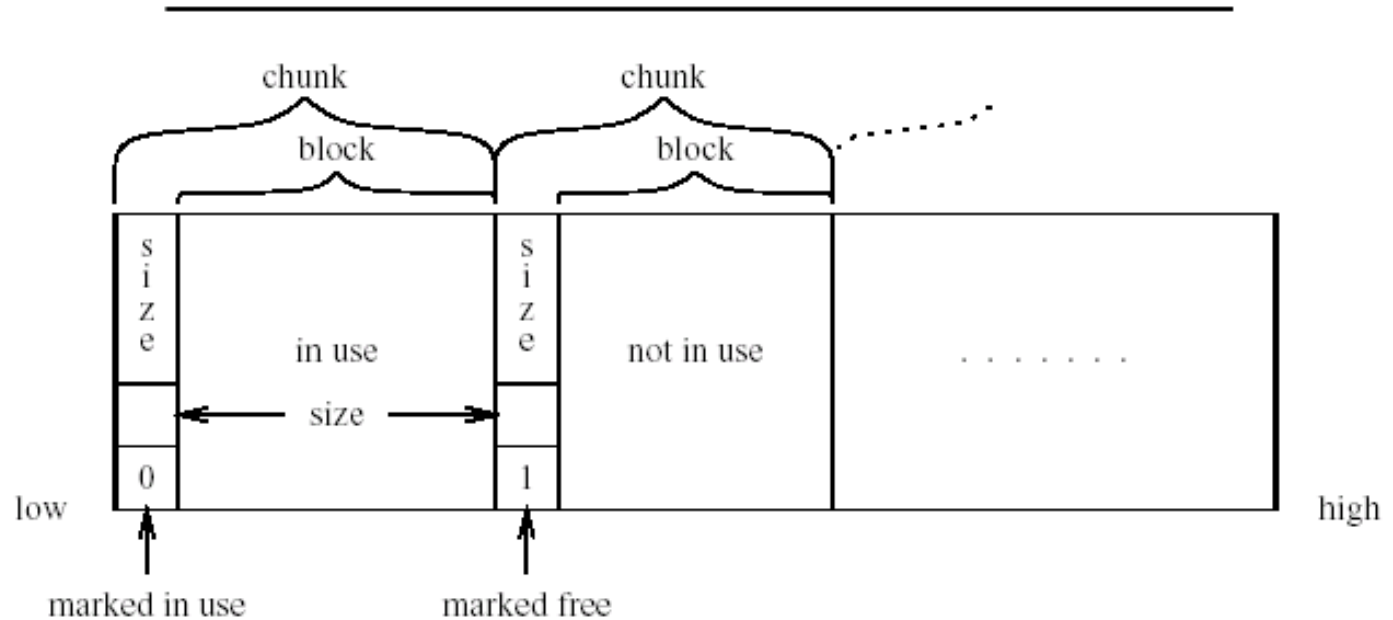
# Data Allocation Methods

- Explicit deallocation
- Automatic deallocation

# Explicit Deallocation

- Pascal, C, C++
- Two basic mechanisms
  - `void * malloc(size_t size)`
  - `void free(void *ptr)`
- Part of the language runtime
- Expensive
- Error prone
- Different implementations

# Memory Structure used by malloc()/free()





# Simple Implementation

---

```
SET the polymorphic chunk pointer First_chunk pointer TO
    Beginning of available memory;
SET the polymorphic chunk pointer One past available memory TO
    Beginning of available memory + Size of available memory;

SET First_chunk pointer .size TO Size of available memory;
SET First_chunk pointer .free TO True;

FUNCTION Malloc (Block size) RETURNING a polymorphic block pointer:
    SET Pointer TO Pointer to free block of size (Block size);
    IF Pointer /= Null pointer: RETURN Pointer;

    Coalesce free chunks;
    SET Pointer TO Pointer to free block of size (Block size);
    IF Pointer /= Null pointer: RETURN Pointer;

    RETURN Solution to out of memory condition (Block size);

PROCEDURE Free (Block pointer):
    SET Chunk pointer TO Block pointer - Administration size;
    SET Chunk pointer .free TO True;
```

call gc

# Next Free Block

---

```
FUNCTION Pointer to free block of size (Block size)
  RETURNING a polymorphic block pointer:
  // Note that this is not a pure function
  SET Chunk pointer TO First_chunk pointer;
  SET Requested chunk size TO Administration size + Block size;

  WHILE Chunk pointer /= One past available memory:
    IF Chunk pointer .free:
      IF Chunk pointer .size - Requested chunk size >= 0:
        // large enough chunk found:
        Split chunk (Chunk pointer, Requested chunk size);
        SET Chunk pointer .free TO False;
        RETURN Chunk pointer + Administration size;
      // try next chunk:
      SET Chunk pointer TO Chunk pointer + Chunk pointer .size;
  RETURN Null pointer;
```

# Splitting Chunks

```
PROCEDURE Split chunk (Chunk pointer, Requested chunk size):  
  SET Left_over size TO Chunk pointer .size - Requested chunk size;  
  IF Left_over size > Administration size:  
    // there is a non-empty left-over chunk  
    SET Chunk pointer .size TO Requested chunk size;  
    SET Left_over chunk pointer TO  
      Chunk pointer + Requested chunk size;  
    SET Left_over chunk pointer .size TO Left_over size;  
    SET Left_over chunk pointer .free TO True;
```

# Coalescing Chunks

```
PROCEDURE Coalesce free chunks:
  SET Chunk pointer TO First_chunk pointer;

  WHILE Chunk pointer /= One past available memory:
    IF Chunk pointer .free:
      Coalesce with all following free chunks (Chunk pointer);
      SET Chunk pointer TO Chunk pointer + Chunk pointer .size;

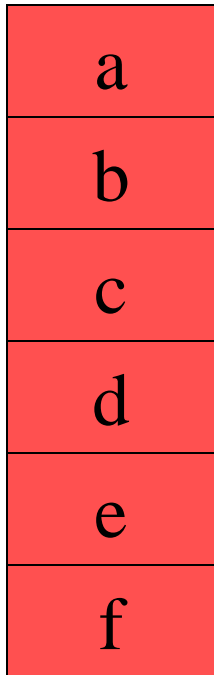
PROCEDURE Coalesce with all following free chunks (Chunk pointer):
  SET Next_chunk pointer TO Chunk pointer + Chunk pointer .size;
  WHILE Next_chunk pointer /= One past available memory
    AND Next_chunk pointer .free:
    // Coalesce them:
    SET Chunk pointer .size TO
      Chunk pointer .size + Next_chunk pointer .size;
    SET Next_chunk pointer TO Chunk pointer + Chunk pointer .size;
```

# Fragmentation

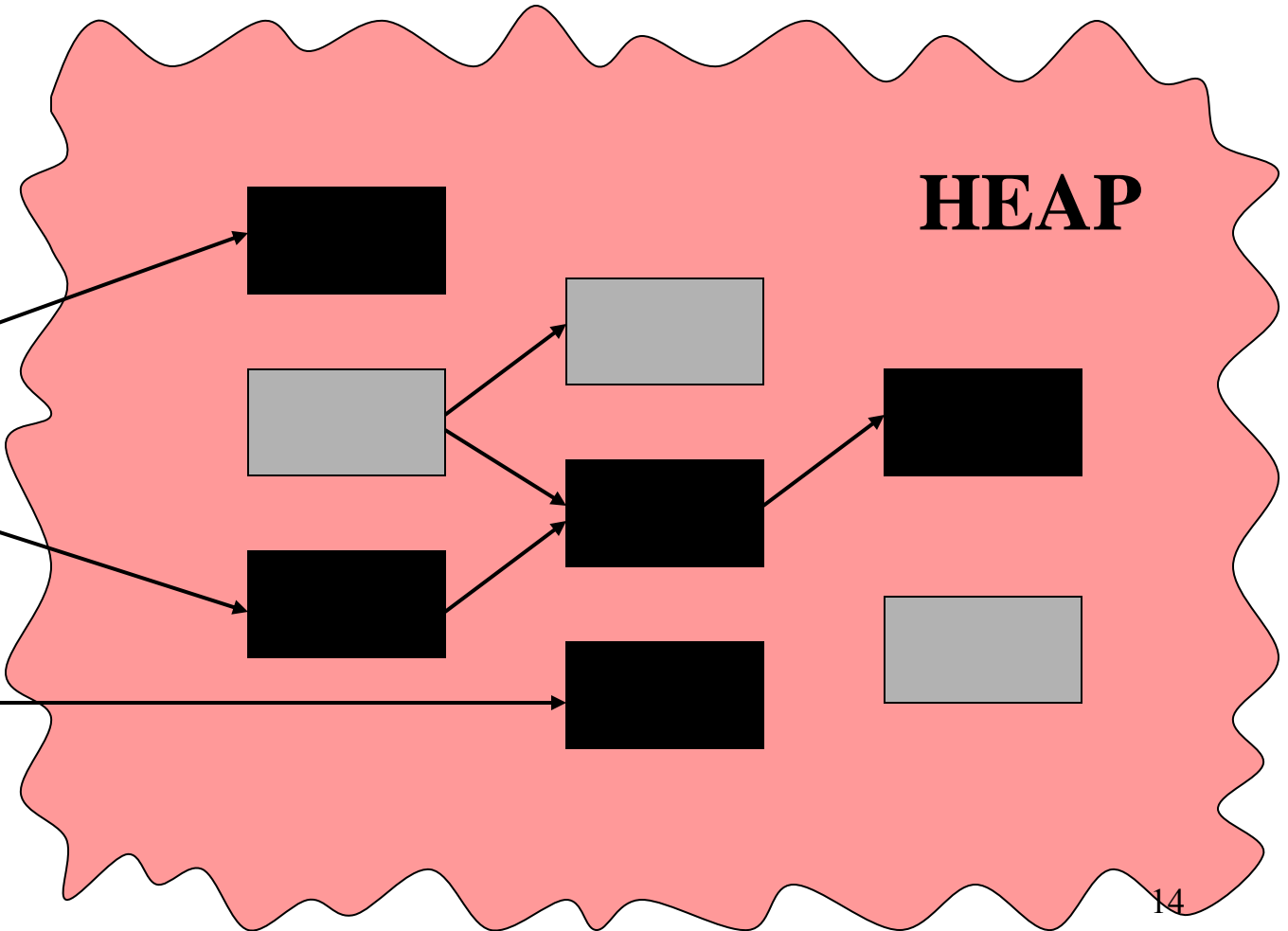
- External
  - Too many small chunks
- Internal
  - A use of too big chunk without splitting the chunk
- Freelist may be implemented as an array of lists

# Garbage Collection

**ROOT SET**

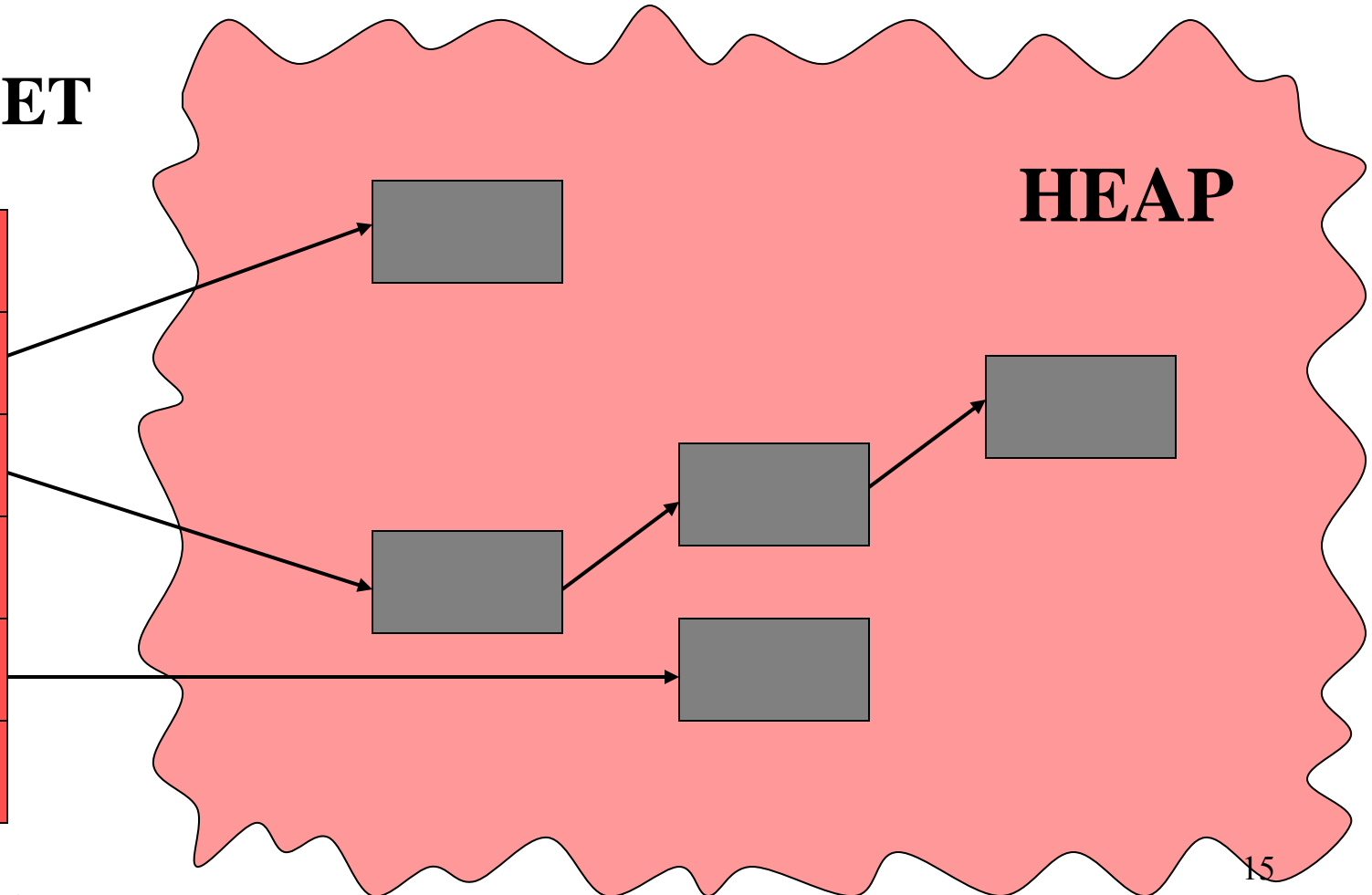
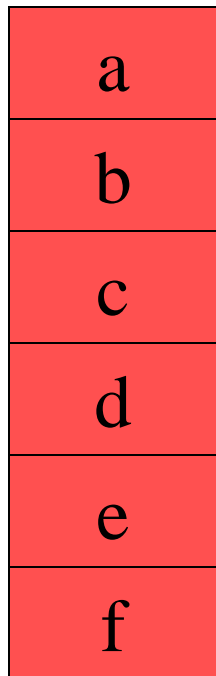


Stack +Registers



# Garbage Collection

**ROOT SET**



Stack +Registers

# What is garbage collection

- The runtime environment reuse chunks that were allocated but are not subsequently used
- garbage chunks
  - not live
- It is undecidable to find the garbage chunks:
  - Decidability of liveness
  - Decidability of type information
- conservative collection
  - every live chunk is identified
  - some garbage runtime chunk are not identified
- Find the reachable chunks via pointer chains
- Often done in the allocation function



```
typedef struct list { struct list *link; int key } *List;
```

```
typedef struct tree { int key;  
                    struct tree *left;  
                    struct tree *right } *Tree;
```

```
foo() { List x = cons(NULL, 7);
```

```
      List y = cons(x, 9);
```

```
      x->link = y;
```

```
    }
```

```
void main() {
```

```
    Tree p, r; int q;
```

```
    foo();
```

```
    p = maketree(); r = p->right;
```

```
    q = r->key;
```

```
    showtree(r); }
```

stack

heap

p

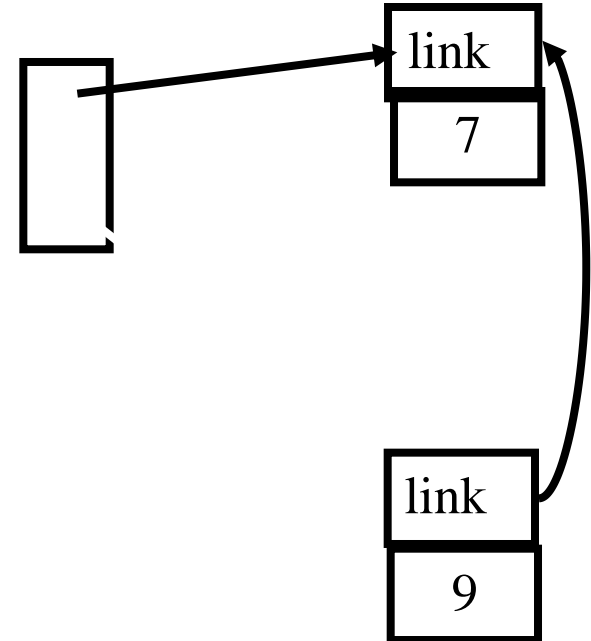
q

r



x

y



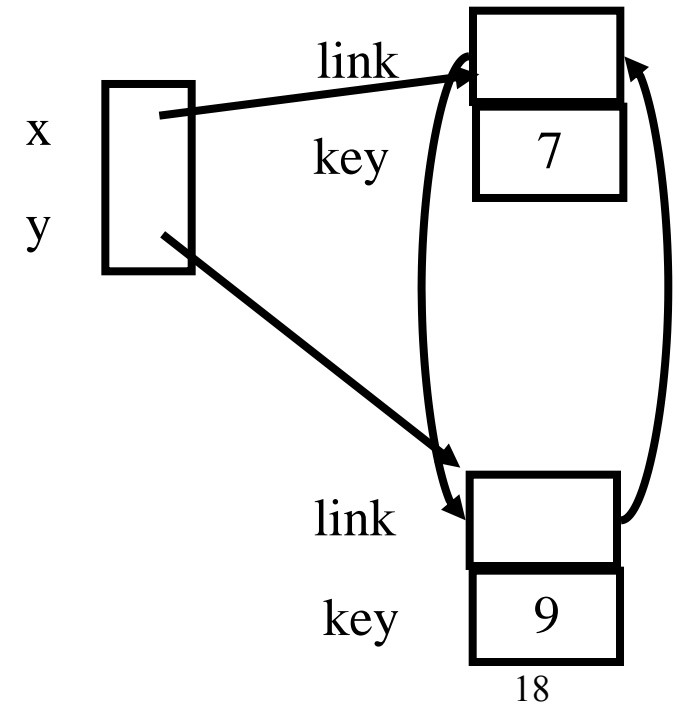
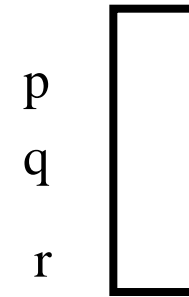
```
typedef struct list { struct list *link; int key } *List;
```

```
typedef struct tree { int key;  
                    struct tree *left;  
                    struct tree *right } *Tree;
```

```
foo() { List x = cons(NULL, 7);  
      List y = cons(x, 9);  
      x->link = y;  
      }
```

```
void main() {  
  Tree p, r; int q;  
  foo();  
  p = maketree(); r = p->right;  
  q = r->key;  
  showtree(r); }
```

stack                      heap



```
typedef struct list { struct list *link; int key } *List;
```

```
typedef struct tree { int key;
```

```
    struct tree *left;
```

```
    struct tree *right } *Tree;
```

```
foo() { List x = create_list(NULL, 7);
```

```
    List y = create_list(x, 9);
```

```
    x->link = y;
```

```
    }
```

```
void main() {
```

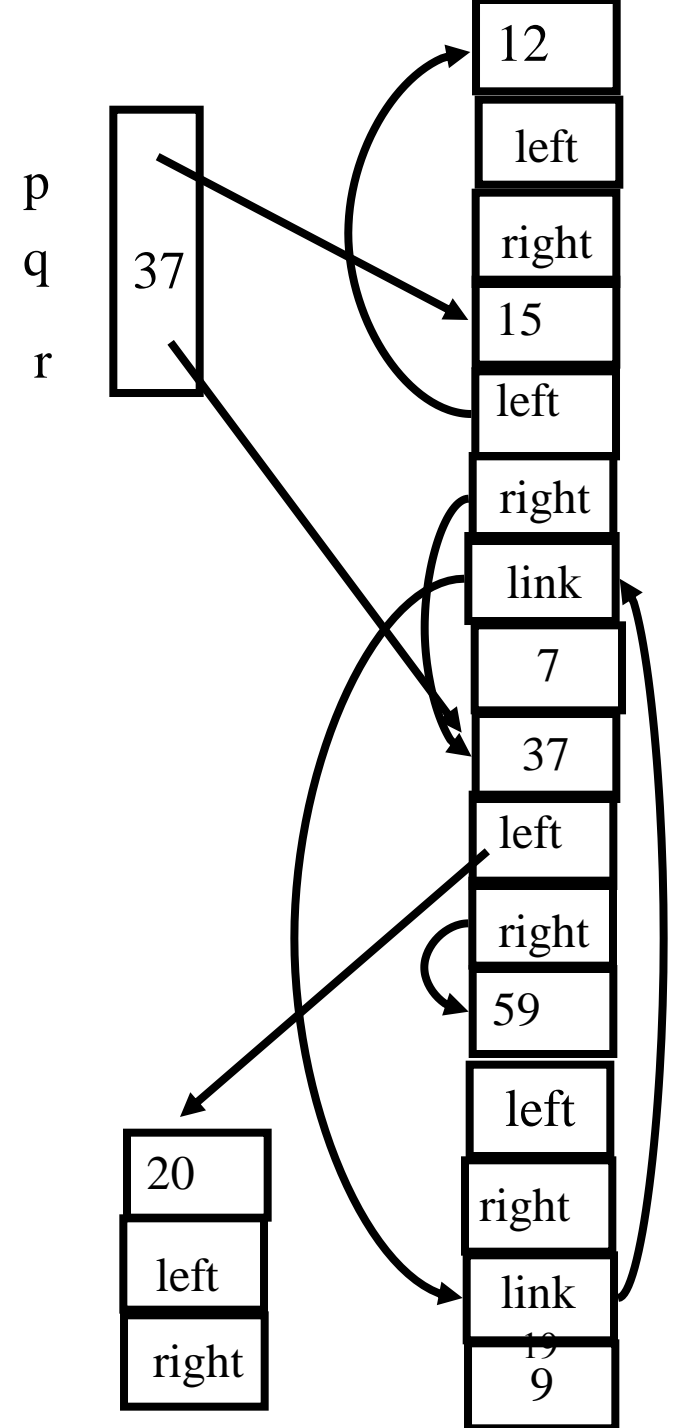
```
    Tree p, r; int q;
```

```
    foo();
```

```
    p = maketree(); r = p->right;
```

```
    q = r->key;
```

```
    showtree(r); }
```



# Outline

- Why is it needed?
  - Why is it taught?
  - Reference Counts
  - Mark-and-Sweep Collection
  - Copying Collection
  - Generational Collection
  - Incremental Collection
  - Interfaces to the Compiler
- } Tracing

# A Pathological C Program

```
a = malloc(...);
```

```
b = a;
```

```
free (a);
```

```
c = malloc (...);
```

```
if (b == c) printf(“unexpected equality”);
```

# Garbage Collection vs. Explicit Memory Deallocation

- Faster program development
- Less error prone
- Can lead to faster programs
  - Can improve locality of references
- Support very general programming styles, e.g. higher order and OO programming
- Standard in ML, Java, C#
- Supported in C and C++ via separate libraries
- May require more space
- Needs a large memory
- Can lead to long pauses
- Can change locality of references
- Effectiveness depends on programming language and style
- Hides documentation
- More trusted code

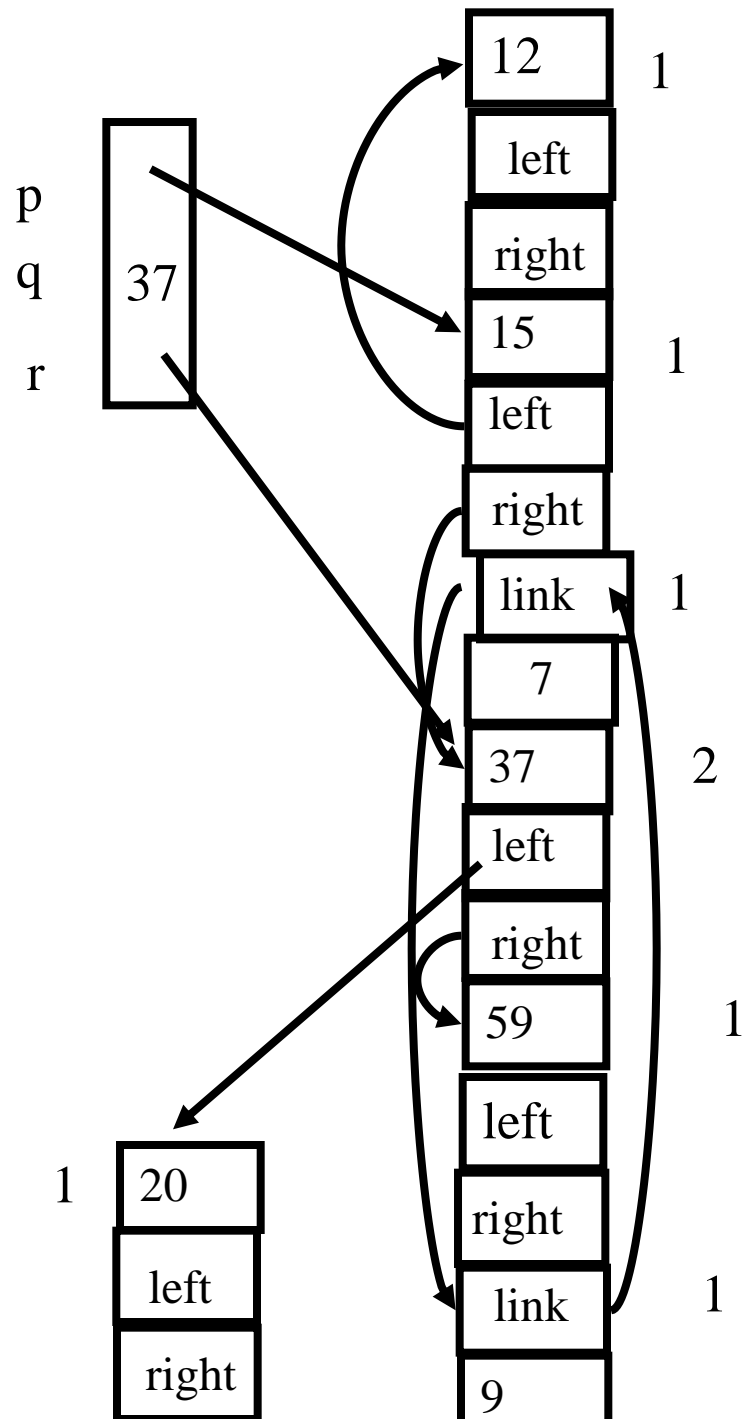
# Interesting Aspects of Garbage Collection

- Data structures
- Non constant time costs
- Amortized algorithms
- Constant factors matter
- Interfaces between compilers and runtime environments
- Interfaces between compilers and virtual memory management

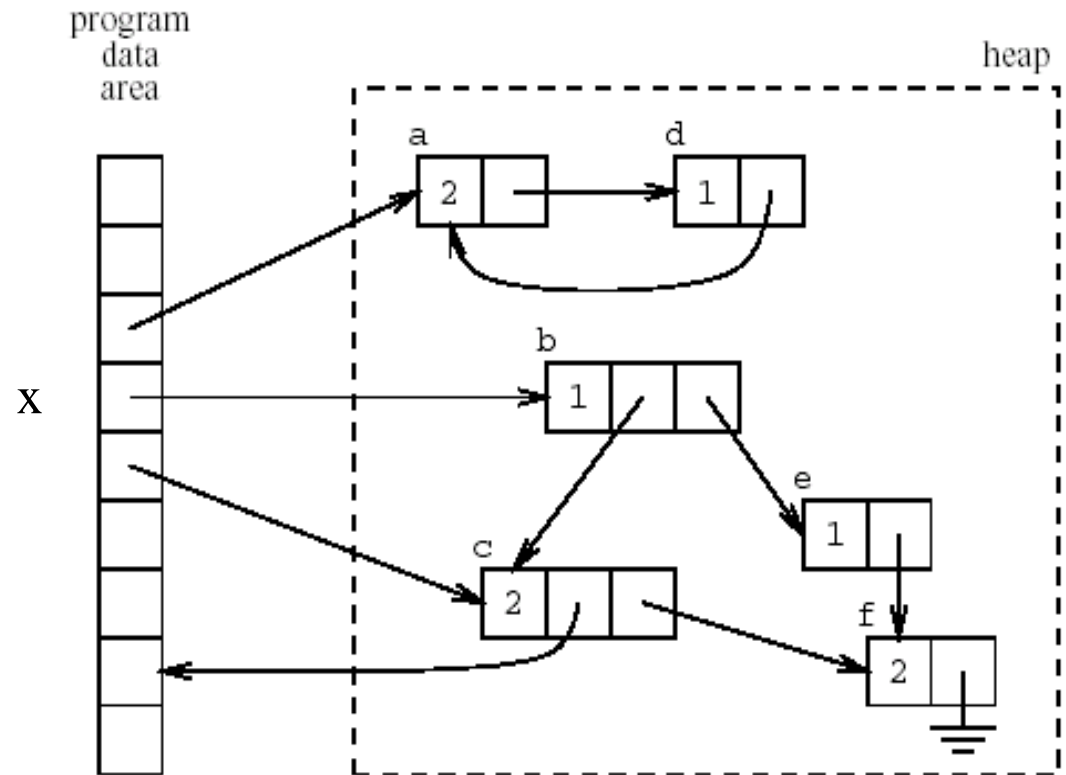
# Reference Counts

- Maintain a counter per chunk
- The compiler generates code to update counter
- Constant overhead per instruction
- Cannot reclaim cyclic elements

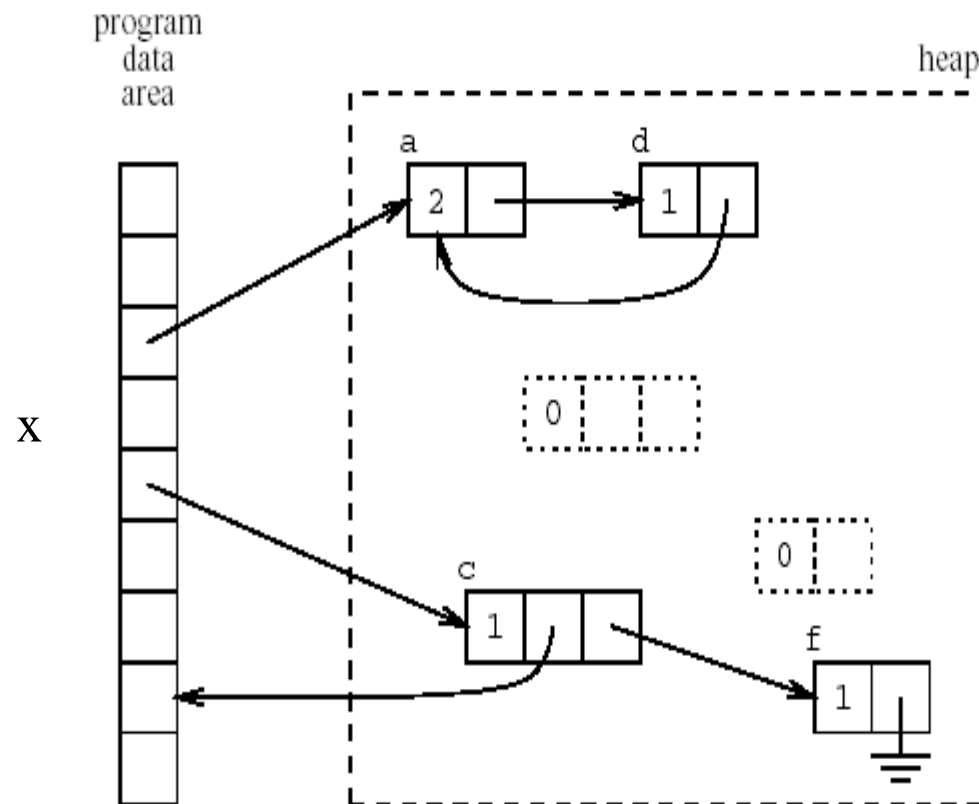




# Another Example



# Another Example ( $x \rightarrow b = \text{NULL}$ )



# Code for $p := q$

---

```
IF Points into the heap (q):  
    Increment q .reference count;  
IF Points into the heap (p):  
    Decrement p .reference count;  
    IF p .reference count = 0:  
        Free recursively depending on reference counts (p);  
SET p TO q;
```

# Recursive Free

```
PROCEDURE Free recursively depending on reference counts(Pointer);
  WHILE Pointer /= No chunk:
    IF NOT Points into the heap (Pointer): RETURN;
    IF NOT Pointer .reference count = 0: RETURN;

    FOR EACH Index IN 1 .. Pointer .number of pointers - 1:
      Free recursively depending on reference counts
        (Pointer .pointer [Index]);

  SET Aux pointer TO Pointer;
  IF Pointer .number of pointers = 0:
    SET Pointer TO No chunk;
  ELSE Pointer .number of pointers > 0:
    SET Pointer TO
      Pointer .pointer [Pointer .number of pointers];
  Free chunk(Aux pointer);    // the actual freeing operation
```

# Lazy Reference Counters

- Free one element
- Free more elements when required
- Constant time overhead
- But may require more space

# Reference Counts (Summary)

- Fixed but big constant overhead
- Fragmentation
- Cyclic Data Structures
- Compiler optimizations can help
- Can delay updating reference counters from the stack
- Implemented in libraries and file systems
  - No language support
- But not currently popular
- Will it be popular for large heaps?

# Mark-and-Sweep(Scan) Collection

- **Mark** the chunks reachable from the roots (stack, static variables and machine registers)
- **Sweep** the heap space by moving unreachable chunks to the freelist (Scan)



# The Mark Phase

for each root  $v$

DFS( $v$ )

function DFS( $x$ )

if  $x$  is a pointer and chunk  $x$  is not marked

mark  $x$

for each reference field  $f_i$  of chunk  $x$

DFS( $x.f_i$ )

# The Sweep Phase

$p :=$  first address in heap

while  $p <$  last address in the heap

    if chunk  $p$  is marked

        unmark  $p$

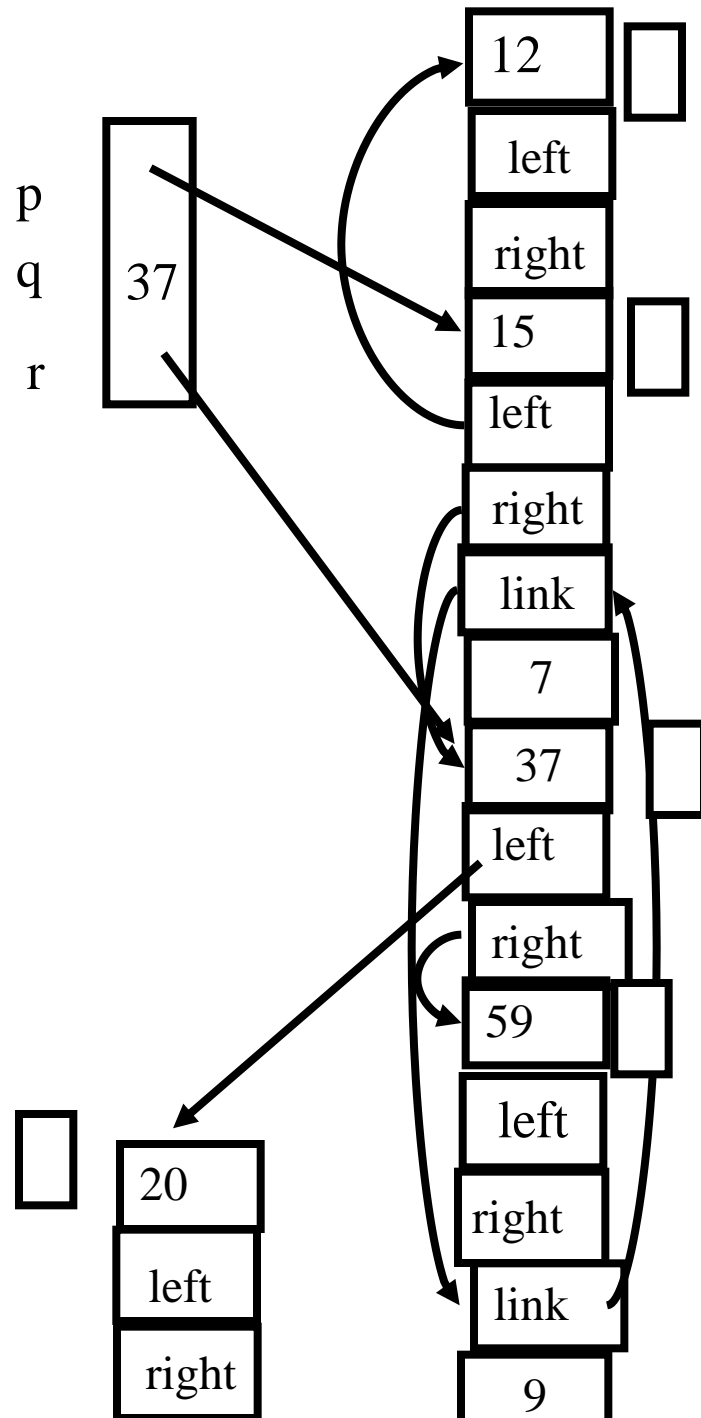
    else let  $f_1$  be the first pointer reference field in  $p$

$p.f_1 :=$  freelist

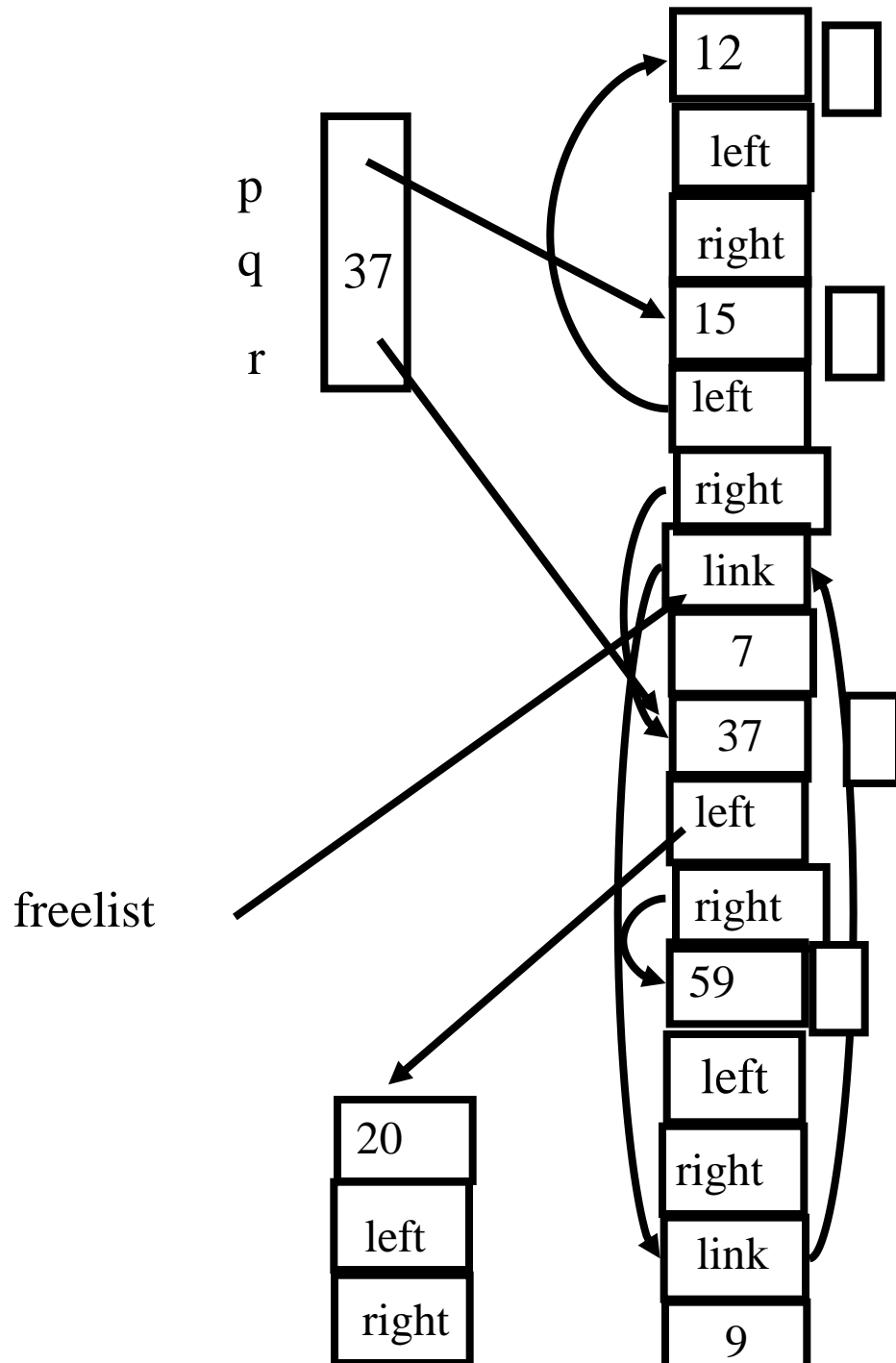
        freelist  $:= p$

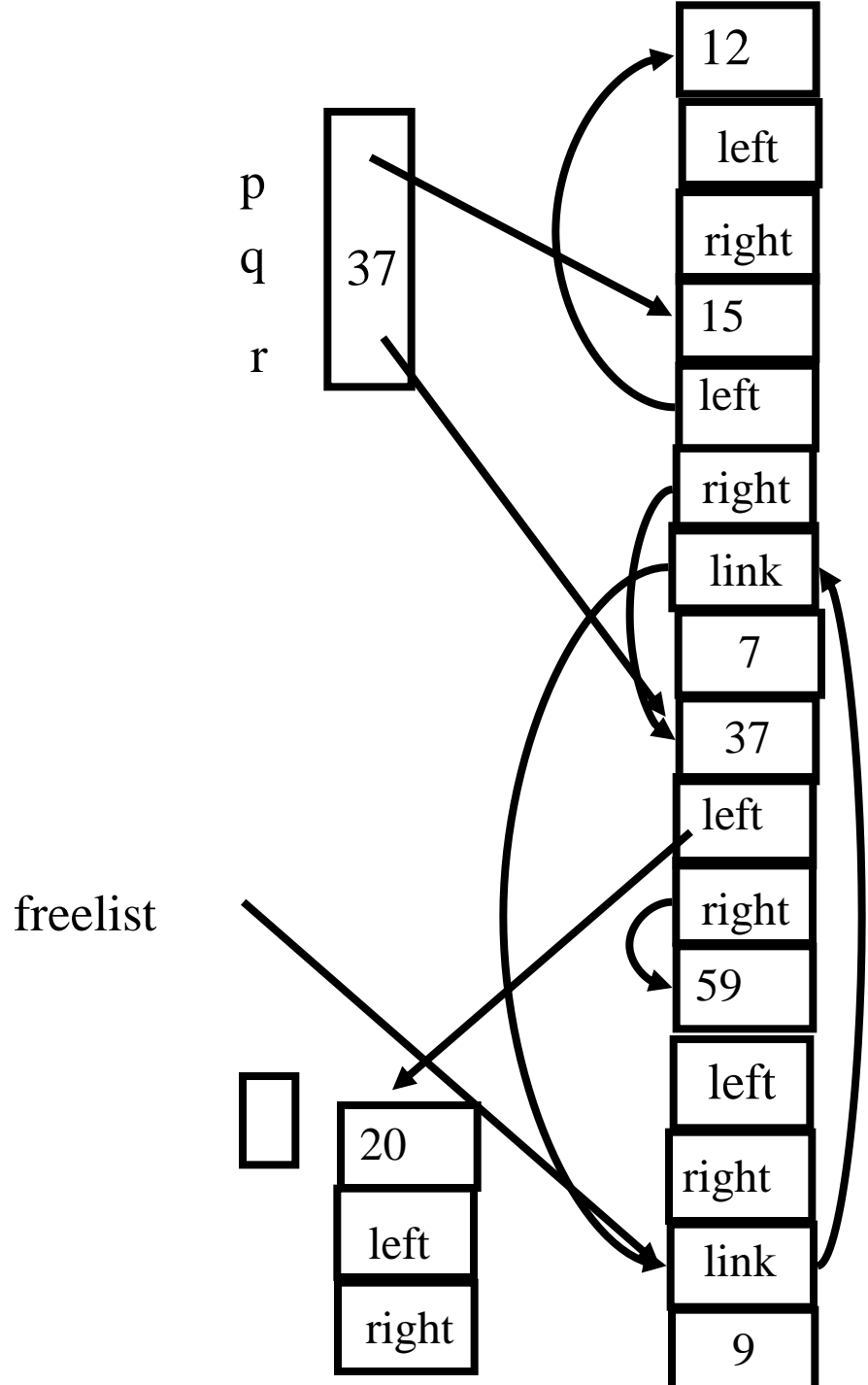
$p := p +$  size of chunk  $p$

Mark



Sweep





# Cost of GC

- The cost of a single garbage collection can be linear in the size of the store
  - may cause quadratic program slowdown
- Amortized cost
  - collection-time/storage reclaimed
  - Cost of one garbage collection
    - $c_1 R + c_2 H$
  - $H - R$  Reclaimed chunks
  - Cost per reclaimed chunk
    - $(c_1 R + c_2 H) / (H - R)$
  - If  $R/H > 0.5$ 
    - increase  $H$
  - if  $R/H < 0.5$ 
    - cost per reclaimed word is  $c_1 + 2c_2 \sim 16$
  - There is no lower bound

# The Mark Phase

for each root  $v$

DFS( $v$ )

function DFS( $x$ )

if  $x$  is a pointer and chunk  $x$  is not marked

mark  $x$

for each reference field  $f_i$  of chunk  $x$

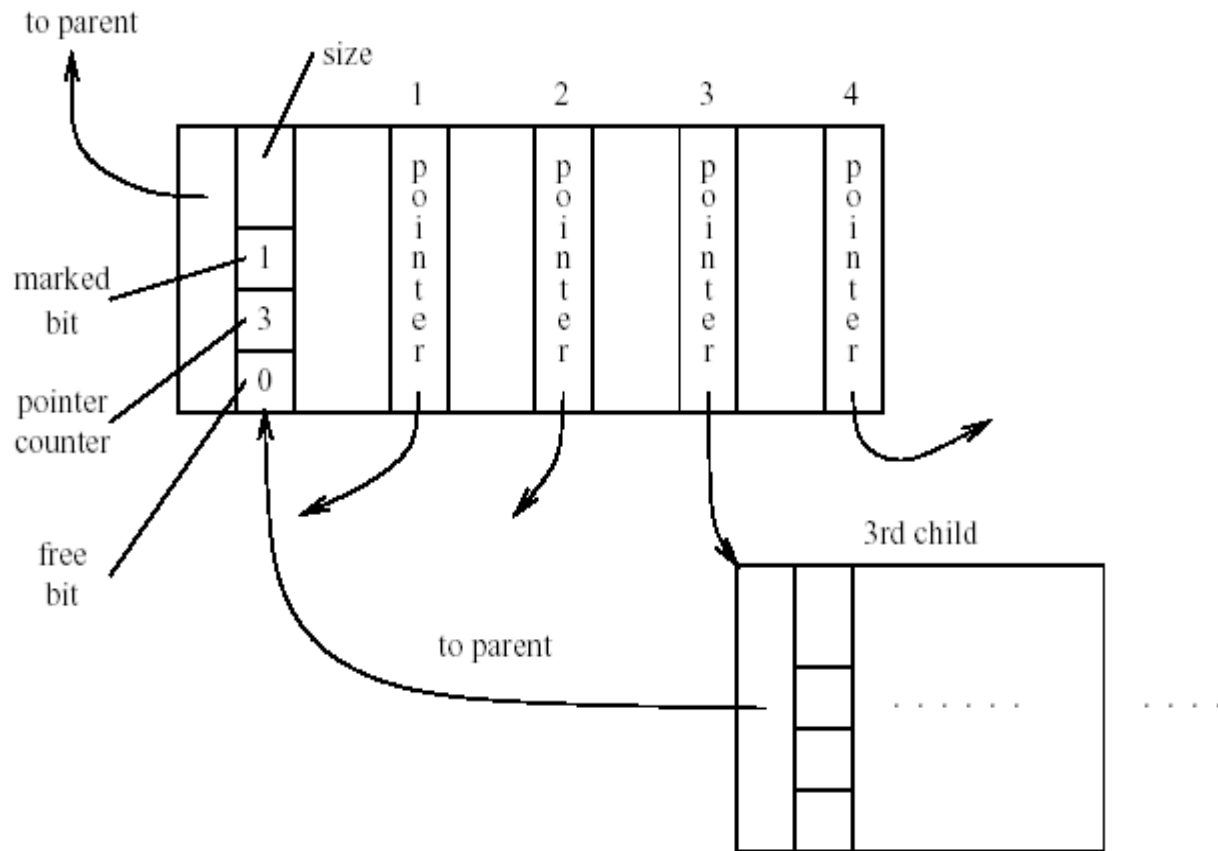
DFS( $x.f_i$ )

# Efficient implementation of Mark(DFS)

- Explicit stack
- Parent pointers
- Pointer reversal
- Other data structures



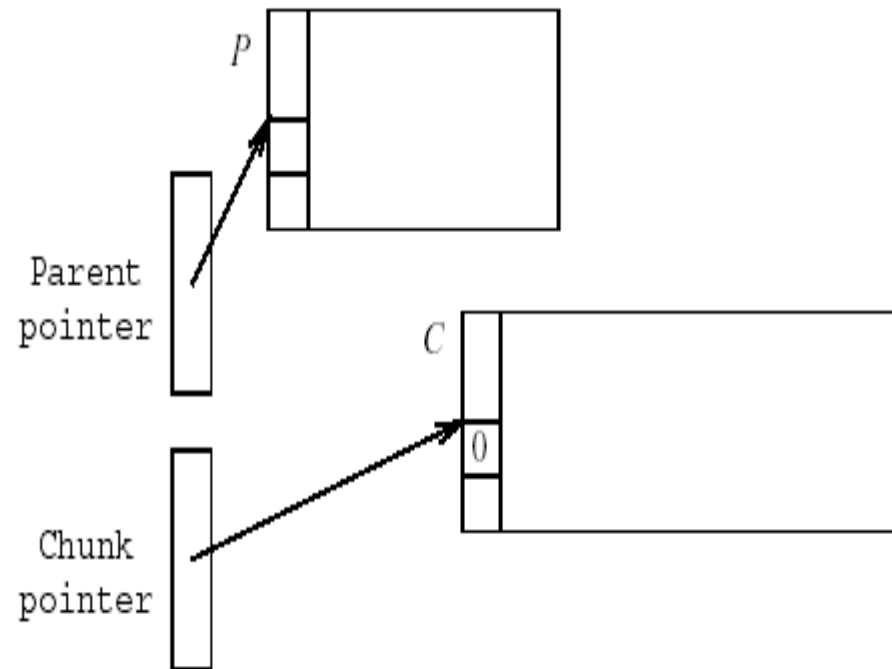
# Adding Parent Pointer



# Avoiding Parent Pointers (Deutch-Schorr-Waite)

- Depth first search can be implemented without recursion or stack
- Maintain a counter of visited children
- Observation:
  - The pointer link from a parent to a child is not needed when it is visited
  - Temporary store pointer to the parent (instead of the field)
  - Restore when the visit of child is finished

# Arriving at C



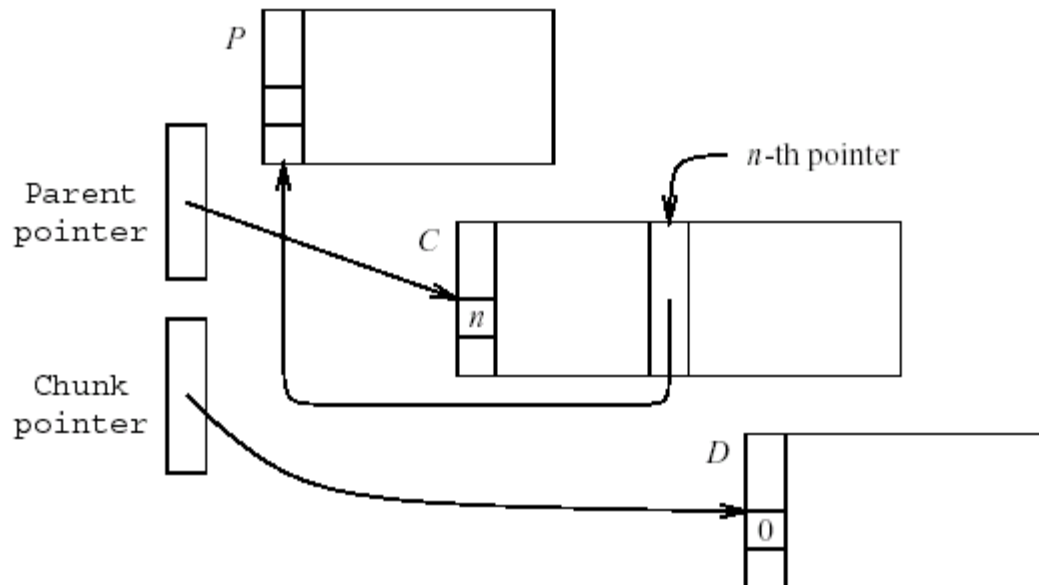
# Visiting n-pointer field D

SET old parent pointer TO parent pointer ;

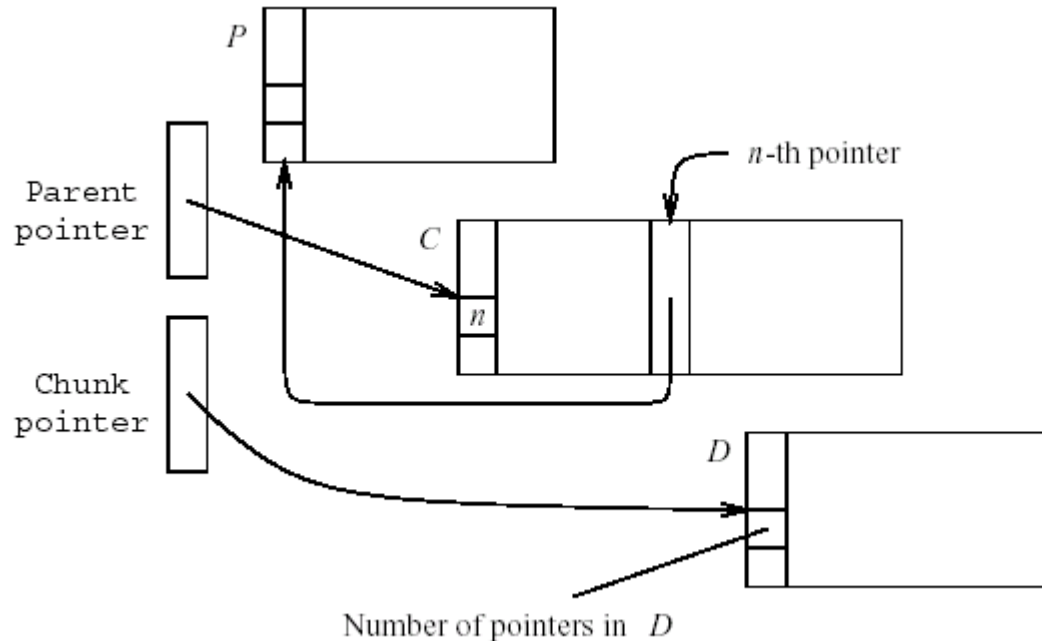
SET Parent pointer TO chunk pointer ;

SET Chunk pointer TO n-th pointer field of C;

SET n-th pointer field in C TO old parent pointer;



# About to return from D



SET old parent pointer TO Parent pointer ;

SET Parent pointer TO n-th pointer field of C ;

SET n-th pointer field of C TO chunk pointer;

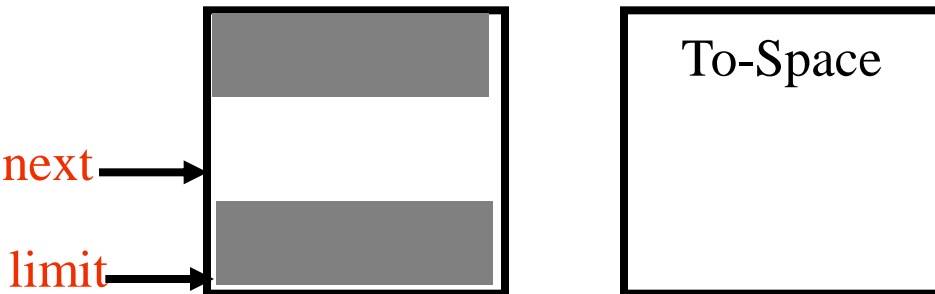
SET chunk pointer TO old parent pointer;

# Compaction

- The sweep phase can compact adjacent chunks
- Reduce fragmentation

# Copying Collection

- Maintains two separate heaps
  - from-space
  - to-space
- pointer **next** to the next free chunk in from-space
- A pointer **limit** to the last chunk in from-space
- If **next** = **limit** copy the reachable chunks from from-space into to-space
  - set **next** and **limit**
  - Switch from-space and to-space
- Requires type information



# Breadth-first Copying Garbage Collection

next := beginning of to-space

scan := next

for each root r

    r := Forward(r)

while scan < next

    for each reference field  $f_i$  of chunk at scan

        scan. $f_i$  := Forward(scan. $f_i$ )

    scan := scan + size of chunk at scan



# The Forwarding Procedure

function Forward(p)

  if p points to from-space

    then if  $p.f_1$  points to to-space

      return  $p.f_1$

    else for each reference field  $f_i$  of p

$next.f_i := p.f_i$

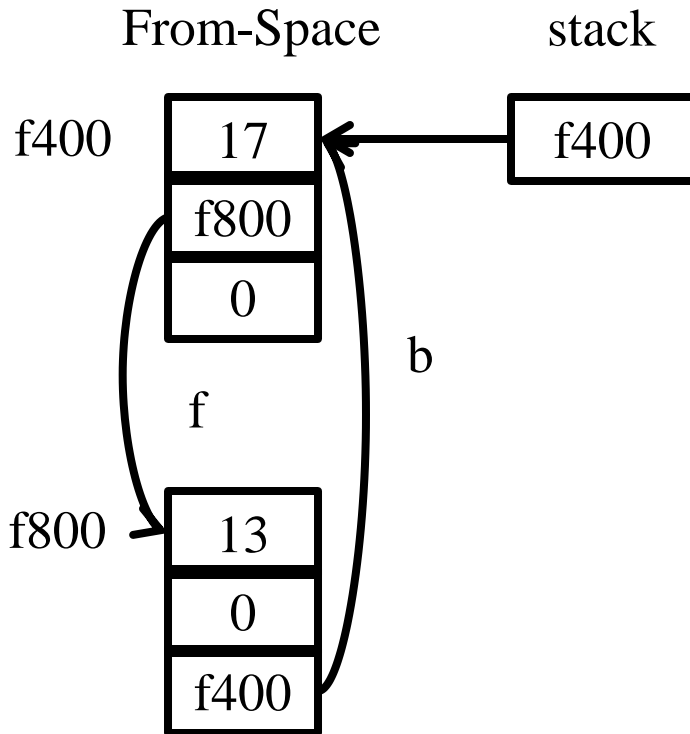
$p.f_1 := next$

$next := next$  size of chunk p

      return  $p.f_1$

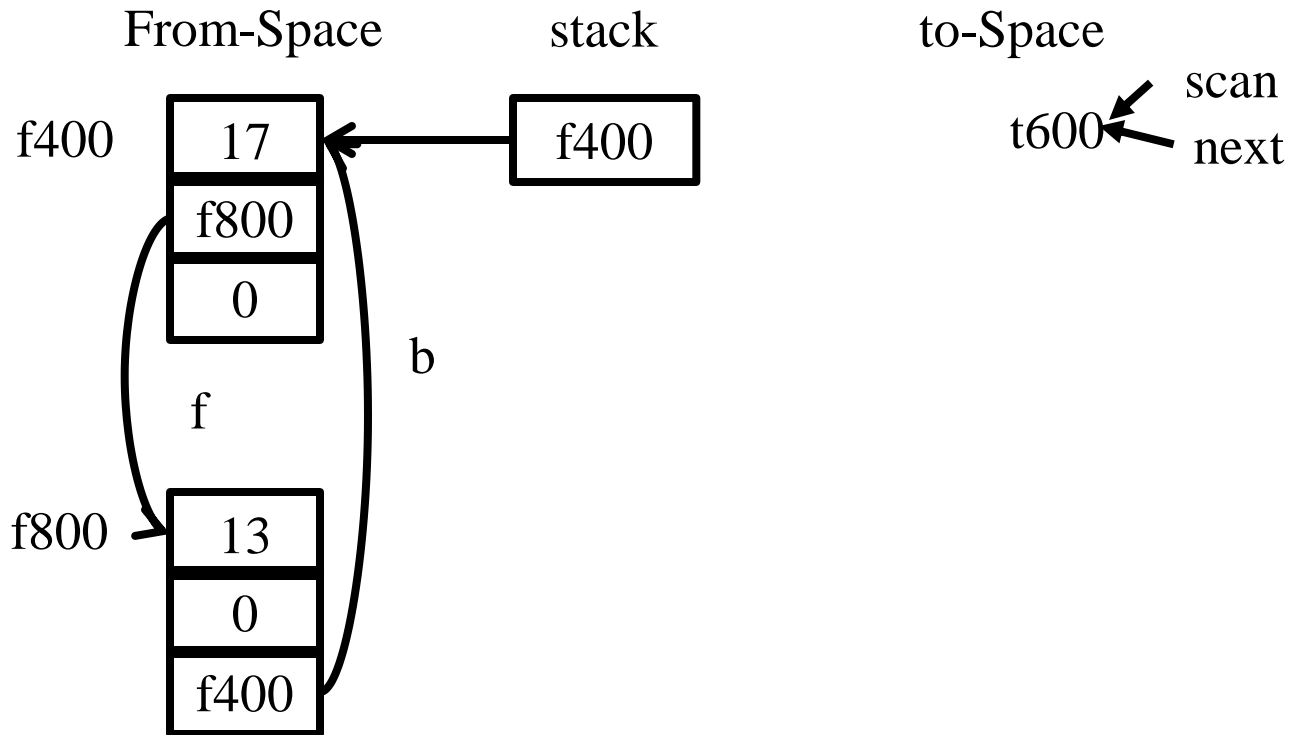
  else return p

# A Simple Example

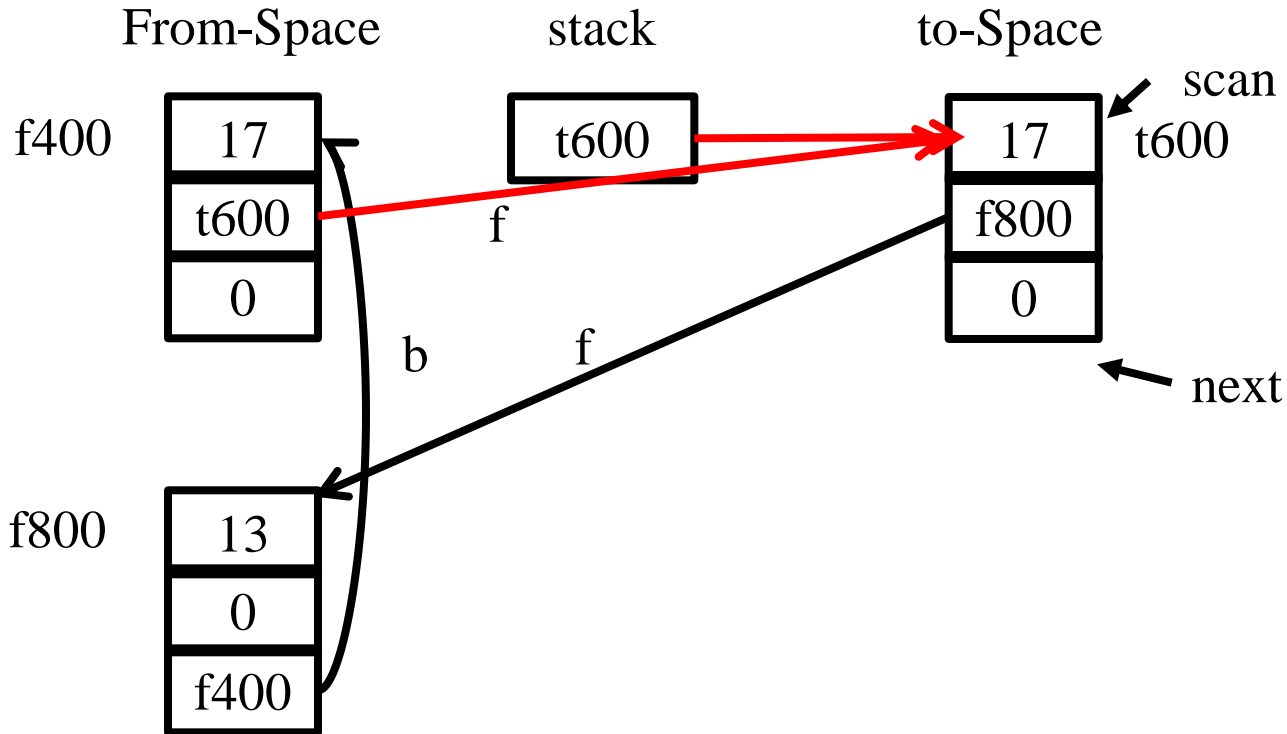


```
struct DL{  
    int data;  
    struct DL* f;  
    struct DL *b  
}
```

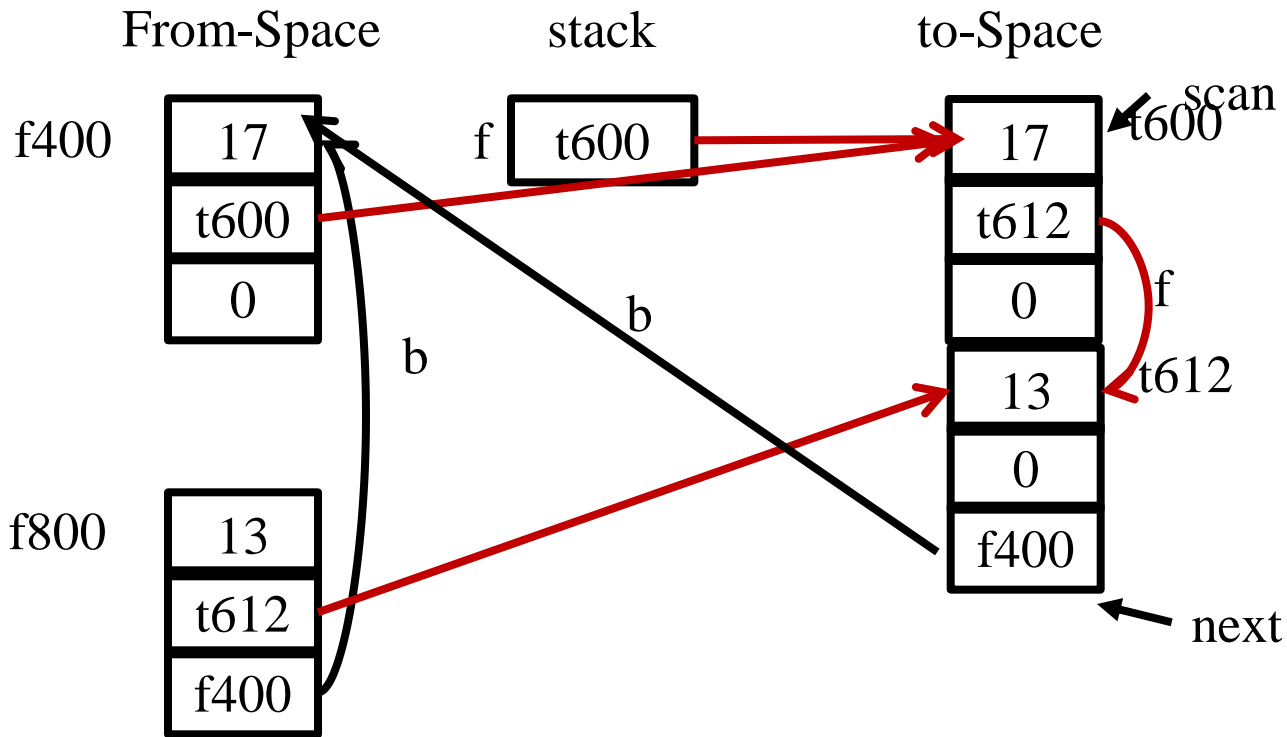
# Before Forward(f400)



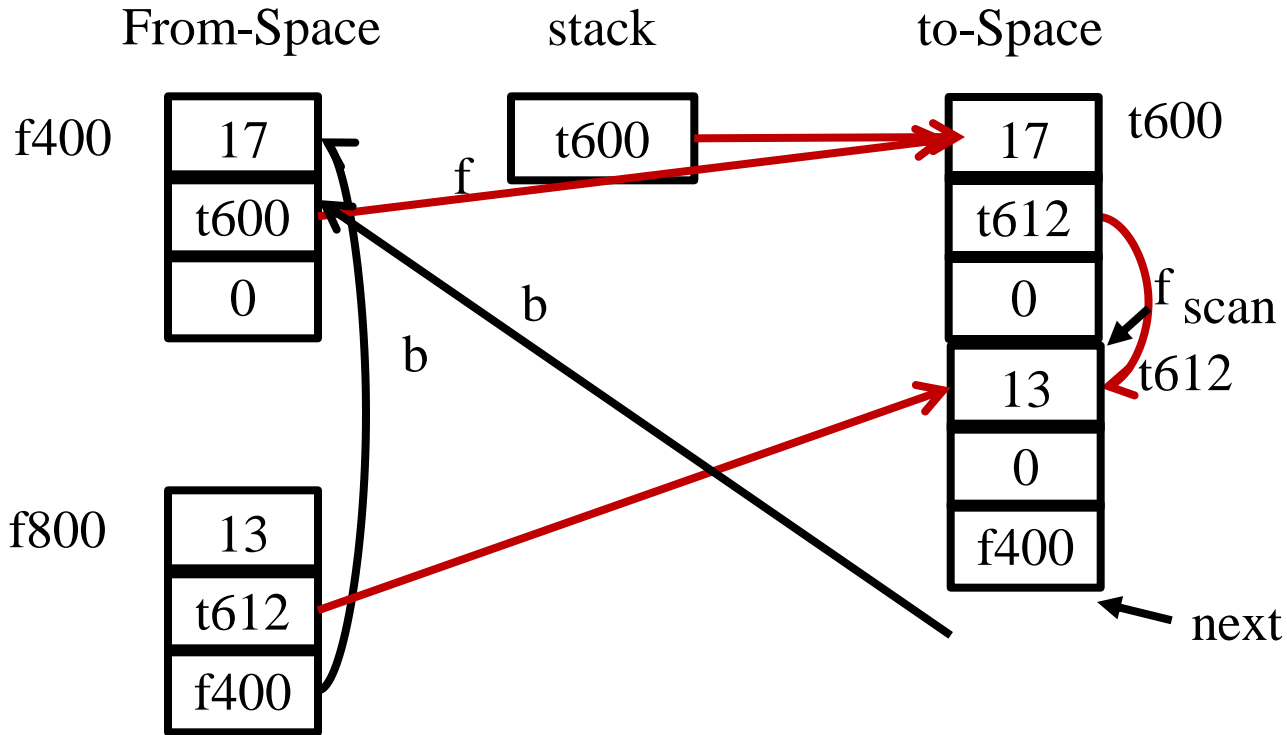
# After Forward(f400) before Forward(f800)



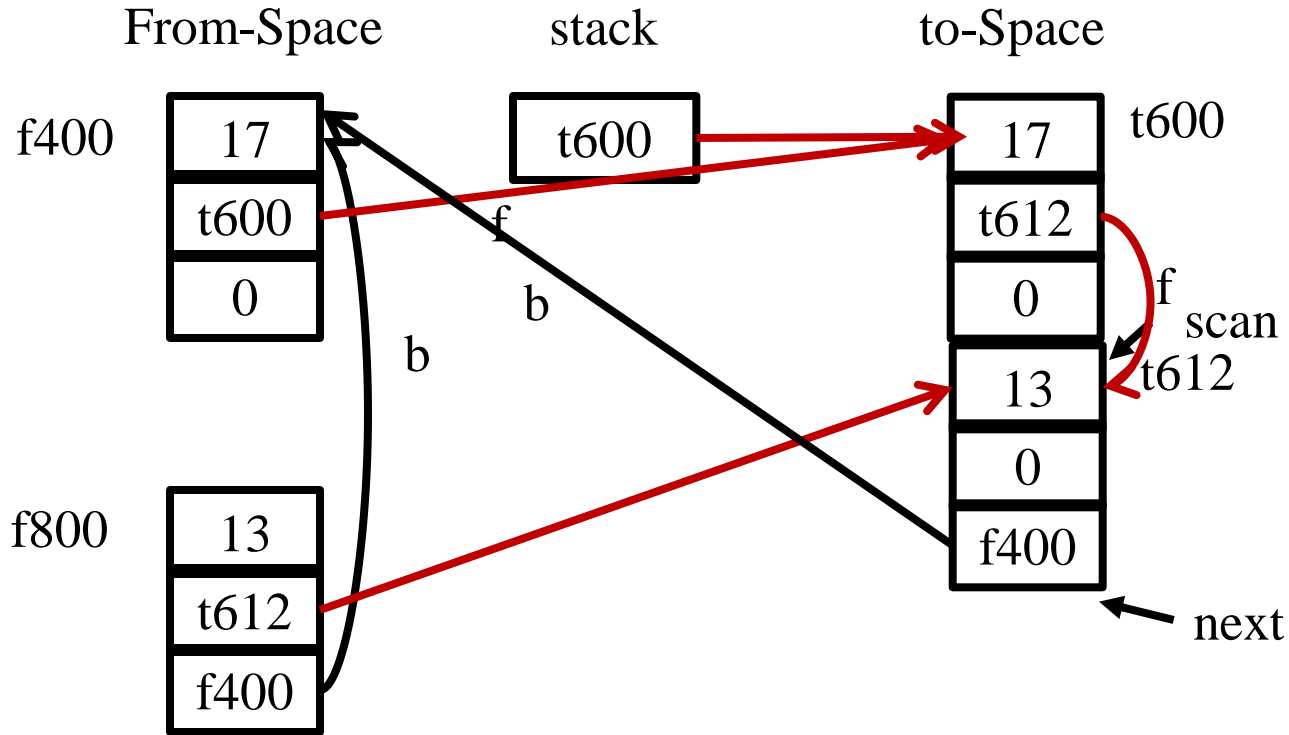
# After Forward(f800) Before Forward(0)



# After Forward(0) Before Forward(0)

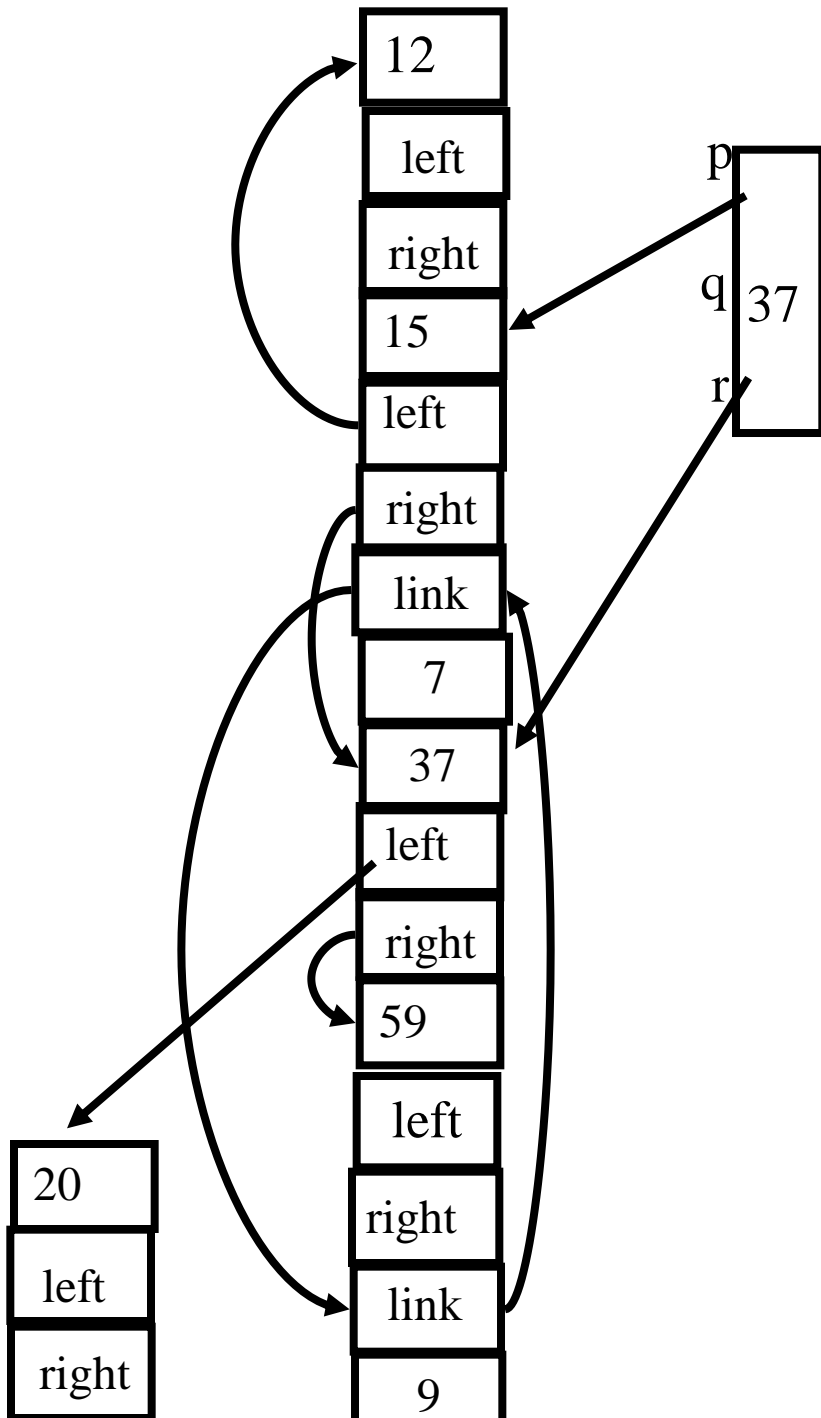


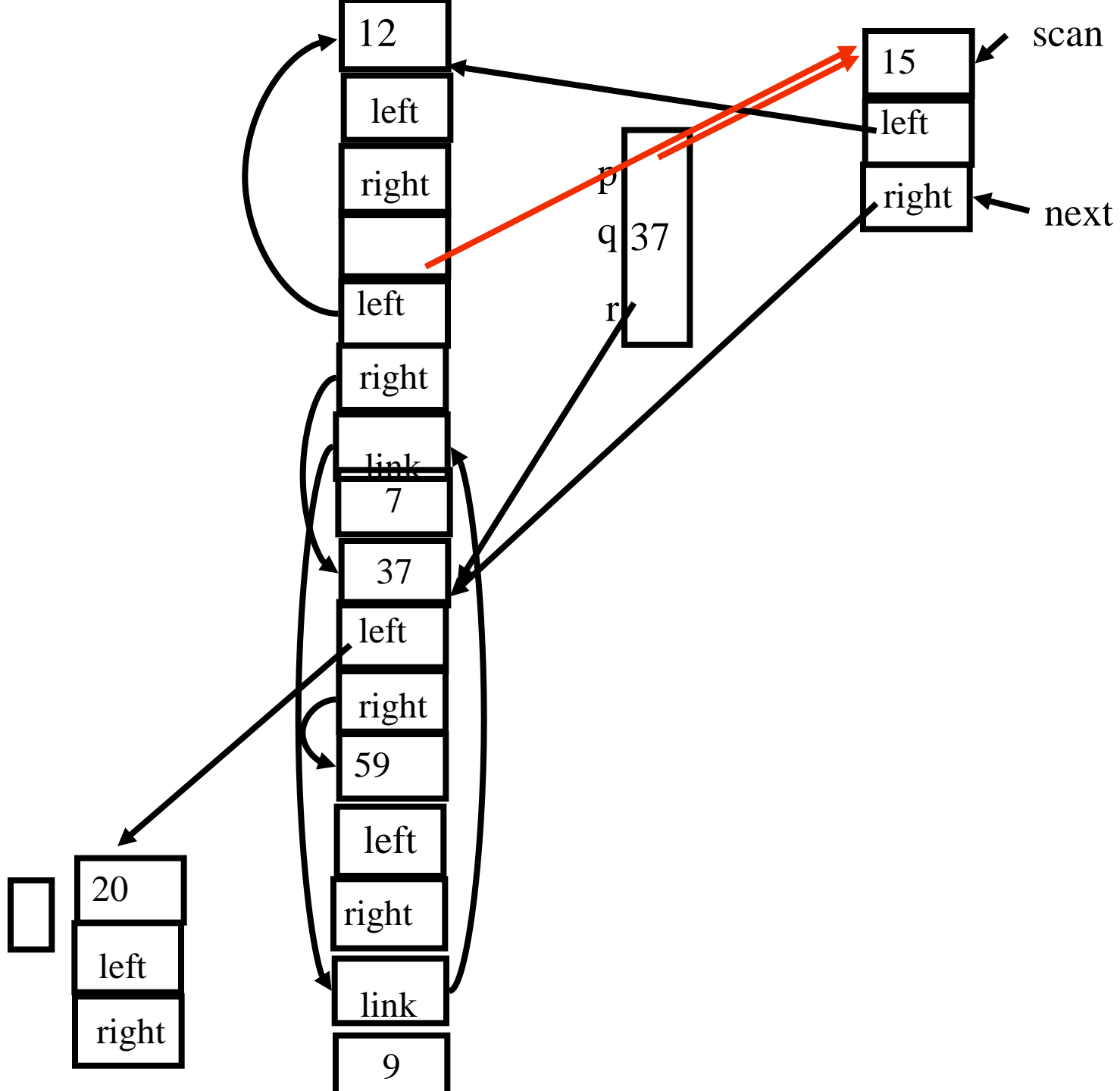
# After Forward(0) Before Forward(f400)

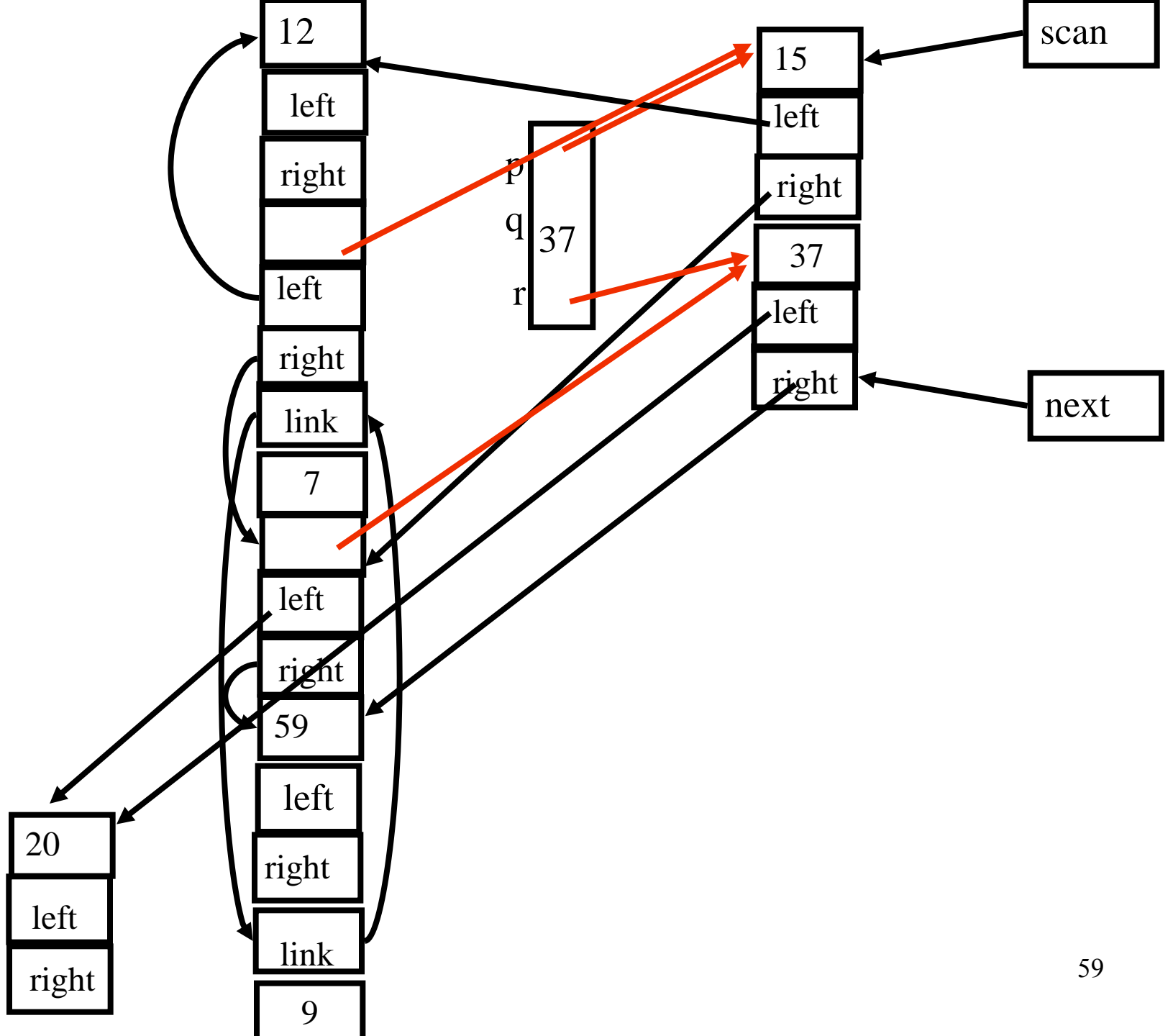
















# Amortized Cost of Copy Collection

$$c_3R / (H/2 - R)$$

# Locality of references

- Copy collection does not create fragmentation
- Cheney's algorithm may lead to subfields that point to far away chunks
  - poor virtual memory and cache performance
- DFS normally yields better locality but is harder to implement
- DFS may also be bad for locality for chunks with more than one pointer fields
- A compromise is a hybrid breadth first search with two levels down (Semi-depth first forwarding)
- Results can be improved using dynamic information

# The New Forwarding Procedure

```
function Forward(p)
    if p points to from-space
        then if p.f1 points to to-space
            return p.f1
        else Chase(p); return p.f1
    else return p

function Chase(p)
    repeat
        q := next
        next := next + size of chunk p
        r := null
        for each reference field fi of p
            q.fi := p.fi
            if q.fi points to from-space and
                q.fi.f1 does not point to to-space
                then r := q.fi
            p.f1 := q
            p := r
    until p = null
```



# Generational Garbage Collection

- Newly created objects contain higher percentage of garbage
- Partition the heap into generations  $G_1$  and  $G_2$
- First garbage collect the  $G_1$  heap
  - chunks which are reachable
- After two or three collections chunks are promoted to  $G_2$
- Once a while garbage collect  $G_2$
- Can be generalized to more than two heaps
- But how can we garbage collect in  $G_1$ ?

# Scanning roots from older generations

- **remembered list**

- The compiler generates code after each destructive update  $b.f_i := a$  to put  $b$  into a vector of updated objects scanned by the garbage collector

- **remembered set**

- remembered-list + “set-bit”

- **Card marking**

- Divide the memory into  $2^k$  cards

- **Page marking**

- $k =$  page size
- virtual memory system catches updates to old-generations using the dirty-bit

# Incremental Collection

- Even the most efficient garbage collection can interrupt the program for quite a while
- Under certain conditions the collector can run concurrently with the program (mutator)
- Need to guarantee that mutator leaves the chunks in consistent state, e.g., may need to restart collection
- Two solutions
  - compile-time
    - Generate extra instructions at store/load
  - virtual-memory
    - Mark certain pages as read(write)-only
    - a write into (read from) this page by the program restart mutator

# Tricolor marking

- Generalized GC
- Three kinds of chunks
  - White
    - Not visited (not marked or not copied)
  - Grey
    - Marked or copied but children have not been examined
  - Black
    - Marked and their children are marked

# Basic Tricolor marking

while there are any grey objects

    select a grey chunk  $p$

    for each reference field  $f_i$  of  
chunk  $p$

        if chunk  $p.f_i$  is white

            color chunk  $p.f_i$  grey

    color chunk  $p$  black

Invariants

- No black points to white
- Every grey is on the collector's (stack or queue) data structure

# Establishing the invariants

- Dijkstra, Lamport, et al
  - Mutator stores a white pointer **a** into a black pointer **b**
    - color **a** grey (compile-time)
- Steele
  - Mutator stores a white pointer **a** into a black pointer **b**
    - color **b** grey (compile-time)
- Boehm, Demers, Shenker
  - All black pages are marked read-only
  - A store into black page mark all the objects in this page grey (virtual memory system)
- Baker
  - Whenever the mutator fetches a pointer **b** to a grey or white object
    - color **b** grey (compile-time)
- Appel, Ellis, Li
  - Whenever the mutator fetches a pointer **b** from a page containing a non black object
    - color every object on this page black and children grey (virtual memory system)

# Interfaces to the Compiler

- The semantic analysis identifies chunk fields which are pointers and their size
- Generate runtime descriptors at the beginning of the chunks
  - Can employ different allocation/deallocation functions
- Pass the descriptors to the allocation function
- The compiler also passes pointer-map
  - the set of live pointer locals, temporaries, and registers
- Recorded at ?-time for every procedure

# Summary

- Garbage collection is an effective technique
- Leads to more secure programs
- Tolerable cost
- But is not used in certain applications
  - Realtime
- Generational garbage collection works fast
  - Emulates stack
- But high synchronization costs
- Compiler can allocate data on stack sometimes
  - Escape analysis
- May be improved