

Programming Language Semantics

Denotational Semantics

Chapter 5

Based on a lecture by

Martin Abadi

Introduction

- Denotational semantics is supposed to be mathematical:
 - The meaning of an expression is a mathematical object
 - A fair amount of mathematics is involved
- Denotational semantics is compositional
- Denotational semantics is more abstract and canonical than operational semantics
 - No small step vs. big step
- Denotational semantics is also called
 - Fixed point semantics
 - Mathematical semantics
 - Scott-Strachey semantics

Plan

- Definition of the denotational semantics of IMP (first attempt)
- Complete partial orders and related properties
 - Monotonicity
 - Continuity
- Definition of denotational semantics of IMP

Denotational semantics

- **A**: $Aexp \rightarrow (\Sigma \rightarrow \mathbf{N})$
- **B**: $Bexp \rightarrow (\Sigma \rightarrow \mathbf{T})$
- **C**: $Com \rightarrow (\Sigma \rightarrow \Sigma)$
- Defined by structural induction

Denotational semantics of Aexp

- $\mathbf{A}: \text{Aexp} \rightarrow (\Sigma \rightarrow \mathbf{N})$
- $\mathbf{A} \llbracket n \rrbracket = \{(\sigma, n) \mid \sigma \in \Sigma\}$
- $\mathbf{A} \llbracket X \rrbracket = \{(\sigma, \sigma(X)) \mid \sigma \in \Sigma\}$
- $\mathbf{A} \llbracket a_0 + a_1 \rrbracket = \{(\sigma, n_0 + n_1) \mid (\sigma, n_0) \in \mathbf{A} \llbracket a_0 \rrbracket, (\sigma, n_1) \in \mathbf{A} \llbracket a_1 \rrbracket\}$
- $\mathbf{A} \llbracket a_0 - a_1 \rrbracket = \{(\sigma, n_0 - n_1) \mid (\sigma, n_0) \in \mathbf{A} \llbracket a_0 \rrbracket, (\sigma, n_1) \in \mathbf{A} \llbracket a_1 \rrbracket\}$
- $\mathbf{A} \llbracket a_0 \times a_1 \rrbracket = \{(\sigma, n_0 \times n_1) \mid (\sigma, n_0) \in \mathbf{A} \llbracket a_0 \rrbracket, (\sigma, n_1) \in \mathbf{A} \llbracket a_1 \rrbracket\}$

Lemma: $\mathbf{A} \llbracket a \rrbracket$ is a function

Denotational semantics of \mathbf{Aexp} with λ

- $\mathbf{A}: \mathbf{Aexp} \rightarrow (\Sigma \rightarrow \mathbf{N})$
- $\mathbf{A} \llbracket n \rrbracket = \lambda \sigma \in \Sigma. n$
- $\mathbf{A} \llbracket X \rrbracket = \lambda \sigma \in \Sigma. \sigma(X)$
- $\mathbf{A} \llbracket a_0 + a_1 \rrbracket = \lambda \sigma \in \Sigma. (\mathbf{A} \llbracket a_0 \rrbracket \sigma + \mathbf{A} \llbracket a_1 \rrbracket \sigma)$
- $\mathbf{A} \llbracket a_0 - a_1 \rrbracket = \lambda \sigma \in \Sigma. (\mathbf{A} \llbracket a_0 \rrbracket \sigma - \mathbf{A} \llbracket a_1 \rrbracket \sigma)$
- $\mathbf{A} \llbracket a_0 \times a_1 \rrbracket = \lambda \sigma \in \Sigma. (\mathbf{A} \llbracket a_0 \rrbracket \sigma \times \mathbf{A} \llbracket a_1 \rrbracket \sigma)$

Denotational semantics of Bexp

- $\mathbf{B}: \text{Bexp} \rightarrow (\Sigma \rightarrow \mathbf{T})$
- $\mathbf{B} \llbracket \text{true} \rrbracket = \{(\sigma, \text{true}) \mid \sigma \in \Sigma\}$
- $\mathbf{B} \llbracket \text{false} \rrbracket = \{(\sigma, \text{false}) \mid \sigma \in \Sigma\}$
- $\mathbf{B} \llbracket a_0 = a_1 \rrbracket = \{(\sigma, \text{true}) \mid \sigma \in \Sigma \ \& \ \mathbf{A} \llbracket a_0 \rrbracket \sigma = \mathbf{A} \llbracket a_1 \rrbracket \sigma\} \cup \{(\sigma, \text{false}) \mid \sigma \in \Sigma \ \& \ \mathbf{A} \llbracket a_0 \rrbracket \sigma \neq \mathbf{A} \llbracket a_1 \rrbracket \sigma\}$
- $\mathbf{B} \llbracket a_0 \leq a_1 \rrbracket = \{(\sigma, \text{true}) \mid \sigma \in \Sigma \ \& \ \mathbf{A} \llbracket a_0 \rrbracket \sigma \leq \mathbf{A} \llbracket a_1 \rrbracket \sigma\} \cup \{(\sigma, \text{false}) \mid \sigma \in \Sigma \ \& \ \mathbf{A} \llbracket a_0 \rrbracket \sigma \not\leq \mathbf{A} \llbracket a_1 \rrbracket \sigma\}$
- $\mathbf{B} \llbracket \neg b \rrbracket = \{(\sigma, \neg_{\mathbf{T}} t) \mid \sigma \in \Sigma, (\sigma, t) \in \mathbf{B} \llbracket b \rrbracket\}$
- $\mathbf{B} \llbracket b_0 \wedge b_1 \rrbracket = \{(\sigma, t_0 \wedge_{\mathbf{T}} t_1) \mid \sigma \in \Sigma, (\sigma, t_0) \in \mathbf{B} \llbracket b_0 \rrbracket, (\sigma, t_1) \in \mathbf{B} \llbracket b_1 \rrbracket\}$
- $\mathbf{B} \llbracket b_0 \vee b_1 \rrbracket = \{(\sigma, t_0 \vee_{\mathbf{T}} t_1) \mid \sigma \in \Sigma, (\sigma, t_0) \in \mathbf{B} \llbracket b_0 \rrbracket, (\sigma, t_1) \in \mathbf{B} \llbracket b_1 \rrbracket\}$

Lemma: $\mathbf{B} \llbracket b \rrbracket$ is a function

Denotational semantics of commands?

- Running a command c starting from a state σ yields another state σ'
- So, we may try to define $\mathbf{C} \llbracket c \rrbracket$ as a function that maps σ to σ' :
 - $\mathbf{C} \llbracket . \rrbracket: \text{Com} \rightarrow (\Sigma \rightarrow \Sigma)$

Denotational semantics of commands?

- Problem: running a command might not yield anything if the command does not terminate
- We introduce the special element \perp to denote a special outcome that stands for non-termination
- For any set X , we write X_{\perp} for $X \cup \{\perp\}$
- Convention:
 - whenever $f \in X \rightarrow X_{\perp}$ we extend f to $X_{\perp} \rightarrow X_{\perp}$ “strictly” so that $f(\perp) = \perp$

Denotational semantics of commands?

- We try:
 - $C \llbracket \cdot \rrbracket : \text{Com} \rightarrow (\Sigma_{\perp} \rightarrow \Sigma_{\perp})$
- $C \llbracket \text{skip} \rrbracket \sigma = \sigma$
- $C \llbracket c_0 ; c_1 \rrbracket \sigma = C \llbracket c_1 \rrbracket (C \llbracket c_0 \rrbracket \sigma)$
- $C \llbracket \text{if } b \text{ then } c_0 \text{ else } c_1 \rrbracket \sigma =$
if $B \llbracket b \rrbracket \sigma$ then $C \llbracket c_0 \rrbracket \sigma$ else $C \llbracket c_1 \rrbracket \sigma$
- $C \llbracket \text{while } b \text{ do } c \rrbracket \sigma = ?$

Examples

- $C \llbracket X := 2; X := 1 \rrbracket \sigma = \sigma[1/X]$
- $C \llbracket \text{if true then } X := 2; X := 1 \text{ else } \dots \rrbracket \sigma = \sigma[1/X]$
- The semantics does not care about intermediate states
- So far, we did not explicitly need \perp

Denotational semantics of commands?

- Abbreviation $W=C$ **[[while b do C]]**
- Idea: we rely on the equivalence
while b do c \sim if b then (c; while b do c) else skip
- We may try using unwinding equation
 $W(\sigma) = \text{if } B[[b]]\sigma \text{ then } W(C[[c]] \sigma) \text{ else } \sigma$
- Unacceptable solution
 - Defines W in terms of itself
 - It not evident that a suitable W exists
 - It may not describe W uniquely
(e.g., for while true do skip)

Introduction to Domain Theory

- We will solve the unwinding equation through a general theory of recursive equations
- Think of programs as processors of streams of bits (streams of 0's and 1's, possibly terminated by \$)
What properties can we expect?



Motivation

- Let “isone” be a function that must return “1\$” when the input string has at least a 1 and “0\$” otherwise
- What should the result of “isone” be on the partial input “00.. 0” ?
 - It must be the empty string ε
 - **Monotonicity** : Output is never retracted
More information about the input is reflected in more information about the output
- How do we express monotonicity precisely?

Monotonicity

- Define a partial order

$$x \sqsubseteq y$$

- A partial order is reflexive, transitive, and antisymmetric
- y is a refinement of x
- For streams of bits $x \sqsubseteq y$ when x is a prefix of y
- For programs, a typical order is:
 - No output (yet) \sqsubseteq some output
- Other orders
 - Subsets

Monotonicity

- A set equipped with a partial order is a poset
- Definition:
 - D and E are postes
 - A function $f:D \rightarrow E$ is monotonic if
$$\forall x, y \in D: x \sqsubseteq_D y \Rightarrow f(x) \sqsubseteq_E f(y)$$
 - The semantics of the program ought to be a monotonic function
 - More information about the input leads to more information about the output

Monotonicity Example

- Consider our “isone” function with the prefix ordering
- Notation:
 - 0^k is the stream with k consecutive 0’s
 - 0^∞ is the infinite stream with only 0’s
- Question (revisited): what is $\text{isone}(0^k)$?
 - By definition, $\text{isone}(0^k\$) = 0\$$ and $\text{isone}(0^k1\$) = 1\$$
 - But $0^k \sqsubseteq 0^k\$$ and $0^k \sqsubseteq 0^k1\$$
 - “isone” must be monotone, so:
 - $\text{isone}(0^k) \sqsubseteq \text{isone}(0^k\$) = 0\$$
 - $\text{isone}(0^k) \sqsubseteq \text{isone}(0^k1\$) = 1\$$
 - Therefore, monotonicity requires that $\text{isone}(0^k)$ is a common prefix of $0\$$ and $1\$$, namely ε

Thesis

- The semantics of every program must be monotonic

Motivation

- Are there other constraints on “isone”?
- Define “isone” to satisfy the equations
 - $\text{isone}(\varepsilon) = \varepsilon$
 - $\text{isone}(1s) = 1s$
 - $\text{isone}(0s) = \text{isone}(s)$
 - $\text{isone}(\$) = 0s$
- What about 0^∞ ?
- **Continuity:** finite output depends only on finite input (no infinite lookahead)

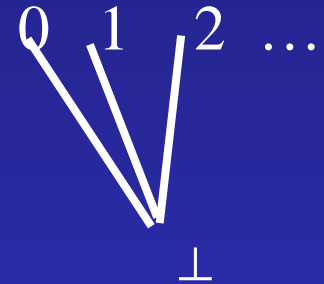
Upper and Lower Bounds

- An upper bound of a set is an element “bigger” than all elements in the set
- The least upper bound is the “smallest” among upper bounds:
 - $x_i \leq \sqcup \langle x_i \rangle$ for all $i \in \mathbb{N}$
 - $\sqcup \langle x_i \rangle \leq y$ for all upper bounds y of $\langle x_i \rangle$
and it is unique if it exists
- Greatest lower bounds are defined similarly

Chains

- A **chain** is a countable increasing sequence
 $\langle x_i \rangle = \{ x_i \in X \mid x_0 \sqsubseteq x_1 \sqsubseteq \dots \}$
- An upper bound of a set is an element “bigger” than all elements in the set
- The least upper bound is the “smallest” among upper bounds:
 - $x_i \sqsubseteq \sqcup \langle x_i \rangle$ for all $i \in \mathbb{N}$
 - $\sqcup \langle x_i \rangle \sqsubseteq y$ for all upper bounds y of $\langle x_i \rangle$
and it is unique if it exists

Complete Partial Orders



- Not every poset has an upper bound
 - with $\perp \sqsubseteq n$ and $n \sqsubseteq n$ for all $n \in \mathbb{N}$
 - $\{1, 2\}$ does not have an upper bound
- Sometimes chains have no upper bound

⋮

2

The chain

1

$0 \leq 1 \leq 2 \leq \dots$

0

does not have an upper bound

Complete Partial Orders

- It is convenient to work with posets where every chain (not necessarily every set) has a least upper bound
- A partial order P is **complete** if every chain in P has a least upper bound also in P
- We say that P is a complete partial order (cpo)
- A cpo with a least (“bottom”) element \perp is a pointed cpo (pcpo)

Examples of cpo's

- Any set P with the order $x \sqsubseteq y$ if and only if $x = y$ is a cpo
It is discrete or flat
- If we add \perp so that $\perp \sqsubseteq x$ for all $x \in P$, we get a flat pointed cpo
- The set \mathbb{N} with \leq is a poset with a bottom, but not a complete one
- The set $\mathbb{N} \cup \{ \infty \}$ with $n \leq \infty$ is a pointed cpo
- The set \mathbb{N} with \geq is a cpo without bottom
- Let S be a set and $P(S)$ denotes the set of all subsets of S ordered by set inclusion

Constructing cpos

- If D and E are pointed cpos, then so is $D \times E$

$(x, y) \sqsubseteq_{D \times E} (x', y')$ iff $x \sqsubseteq_D x'$ and $y \sqsubseteq_E y'$

$\perp_{D \times E} = (\perp_D, \perp_E)$

$\sqcup (x_i, y_i) = (\sqcup_D x_i, \sqcup_E y_i)$

Constructing cpos (2)

- If S is a set of E is a pcpos, then so is

$$S \rightarrow E$$

$$m \sqsubseteq m' \text{ iff } \forall s \in S: m(s) \sqsubseteq_E m'(s)$$

$$\perp_{S \rightarrow E} = \lambda s. \perp_E$$

$$\sqcup (m, m') = \lambda s. m(s) \sqcup_E m'(s)$$

Continuity

- A monotonic function maps a chain of inputs into a chain of outputs:

$$x_0 \sqsubseteq x_1 \sqsubseteq \dots \Rightarrow f(x_0) \sqsubseteq f(x_1) \sqsubseteq \dots$$

- It is always true that:

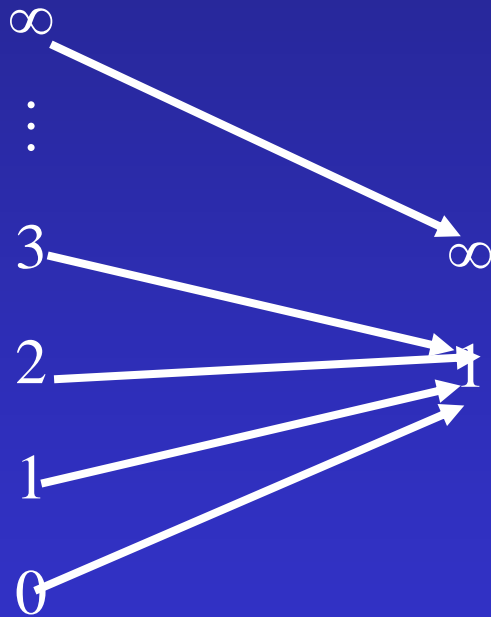
$$\sqcup_i \langle f(x_i) \rangle \sqsubseteq f(\sqcup_i \langle x_i \rangle)$$

- But

$$f(\sqcup_i \langle x_i \rangle) \sqsubseteq \sqcup_i \langle f(x_i) \rangle$$

is not always true

A Discontinuity Example



$$f(\sqcup_i \langle x_i \rangle) \neq \sqcup_i \langle f(x_i) \rangle$$

Continuity

- Each $f(x_i)$ uses a “finite” view of the input
- $f(\sqcup \langle x_i \rangle)$ uses an “infinite” view of the input
- A function is **continuous** when
$$f(\sqcup \langle x_i \rangle) = \sqcup_i \langle f(x_i) \rangle$$
- The output generated using an infinite view of the input does not contain more information than all of the outputs based on finite inputs

Examples of Continuous Functions

- For the partial order $(\mathbf{N} \cup \{\infty\}, \leq)$
 - The identity function is continuous
 $\text{id}(\sqcup n_i) = \sqcup \text{id}(n_i)$
 - The constant function “five(n)=5” is continuous
 $\text{five}(\sqcup n_i) = \sqcup \text{five}(n_i)$
- For a flat cpo A , any monotonic function $f: A_{\perp} \rightarrow A_{\perp}$ such that \bar{f} is strict is continuous
- Chapter 8 of the textbook includes many more continuous functions

Fixed Points

- Solve the equation:

$$W(\sigma) = \begin{cases} W(C[[c]] \sigma) & \text{if } B[[b]](\sigma)=\text{true} \\ \sigma & \text{if } B[[b]](\sigma)=\text{false} \\ \perp & \text{if } B[[b]](\sigma)=\perp \end{cases}$$

where $W: \Sigma_{\perp} \rightarrow \Sigma_{\perp}$

$W = C[[\text{while be do } c]]$

- This equation can be written as $W = F(W)$

with:

$$F(W) = \lambda \sigma. \begin{cases} W(C[[c]] \sigma) & \text{if } B[[b]](\sigma)=\text{true} \\ \sigma & \text{if } B[[b]](\sigma)=\text{false} \\ \perp & \text{if } B[[b]](\sigma)=\perp \end{cases}$$

Fixed Point (cont)

- Thus we are looking for a solution for $W = F(W)$
 - a fixed point of F
- Typically there are many fixed points
- We may argue that W ought to be continuous
 $W \in [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]$
- Cut the number of solutions
- We will see how to find the least fixed point for such an equation provided that F itself is continuous

Fixed Point Theorem

- Define $F^k = \lambda x. F(F(\dots F(x)\dots))$ (F composed k times)
- If D is a pointed cpo and $F : D \rightarrow D$ is continuous, then
 - for any fixed-point x of F and $k \in \mathbb{N}$
 $F^k(\perp) \sqsubseteq x$
 - The least of all fixed points is
 $\sqcup_k F^k(\perp)$
- Proof:
 - i. By induction on k .
 - Base: $F^0(\perp) = \perp \sqsubseteq x$
 - Induction step: $F^{k+1}(\perp) = F(F^k(\perp)) \sqsubseteq F(x) = x$
 - ii. It suffices to show that $\sqcup_k F^k(\perp)$ is a fixed-point
 - $F(\sqcup_k F^k(\perp)) = \sqcup_k F^{k+1}(\perp) = \sqcup_k F^k(\perp)$

Fixed-Points (notes)

- If F is continuous on a pointed cpo, we know how to find the least fixed point
- All other fixed points can be regarded as refinements of the least one
- They contain more information, they are more precise
- In general, they are also more arbitrary
- They also make less sense for our purposes

Denotational Semantics of IMP

- Σ_{\perp} is a flat pointed cpo
 - A state has more information on non-termination
 - Otherwise, the states must be equal to be comparable (information-wise)
- We want strict functions $\Sigma_{\perp} \rightarrow \Sigma_{\perp}$ (therefore, continuous functions)
- The partial order on $\Sigma_{\perp} \rightarrow \Sigma_{\perp}$
 $f \sqsubseteq g$ iff $f(x) = \perp$ or $f(x) = g(x)$ for all $x \in \Sigma_{\perp}$
 - g terminates with the same state whenever f terminates
 - g might terminate for more inputs

Denotational Semantics of IMP

- Recall that W is a fixed point of

$$F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$$

$$F(w) = \lambda \sigma. \begin{cases} w(C[[c]](\sigma)) & \text{if } B[[b]](\sigma) = \text{true} \\ \sigma & \text{if } B[[b]](\sigma) = \text{false} \\ \perp & \text{if } B[[b]](\sigma) = \perp \end{cases}$$

- F is continuous

- Thus, we set

$$C[[\text{while } b \text{ do } c]] = \sqcup F^k(\perp)$$

- Least fixed point

– Terminates least often of all fixed points

- Agrees on terminating states with all fixed point

Example(1)

- while true do skip
- $F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$

$$F = \lambda w. \lambda \sigma. \begin{cases} w(C[[c]](\sigma)) & \text{if } B[[b]](\sigma) = \text{true} \\ \sigma & \text{if } B[[b]](\sigma) = \text{false} \\ \perp & \text{if } B[[b]](\sigma) = \perp \end{cases}$$

$$B[[\text{true}]] = \lambda \sigma. \text{true}$$

$$C[[\text{skip}]] = \lambda \sigma. \sigma$$

$$F = \lambda w. \lambda \sigma. w(\sigma)$$

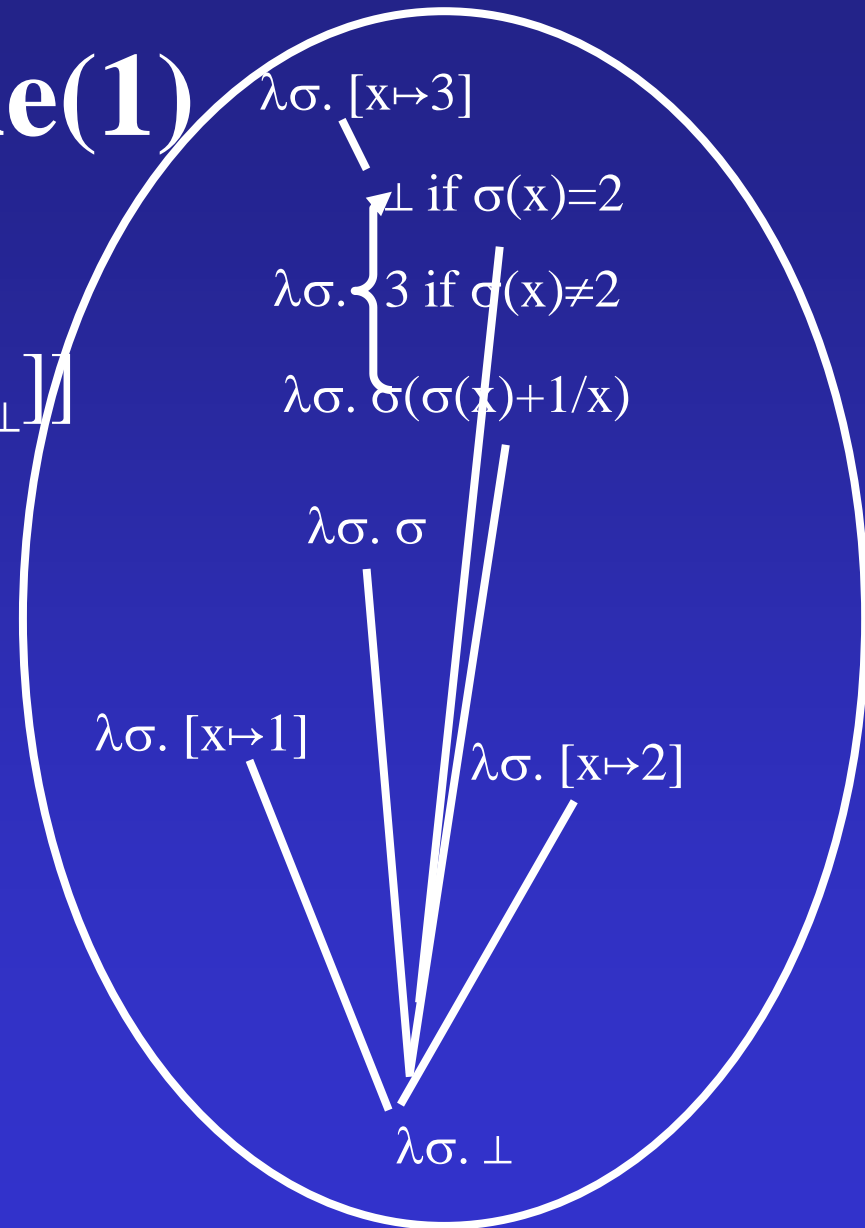
Example(1)

- while true do skip
- $F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$

$$F = \lambda w. \lambda \sigma. w(\sigma)$$

$$\text{Var} = \{x\}$$

$$C[\text{while true do skip}] = \bigsqcup F^k(\perp) = \lambda \sigma. \perp$$



Example(2)

- while false do c
- $F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$

$$F = \lambda w. \lambda \sigma. \begin{cases} w(C[[c]](\sigma)) & \text{if } B[[b]](\sigma) = \text{true} \\ \sigma & \text{if } B[[b]](\sigma) = \text{false} \\ \perp & \text{if } B[[b]](\sigma) = \perp \end{cases}$$

$$B[[\text{false}]] = \lambda \sigma. \text{false}$$

$$F = \lambda w. \lambda \sigma. \sigma$$

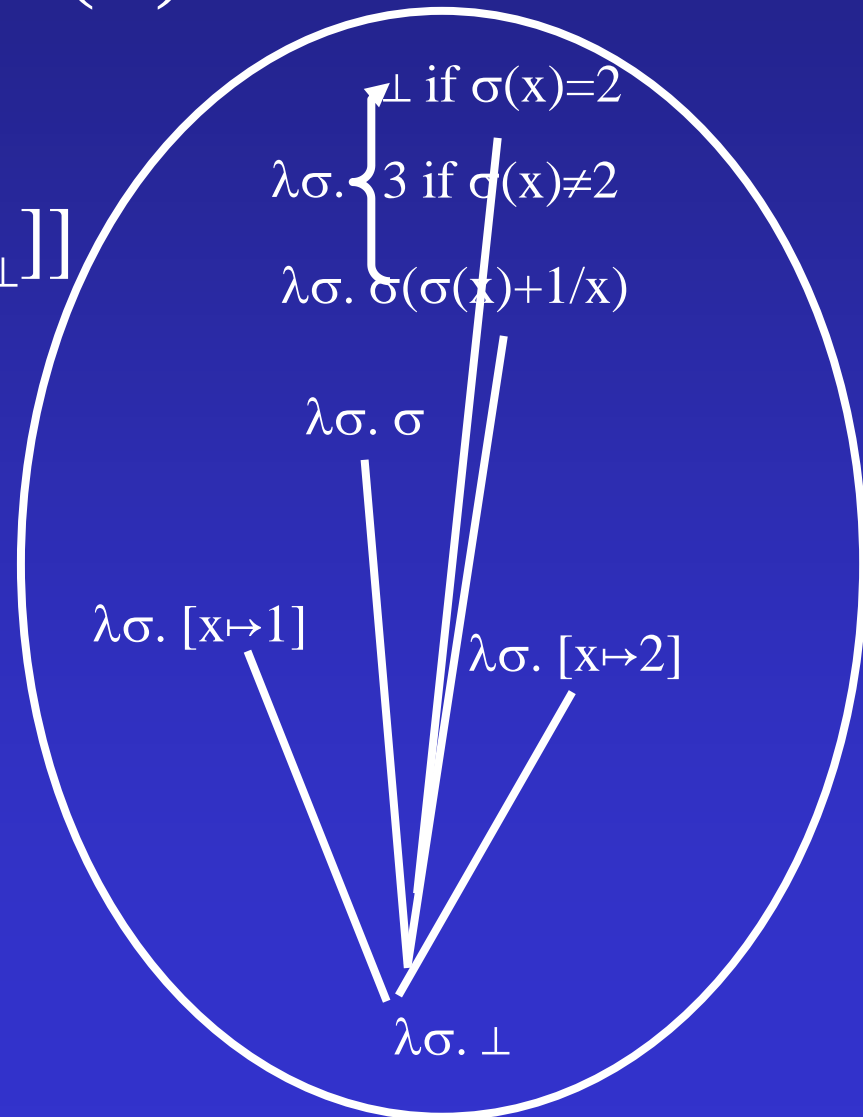
Example(2)

- while true do skip
- $F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$

$$F = \lambda w. \lambda \sigma. \sigma$$

$$\text{Var} = \{x\}$$

$$C[[\text{while false do } C]] = \bigsqcup F^k(\perp) = \lambda \sigma. \sigma$$



Example(3)

- while $x \neq 3$ do $x = x - 1$
- $F: [[\Sigma_{\perp} \rightarrow \Sigma_{\perp}] \rightarrow [\Sigma_{\perp} \rightarrow \Sigma_{\perp}]]$

$$F = \lambda w. \lambda \sigma. \begin{cases} w(C[[c]](\sigma)) & \text{if } B[[b]](\sigma) = \text{true} \\ \sigma & \text{if } B[[b]](\sigma) = \text{false} \\ \perp & \text{if } B[[b]](\sigma) = \perp \end{cases}$$

$$B[[x \neq 3]] = \lambda \sigma. \sigma(x) \neq 3$$

$$c[[x = x - 1]] = \lambda \sigma. \sigma(\sigma(x) - 1/x)$$

$$F = \lambda w. \lambda \sigma. \begin{cases} w(\sigma(\sigma(x) - 1/x)) & \text{if } \sigma(x) \neq 3 \\ \sigma & \text{if } \sigma(x) = 3 \end{cases}$$

Example(3)

- while $x \neq 3$ do $x = x - 1$

$$F = \lambda w. \lambda \sigma. \begin{cases} B(\sigma(\sigma(x)-1/x)) & \text{if } \sigma(x) \neq 3 \\ \sigma & \text{if } \sigma(x) = 3 \end{cases}$$

$F^0(\perp)$	$\lambda \sigma. \perp$
$F^1(\perp)$	$\lambda \sigma. \text{if } \sigma(x) = 3 \text{ then } \sigma(3/x) \text{ else } \perp$
$F^2(\perp)$	$\lambda \sigma. \text{if } 3 \leq \sigma(x) \leq 4 \text{ then } \sigma(3/x) \text{ else } \perp$
$F^k(\perp)$	$\lambda \sigma. \text{if } 3 \leq \sigma(x) \leq 3+k-1 \text{ then } \sigma(3/x) \text{ else } \perp$
$\bigsqcup_k F^k(\perp)$	$\lambda \sigma. \text{if } 3 \leq \sigma(x) \text{ then } \sigma(3/x) \text{ else } \perp$

Example 4 Nested Loops

```
Z = 0 ;
```

```
while X > 0 do (
```

```
    Y = X;
```

```
    while (Y>0) do
```

```
        Z = Z + Y ;
```

```
        Y = Y - 1; )
```

```
    X = X - 1
```

```
)
```

Equivalence of Semantics

- $\forall \sigma, \sigma' \in \Sigma:$

$$\sigma' = C[[c]]\sigma \Leftrightarrow \langle c, \sigma \rangle \rightarrow \sigma' \Leftrightarrow \langle c, \sigma \rangle \Rightarrow^* \sigma'$$

Complete Partial Orders

- Let (D, \sqsubseteq) be a partial order
 - D is a **complete lattice** if every subset has both greatest lower bounds and least upper bounds

Knaster-Tarski Theorem

- Let $f: L \rightarrow L$ be a monotonic function on a complete lattice L
- The least fixed point $\text{lfp}(f)$ exists
 - $\text{lfp}(f) = \bigcap \{x \in L: f(x) \sqsubseteq x\}$

Summary

- Denotational definitions are not necessarily better than operational semantics, and they usually require more mathematical work
- The mathematics may be done once and for all
- The mathematics may pay off:
- Some of its techniques are being transferred to operational semantics.
- It is trivial to prove that
“If $B[[b_1]] = B[[b_2]]$ and $C[[c_1]] = C[[c_2]]$
then
 $C[[\text{while } b_1 \text{ do } c_1]] = C[[\text{while } b_2 \text{ do } c_2]]$ ”
(compare with the operational semantics)

Summary

- Denotational semantics provides a way to declare the meaning of programs in an abstract way
 - Can handle side-effects
 - Loops
 - Recursion
 - Gotos
 - Non-determinism
 - But not low level concurrency
- Fixed point theory provides a declarative way to specify computations
 - Many usages