Verifying Equivalence of Spark Programs
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Abstract. \textit{Spark} is a popular framework for writing large scale data processing applications. Our goal is to develop tools for reasoning about Spark programs. This is challenging because Spark programs combine database-like relational algebraic operations and aggregate operations with \textit{User Defined Functions (UDFs)}.

We present the first technique for verifying the equivalence of Spark programs. We model Spark as a programming language whose semantics imitates Relational Algebra queries (with aggregations) over bags (multi-sets) and allows for UDFs expressible in Presburger Arithmetics. While the problem of checking equivalence is undecidable in general, we present a sound technique for verifying the equivalence of an interesting class of Spark programs, and show that it is complete under certain restrictions.

We implemented our technique in a prototype tool, and used it to verify the equivalence of a few small, but intricate, open-source Spark programs.

1 Introduction

\textit{Spark} \cite{spark1,spark2,spark3} is a popular framework for writing large scale data processing applications. Such frameworks, intended for data-intensive operations, share many similarities with NoSQL database systems \cite{nosql1}. Unlike traditional relational databases, which are accessed using a standard query language, NoSQL databases are often accessed via an entire program. A key property of Spark is the ability to employ User Defined Functions (UDFs), which are used in higher-order operations such as \textit{map}, \textit{filter}, and \textit{fold}.

Spark is an evolution of the Map-Reduce paradigm, which provides an abstraction of the distributed data as bags of items called \textit{resilient distributed datasets (RDDs)}. An RDD $r$ can be accessed using operations such as \textit{map}, which applies a function to all items in $r$, \textit{filter}, which filters items in $r$ using a given boolean function, and \textit{fold} which aggregates items together, again using a UDF. Intuitively, map, filter and fold can be seen as extensions to the standard database operations \textit{project}, \textit{select} and \textit{aggregation}, respectively, with arbitrary UDFs applied. A language such as \textit{Scala} or \textit{Python} is used as Spark’s interface, which allows to embed calls to the underlying framework in standard programs, as well as to define the UDFs that Spark executes.
This paper addresses the problem of reasoning about Spark programs. In particular, we are interested in questions of checking whether two Spark programs are equivalent and identifying the differences between two programs. This problem is important for query optimization [5], program correctness, program regression, and software understanding. We show that problem of checking equivalence of Spark programs is undecidable in general, even for programs containing a single aggregate operation. Therefore, we are interested in (1) identifying sub-cases in which it is decidable to check equivalence, and (2) identifying sound and useful methods for dealing with large classes of Spark programs. We note that some of the intricacies arise from the fact RDDs are bags (and not sets or individual items), and Spark programs may contain aggregations (fold operations).

**Main Results**

Our main technical contributions can be summarized as follows:

- We present a simplified model of Spark by defining SparkLite, a functional programming language in which UDFs are expressed over a decidable theory.
- We prove that verifying the equivalence of SparkLite programs is undecidable.
- We identify several interesting classes of SparkLite programs and develop sound, and in certain cases complete, methods for proving program equivalence. (See Table 1.)
- We implemented our approach over Z3 [13], and applied it to several interesting programs taken out of real-life Spark applications. In case the tool fails to verify equivalence, it produces a counterexample of RDD elements which are witnesses for the difference between the programs. This counterexample is guaranteed to be real for programs which have a complete verification method, and can help understand the differences between these programs.

**1.1 Overview**

We now provide an informal overview on our verification technique, and its scope. Our main tool for showing equivalence of Spark programs is reducing the equivalence question to the validity of a formula in Presburger arithmetic, which is a decidable theory [15, 24]. Our practical tool uses Z3. This is surprising since Spark programs contain implicit loops and higher-order functions. Our insight is that in many cases these loops are simple enough to allow reasoning by using universal formulae for programs without aggregations and extract simple inductive invariants for programs with aggregations. We now demonstrate that through a series of simple examples.
A simple example. Figure 1 shows two equivalent Spark programs and the formula that we use for checking their equivalence. The programs accept an RDD of integer elements. They return another RDD where each element is twice the value of the original element, for elements which are at least 50. The programs operate differently: \( P_1 \) first multiplies, then filters, while \( P_2 \) goes the other way around. \texttt{map} and \texttt{filter} are operations that apply a function on each element in the RDD, and yield a new RDD. For example, let RDD \( R \) be the bag \( \{2, 2, 103, 64\} \) (note that repetitions are allowed). \( R \) is an input of both \( P_1 \) and \( P_2 \). The \texttt{map} operator in the first line of \( P_1 \) produces a new RDD, \( R'_1 \), by doubling every element of \( R \), i.e., \( R'_1 = \{4, 4, 206, 128\} \). The \texttt{filter} operator in the second line generates RDD \( R''_1 \), containing the elements of \( R'_1 \) which are at least 100, i.e., \( R''_1 = \{206, 128\} \). The second program first applies the filter operator, producing an RDD \( R'_2 \) of all the elements in \( R \) which are smaller than 50, resulting in the RDD \( R'_2 = \{103, 64\} \). \( P_2 \) applies the map operator to produce RDD \( R''_2 \) which contains the same elements as \( R''_1 \). Hence, both programs return the same value.

To verify that the programs are indeed equivalent, we encode them symbolically using formulae in first-order logic, such that the question of equivalence boils down to proving the validity of a formula. In this example, we encode \( P_1 \) as: \( \text{ite}(2 \ast x \geq 100, 2 \ast x, \bot) \), and \( P_2 \) as: \( 2 \ast \text{ite}(x \geq 50, x, \bot) \), where \( \text{ite} \) denotes the if-then-else operator and \( \bot \) is used to denote that the element has been removed. The variable symbol \( x \) can be thought of as an arbitrary element in the dataset \( R \), and the terms on the left and right side of the equality sign record the effect of \( P_1 \) and \( P_2 \), respectively, on \( x \). The constant symbol \( \bot \) records the deletion of an element due to not satisfying the condition checked by the \texttt{filter} operation. The formula whose validity attests for the equivalence of \( P_1 \) and \( P_2 \) is thus: \( \forall x. \text{ite}(2 \ast x \geq 100, 2 \ast x, \bot) = 2 \ast \text{ite}(x \geq 50, x, \bot) \).

This example points out an important property of the \texttt{map} and \texttt{filter} operations, namely, their locality: they handle every element separately, with no regard to its multiplicity (the number of duplicates it has in the RDD) or the presence of other elements. Thus, we can symbolically represent the effect of the program on any RDD by encoding its effect on a single arbitrary element.

Usage of inductive reasoning. We also handle programs that use aggregations in a limited way. For example, we give a sound verification technique for \texttt{Agg} \( ^1 \), which is a class of programs that use a single \texttt{fold} operation and returns a primitive
discount = \lambda (prod, p).(prod, p - 20)

\text{min2} = \lambda A, (x, y). \text{if } A < y \text{ then } A \text{ else } y

\textbf{P3}(R: RDD_{\text{Prod \times Int}}):
\text{minP} = \text{fold}(+\infty, \text{min2})(R)
\text{return } \text{minP} \geq 100

\textbf{P4}(R: RDD_{\text{Prod \times Int}}):
R' = \text{map}(\lambda (prod, p), \text{discount}((\text{prod}, p)))(R)
\text{minDiscountP} = \text{fold}(+\infty, \text{min2})(R')
\text{return } \text{minDiscountP} \geq 80

\left( \text{prod}' = \text{prod} \land p' = p - 20 \right)
\land \left( M_2 = \text{ite}(M_1 < p, M_1, p) \land M'_2 = \text{ite}(M'_1 < p', M'_1, p') \right)
\Rightarrow \left( +\infty \geq 100 \iff +\infty \geq 80 \right)
\land \left( (M_1 \geq 100 \iff M'_1 \geq 80) \Rightarrow (M_2 \geq 100 \iff M'_2 \geq 80) \right)
\text{base case}

\text{induction step}

\textbf{Fig. 2.} Equivalent Spark programs with aggregations and an inductive equivalence formula. Variables \text{prod}, p, p', M_1, M'_1, M_2, M'_2 are universally quantified.

Interestingly, we show that even in this limited class, deciding equivalence is undecidable. (See Theorem 2.) Figure 2 contains an example of two simple equivalent Spark programs which use aggregations. The programs operate over an RDD of pairs (product IDs, price). The programs check if the minimal price of the RDD is at least 100. The second program does it by subtracting 20 from each price in the RDD and comparing the minimum to 80. \text{P3} computes the minimal price in \( R \) using \text{fold}, and then returns \text{true} if it is at least 100 and \text{false} otherwise. \text{P4} first applies \text{discount} to every element, resulting in a temporary RDD \( R' \), and then computes the minimum of \( R' \). It returns \text{true} if the minimum is at least 80, and \text{false} otherwise.

The \text{fold} operation combines the elements of an RDD by repeatedly applying a UDF. \text{fold} cannot be expressed in first order terms. Thus, we use induction to verify that two \text{fold} results are equal. Roughly speaking, the induction leverages the somewhat local nature of the \text{fold} operation, specifically, that it does not track how the temporarily accumulated value is obtained: Note that the elements of \( R' \) can be expressed by applying the \text{discount} function on the elements of \( R \). Thus, intuitively, we can assume that in both programs, \text{fold} iterates on the input RDD \( R \) in the same order. (It is permitted to assume a particular order because the applied UDFs must be commutative for the \text{fold} to be well-defined [19].) The base of the induction hypothesis checks that the programs are equivalent when the input RDDs are empty, and the induction step verifies the equivalence is retained when we apply the \text{fold}'s UDF on some arbitrary accumulated value and an element coming from each input RDD. In our example, when the RDDs are empty both programs return \text{true}. (The \text{fold} operation returns +\infty.) Otherwise, we assume that after \( n \) prices checked, the minimum \( M_1 \) in \( P3 \) is at least 100 iff the minimum \( M'_1 \) in \( P4 \) is at least 80. The programs are equivalent if this invariant is kept after checking the next product and price ((\text{prod}, p), (\text{prod}', p')) giving updated intermediate values \( M_2 \) and \( M'_2 \).

Completeness of the inductive reasoning. In the example in Figure 2, we use a simple form of induction by essentially proving that two higher-order operations...
are equivalent iff they are equivalent on every input element and arbitrary temporarily accumulated values \((M_1 \text{ and } M'_1 \text{ in Figure 2})\). Such an approach is incomplete. We now show an example for incompleteness, and a modified verification formula which is complete for a designated set of Spark programs called \(\text{AggPair}^1_{\text{sync}}\), which is a subclass of \(\text{Agg}^1\). In Figure 3, \(P_3\) and \(P_4\) were rewritten into \(P_5\) and \(P_6\), respectively, by using \(=\) instead of \(\geq\). In this example the programs are equivalent. We show both the “naïve” formula, similar to the formula from Figure 2, and a revised version of it. We explain shortly how the revised formula is obtained. The naïve formula is not valid, since it requires that the returned values be equivalent ignoring the history of applied \(\text{fold}\) operations generating the intermediate values \(M_1\) and \(M'_1\). In particular, for \(M_1 = 60\), \(M'_1 = 120\), and \(p = 100\), we get a spurious counterexample to equality, leading to the wrong conclusion that the programs may not be equivalent. However, if \(P_5\) and \(P_6\) iterate over the input RDD in the same order, it is not possible that their (temporarily) accumulated values are \(60\) and \(120\) at the same time.

Fortunately, we observed that often, the \(\text{fold}\) UDFs are somewhat restricted. One such natural property, dubbed \(\text{collapsible aggregation}\), is the ability “collapse” the any sequence of application of \(f\) using a single application. We can leverage this property for more complete treatment of equivalence verification if the programs collapse in \(\text{synchrony}\): for functions \(f_1, f_2, \varphi_1, \varphi_2\) and initial values \(i_1\) and \(i_2\):

\[
\forall x, y. \exists a. f_1(f_1(i_1, \varphi_1(x)), \varphi_1(y)) = f_1(i_1, \varphi_1(a)) \\
\land f_2(f_2(i_2, \varphi_2(x)), \varphi_2(y)) = f_2(i_2, \varphi_2(a))
\]

(1)

In our example, \(\min(\min(\infty, x), y) = \min(\infty, a)\), and \(\min(\min(\infty, x - 20), y - 20) = \min(\infty, a - 20)\), for \(a = \min(x, y)\). The reader may be concerned how this closure property can be checked. Interestingly, for formulas in Presburger arithmetic, an SMT solver can decide this property.

We utilized the above closure property by observing that any pair of intermediate results can be expressed as single applications of the UDF. Surely any \(M_1\) must have been obtained by repeating applications of the form \(f_1(f_1(\cdots))\), and similarly for \(M'_1\) with \(f_2(f_2(\cdots))\). Therefore, in the revised formula, instead of quantifying on any \(M_1\) and \(M'_1\), we quantify over the argument \(a\) to that single application, and introduce the assumption incurred by Equation (1). We can then write an induction hypothesis that holds iff the two fold operations return an equal result.

Decidability. Table 1 characterizes the programs for which our method is applicable together with the strength of the method. The example program in Figure 1 is representative of programs that belong to the \(\text{NoAgg}\) class of programs, defined as programs without \(\text{fold}\) operations, for which we have a decision procedure showing it is decidable. We consider four classes of programs containing \(\text{fold}\) operations. Equivalence in \(\text{Agg}^1\) is undecidable, and the result is extended naturally to \(\text{Agg}_R^1\) and \(\text{Agg}^n\). On the other hand, \(\text{AggPair}^1_{\text{sync}}\) is decidable and we provide a decision procedure. The programs in Figures 2 and 3 belong to \(\text{AggPair}^1_{\text{sync}}\). Note that, formally, \(\text{AggPair}^1_{\text{sync}}\) contains pairs of programs, and thus in fact is a relation between programs. Deciding whether a pair of programs belong to
\[ \text{P5} \left( R \colon \text{RDD}_{\text{prod} \times \text{Int}} \right): \]
\[ \text{minP} = \text{fold}(+\infty, \text{minP})(R) \]
\[ \text{return minP} = 100 \]

\[ \text{P6} \left( R \colon \text{RDD}_{\text{prod} \times \text{Int}} \right): \]
\[ R' = \text{map}(\lambda(\text{prod}, p). \text{discount}((\text{prod}, p)))(R) \]
\[ \text{minDiscountP} = \text{fold}(+\infty, \text{minP})(R') \]
\[ \text{return minDiscountP} = 80 \]

Naive formula:
\[
\left( \text{prod}' = \text{prod} \land p' = p - 20 \right)
\left( \land M_2 = \text{ite}(M_1 < p, M_1, p) \land M_2' = \text{ite}(M_1' < p', M_1', p') \right) \quad \text{assumptions}
\implies (\infty = 100 \iff \infty = 80) \quad \text{base case}
\left( (M_1 = 100 \iff M_1' = 80) \implies (M_2 = 100 \iff M_2' = 80) \right) \quad \text{induction step}
\]

Revised formula:
\[
\left( \text{prod}' = \text{prod} \land p' = p - 20 \right)
\left( \land a = (a_0, a_1) \land M_1 = \text{ite}(+\infty < a_1, +\infty, a_1) \quad \text{closure} \right)
\left( \land M_2 = \text{ite}(M_1 < p, M_1, p) \land M_2' = \text{ite}(M_1' < p', M_1', p') \right) \quad \text{assumptions}
\implies (\infty = 100 \iff \infty = 80) \quad \text{base case}
\left( (M_1 = 100 \iff M_1' = 80) \implies (M_2 = 100 \iff M_2' = 80) \right) \quad \text{induction step}
\]

Fig. 3. Equivalent Spark programs for which a more elaborate induction is required. All variables are universally quantified.

\textit{AggPair}_{\text{sync}}^1 \text{ is done by checking the validity of Equation (1), which is expressed in Presburger arithmetic.}

\textbf{Limitations} We restrict ourselves to programs using map, filter, cartesian product, and fold where UDFs are defined in Presburger Arithmetic. It is possible, but technically cumbersome, to extend our work to support self-products and by-key (group-by) operations. However, supporting operators such as union and subtract can be tricky because of the bag semantics. We also ignore certain low-level aspects of Spark, such as fault tolerance and distribution and partitioning of the data. We are encouraged by the fact that the classes of programs we handle cover several interesting programs that we found in the Internet and in textbooks (see Section 4). Presburger arithmetic can be implemented with solvers like Cooper’s algorithm [12]. For simplicity we use Z3 which does not support full Presburger arithmetic, but supports the fragment of Presburger arithmetic used in this paper. Z3 also supports uninterpreted functions which are useful to prove equivalence of other classes of Spark programs, but this is beyond the scope of this paper.

\section{1.2 Related Work}

This paper bridges the areas of databases and programming languages. The problem considered (i.e., determining equivalence of expressions accessing a dataset) is a classic topic in database theory. The solution approach (i.e., using symbolic representation in a decidable theory) is often employed in the programming language community. We briefly discuss related work from both areas.
Query containment and equivalence were first studied in the seminal work \[4\]. This work was extended in numerous papers, e.g., \[20\] for queries with inequalities and \[7\] for acyclic queries. Of most relevance to this paper are the extensions to queries evaluated under bag and bag-set semantics \[6\], and to aggregate queries, e.g., \[10,11,16\]. The latter papers consider specific aggregate functions, such as min, count, sum and average, or aggregate functions defined by operations over abelian monoids. In comparison, we do not restrict UDFs to monoids, and provide a different characterization for decidability.

In the field of verification and programming languages there were several works addressing verifying properties of relational algebra operators. For example, El Ghazi et al. \[14\] took the SMT solver approach to verify relational constraints in Alloy \[18\]. Smith and Albarghouthi \[27\] presented an algorithm for synthesizing Spark programs by analyzing user examples fitted into higher-order sketches. They used SMTs to verify determinism, i.e., the commutativity of the fold UDFs. Chen et al. \[8\], studied the decidability of the latter problem. We use SMT to verify program equality. In this sense, our approaches are complementary.

2 The SparkLite language

In this section, we define SparkLite, a simple functional programming language which allows to use Spark’s resilient distributed datasets (RDDs) \[29\].

Preliminaries. We denote a (possibly empty) sequence of elements coming from a set \(X\) by \(X\). An if-then-else expression \(\text{ite}(p,e,e')\) denotes an expression which evaluates to \(e\) if \(p\) holds and to \(e'\) otherwise. A bag \(m\) over a domain \(X\) is a multiset, i.e., a set which allows for repetitions, with elements taken from \(X\). We denote the multiplicity of an element \(x\) in bag \(m\) by \(m(x)\), where for any \(x\), either \(0 < m(x)\) or \(m(x)\) is undefined. We write \(x \in m\) as a shorthand for \(0 < m(x)\). We write \(\{\{x; n(x) \mid x \in X \land \phi(x)\}\}\) to denote a bag with elements from \(X\) satisfying some property \(\phi\) with multiplicity \(n(x)\), and omit the conjunct \(x \in X\) if \(X\) is clear from context. We denote the size (number of elements) of a set \(X\) by \(|X|\) and that of a bag \(m\) of elements from \(X\) by \(|m|\), i.e., \(|m| = \Sigma_{x \in X} \text{ite}(x \in m, m(x), 0)\). We denote the empty bag by \(\{\}\).

Syntax of SparkLite The syntax of SparkLite is defined in Figure 4. SparkLite supports two primitive types: integers (\(\text{Int}\)) and booleans (\(\text{Boolean}\)). On top of this, the user can define record types \(\tau\), which are Cartesian products of primitive
types, and RDDs: $\text{RDD}_\tau$ is (the type of) bags containing elements of type $\tau$. We refer to primitive types and tuples of primitive types as basic types, and, by abuse of notation, range over them using $\tau$. We use $e$ to denote a basic expression containing only basic types, written in Presburger arithmetics extended to include tuples in a straightforward way. (See Appendix A.) We range over variables using $v$ and $\tau$ for variables of basic types and RDD, respectively.

A program $P(\vec{r}:\text{RDD}_\tau, \vec{v}:\tau) = \text{Fdef} \text{PFdef} E$ is comprised of a header and a body, which are separated by the $=$ sign. The header contains the name of the program (P) and a sequence of the names and types of its input formal parameters, which may be RDDs ($\vec{r}$) or records or primitive types ($\vec{v}$). We denote the sequence of input formal parameters of $P$ by $\text{FV}(P)$. The body of the program is comprised of two sequences of function declarations ($\text{Fdef}$ and $\text{PFdef}$) and the program’s main expression ($E$). $\text{Fdef}$ binds function names $f$ with first-order lambda expressions, i.e., to a function which takes as input a sequence of arguments of basic types and return a value of a basic type. $\text{PFdef}$ associates function names $F$ with a restricted form of second-order lambda expressions, which we refer to as parametric functions. As in the Kappa Calculus [17], a parametric function $F$ receives a sequence of basic expressions and returns a first order function. Parametric functions can be instantiated to form an unbounded number of functions from a single pattern. For example, $\text{def addC} = \lambda x: \text{Int}. \lambda y: \text{Int}. x + y: \text{Int}$ can create any first order function which adds a constant to its argument, e.g., $\text{addC}(1) = \lambda x: \text{Int}. 1 + x: \text{Int}$ and $\text{addC}(2) = \lambda x: \text{Int}. 2 + x: \text{Int}$.

The program’s main expression is comprised of a sequence of let expression which bind general expressions to variables. A general expression is either a basic expression ($e$), an RDD expression ($\mu$) or an aggregate expression ($\text{fold}(e, f)(\eta)$). The expression $\text{cartesian}(\eta, \eta')$ returns the cartesian product of $\eta$ and $\eta'$. The expressions $\text{map}$ and $\text{filter}$ generalize the project and select operators in Relational Algebra (RA) [1,9], with user-defined functions (UDFs): $\text{map}(f)(\eta)$ produces an RDD by applying the unary UDF $f$ to every element $x$ of $\eta$. $\text{filter}(f)(\eta)$ evaluates to a copy of $\eta$ except that all elements in $\eta$ which do not satisfy $f$ are removed. The aggregate expression is a generalization of the aggregate operations in SQL, e.g., $\text{SUM}$ or $\text{AVERAGE}$, with UDFs: $\text{fold}(e, f)(\eta)$ accumulates the results obtained by iteratively applying the binary UDF $f$ to every element $x$ in an RDD $\eta$ in some arbitrary order together with the accumulated result obtained so far, which is initialized to the initial element $e$. If $\eta$ is empty, then $\text{fold}(e, f)(\eta) = e$.

Remarks. We assume that the signature of UDFs given to either map, filter, or fold match the type of the RDD on which they are applied. Also, to ensure that the meaning of $\text{fold}(e, f)(\eta)$ is well defined, we require, as Spark does [19], that $f$ be a commutative on its second argument, i.e., $\forall x, y_1, y_2. f(f(x, y_1), y_2) = f(f(x, y_2), y_1)$. For clarity, we omit the let expressions from examples, and write programs as a sequential composition of variable assignments.

Semantics of SparkLite We define a denotational semantics for SparkLite. As variables are never reassigned, we consider, without loss of generality, programs with no let expressions; these can always be eliminated by substituting every variable by its definition. Let $P$ be a SparkLite program and $\eta$ its main expression.
We first present a sound and complete technique for verifying the equivalence of programs. The class of SparkLite programs is undecidable; Theorem 2 indicates that the problem is undecidable even if we only consider programs containing a single aggregate operation. Thus, in this section, we explore various techniques for verifying program equivalence for restricted classes of SparkLite programs.

3 Verifying Equivalence of Programs without Aggregations

We first present a sound and complete technique for verifying the equivalence of NoAgg programs, the class of SparkLite programs that do not use aggregations.

Program terms. The first step of our technique is the construction of program terms: Given a program \( P \) with main expression \( \eta \), we generate an (intermediate) uninterpreted program term \( \phi(P) \) which, roughly speaking, reflects the effect of the program on arbitrary elements taken from its input RDDs. \( \phi(P) \) refers to functions by name. We produce the program term of \( P \), denoted by \( \Phi(P) \), by applying beta reduction according to the definition of every function in \( P \).

We obtain the uninterpreted program term of \( P \) by applying the translation function \( \phi \), shown in Figure 6, on \( P \)’s main expression. \( \phi \) recursively traverses the expression and generates a first-order logical term over the vocabulary of built-in operations and UDFs defined in \( P \). The base cases of the recursion are plain arithmetic expressions \( e \) and RDD variables \( r \). \( \phi \) acts as the identity function for expressions and replaces any input RDD variable \( r \) with a fresh variable \( x_r \) which we refer to as \( r \)’s representative variable. Strictly speaking, the latter transformation is not necessary technically. It is done merely to emphasize that \( x_r \) is used to represent an arbitrary element of \( r \) and not a whole RDD. Translation of an RDD operation produces a term corresponding to the application of its UDF...
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We use which elements we pick from the RDD, the program would filter them out.

The cartesian product is translated to a pair of uninterpreted program terms to determine whether both program terms are equivalent to \( \phi \) treating possible assignment of their representative variables. Otherwise, the algorithm returns that two programs are equivalent iff they always return an empty RDD, in which case they are trivially equivalent. This check is done by asking the solver to determine whether both program terms are equivalent to \( \bot \), i.e., no matter which elements we pick from the RDD, the program would filter them out.

**Example 1.** Consider the main expression \( \eta = \text{filter}(\text{geq}(100))(\text{map}(\text{double})(R)) \) of the program \( P_1' \) obtained by inlining the let expressions in program \( P_1 \) (see Section 1), defining the doubling function as \( \text{double} = \lambda x.2*x \), and instantiating the parametric function \( \text{geq} = \lambda y.\lambda x.x \geq y \) to act as the condition of the filter. The uninterpreted program term of \( P_1' \) is \( \phi(\eta) = \text{ite}(\text{geq}(100))(\text{double}(x_R)), \text{double}(x_R), \bot) \) and its program term is \( \Phi(P_1') = \text{ite}(2*x_R \geq 100, 2*x_R, \bot) \). Intuitively, we can learn how \( P_1' \) affects every element of, e.g., input RDD \( \{2,2,103,64\} \), by treating \( \Phi(P_1') \) as a “function” of \( x_R \) and “applying” it to 2, 2, 103, and 64.

**Verifying equivalence.** In Figure 7 we present an algorithm for deciding the equivalence of NoAgg programs. \( FV(\phi(P)) \) denotes the set of free variables in the program term of \( P \). \( \text{RepVarSet}(\phi(P)) \) denotes the subset of \( FV(\phi(P)) \) comprised of representative variables. \( FV(P) \) denotes the sequence obtained from \( FV(P) \) by replacing every RDD variable \( r \) with its representative variable \( x_r \).

\[
\begin{align*}
\phi(e) &= e & \phi(\text{map}(f)(\mu)) &= f(\phi(\mu)) \\
\phi(r) &= x_r & \phi(\text{filter}(f)(\mu)) &= \text{ite}(f(\phi(\mu)) = \text{tt}, \phi(\mu), \bot) \\
\phi(\text{fold}(f,e)(\mu)) &= [\phi(\mu)]_{r,f} & \phi(\text{cartesian}(\mu_1,\mu_2)) &= (\phi(\mu_1),\phi(\mu_2))
\end{align*}
\]

Fig. 6. A translation of a general expression to an uninterpreted program term.

```plaintext
bool EqNoAgg(P1, P2):
if FV(P1) = FV(P2) then
  if RepVarSet(\phi(P1)) = RepVarSet(\phi(P2)) then
    return Valid(\forall FV(P1)(\text{ite} FV(\phi(P1)) = \phi(\phi(P2)))
  else
    return Valid(\forall FV(P1)(\phi(P1) \land \phi(P2) = \bot))
else
  return false;
```

Fig. 7. Algorithm for deciding equivalence for NoAgg programs. \( FV(\phi(P)) \) denotes the set of free variables in the program term of \( P \). \( \text{RepVarSet}(\phi(P)) \) denotes the subset of \( FV(\phi(P)) \) comprised of representative variables. \( FV(P) \) denotes the sequence obtained from \( FV(P) \) by replacing every RDD variable \( r \) with its representative variable \( x_r \).

on a single RDD element: A \( \text{map}(f)(\mu) \) operation is translated into a function application. A \( \text{filter}(f)(\mu) \) operation is translated to an \( \text{ite} \) expression which returns the program term of \( \mu \) on the \( \text{then} \) branch and \( \bot \) on the \( \text{else} \) branch. We use \( \bot \) to denote the non-existing value. \( \bot \) cannot be used in a program, and appears only in formulae to record the effect of filtering an element out of an RDD. The cartesian product is translated to a pair of uninterpreted program terms pertaining to its arguments. (For now, ignore the translation of \( \text{fold} \) operations.)

**Example 1.** Consider the main expression \( \eta = \text{filter}(\text{geq}(100))(\text{map}(\text{double})(R)) \) of the program \( P_1' \) obtained by inlining the let expressions in program \( P_1 \) (see Section 1), defining the doubling function as \( \text{double} = \lambda x.2*x \), and instantiating the parametric function \( \text{geq} = \lambda y.\lambda x.x \geq y \) to act as the condition of the filter. The uninterpreted program term of \( P_1' \) is \( \phi(\eta) = \text{ite}(\text{geq}(100))(\text{double}(x_R)), \text{double}(x_R), \bot) \) and its program term is \( \Phi(P_1') = \text{ite}(2*x_R \geq 100, 2*x_R, \bot) \). Intuitively, we can learn how \( P_1' \) affects every element of, e.g., input RDD \( \{2,2,103,64\} \), by treating \( \Phi(P_1') \) as a “function” of \( x_R \) and “applying” it to 2, 2, 103, and 64.

**Verifying equivalence.** In Figure 7 we present an algorithm for deciding the equivalence of NoAgg programs. The algorithm first checks if both uninterpreted program terms are defined using the same representative variables. If they are the same, the algorithm returns that the two programs are equivalent iff the program terms of both programs evaluate to the same value, including \( \bot \), for any possible assignment of their representative variables. Otherwise, the algorithm returns that two programs are equivalent iff they always return an empty RDD, in which case they are trivially equivalent. This check is done by asking the solver to determine whether both program terms are equivalent to \( \bot \), i.e., no matter which elements we pick from the RDD, the program would filter them out.

**Theorem 1 (Decidability of the NoAgg class).** Let \( P_1 \) and \( P_2 \) be NoAgg SparkLite program. \( P_1 \) is equivalent to \( P_2 \) iff EqNoAgg(\( P_1, P_2 \)) returns true.
The proof of the theorem (see Appendix C) is based on three key observations: (i) Let $R$ be the RDD returned by a `NoAgg` program $P$. For any element $x$, $x \in R$ if and only if $x$ can be generated by considering input singleton RDDs, containing the single elements of the input RDDs that contributed to the generation of $x$. This allows to determine that the RDDs produced by two programs contain the same elements by verifying that their program terms, as first-order terms, are equivalent. (ii) Because we forbid self-joins, the multiplicity of $x$ in $R$ can be calculated by summing the product of the multiplicities of every possible combination of single elements taken from the input RDDs that can generate $x$. This allows to determine that programs having equivalent program terms also agree on the multiplicities of elements in the output they produce by syntactically checking that the sets of representative variables used by the uninterpreted program term are equal. (iii) A program always returns an empty RDD iff its program term evaluates to ⊥ for any assignment for its free variables.

Example 2. Let $\text{cartesian}(\text{filter}(\text{geq}(100))(R_0), \text{map}(\text{double})(R_1))$ be the main expression of a program $P$. Thus, the program term of $P$ is $(\text{ite}(x_{R_0} \geq 100, x_{R_0}, \bot), 2 \ast x_{R_1})$. An arbitrary element $(a, b)$ can appear in the RDD $R$ that $P$ returns if $a \geq 100$ and $b$ is even. Moreover, (i) we can find $(a, b)$ in the output only if $a \in R_0$ and $b/2 \in R_1$, and (ii) we can construct singleton input RDDs that can generate any such pair, provided $a \geq 100$ and $b$ is even. Furthermore the multiplicity of an element $(a, b)$ in the output that $P$ produces in $R_0(a) \ast R_1(b/2)$, if $a \geq 100$ and $b$ is even. If $(a, b)$ is not of that form, then $\Phi(P)(a, b)$ evaluates to ⊥.

The reason we use the uninterpreted program terms to check that the sets of representative variables agree, and not, e.g., the program terms, is that programs may ignore the values found in the input RDDs. As a result, even if the programs have identical program terms, they may produce the same elements but with different multiplicities, as the following example illustrates.

Example 3. Let $P7(R_0, R_1) = \text{one} = \lambda x.1 \text{map}(\text{one})(R_0)$ and $P8(R_0, R_1) = \text{one} = \lambda x.1 \text{map}(\text{one})(R_1)$ be SparkLite programs. $P7$ and $P8$ have the same program term (the constant 1). Thus, the RDDs they produce would only contain 1s. However, $P7$ generates a 1 for every element in $R_0$ whereas $P8$ generate a 1 for every element in $R_1$. Hence, if the size of $R_0$ is different from that of $R_1$, the two programs would produce different outputs. Note that the uninterpreted program terms of $P7$ and $P8$ are $\text{one}(x_{R_0})$ and $\text{one}(x_{R_1})$, respectively, and that they have the same program term, namely 1. Our algorithm would find out that $\text{RepVarSet}(\phi(P5)) = \{x_{R_0}\} \neq \{x_{R_1}\} = \text{RepVarSet}(\phi(P6))$, and would determine that the programs are not equivalent.

Indeed, Lemma 1, proven in Appendix B, shows that programs that do not always produce empty RDDs can be equal only if their uninterpreted terms have equal sets of representative variables. However, if two programs always produce the empty RDD they are equal, regardless of the input RDDs they operate on. This is the reason we have to take special care of such programs.
Lemma 1. Let $P$ and $P'$ be NoAgg programs such that at least one of them does not always produce an empty RDD. If $\text{RepVarSet}(\phi(P)) \neq \text{RepVarSet}(\phi(P'))$ then the programs are not equivalent.

The underlying theory. EqNoAgg is sound regardless of the kind of basic expressions that programs can use, provided we have a sound technique for verifying validity of the generated formulae. It is complete whenever these formulae are in a decidable theory. Appendix A includes a description of a simple decidable extension to Presburger arithmetic which serves as the underlying theory of the formulae generated for SparkLite programs.

3.2 Verifying Equivalence of SparkLite Programs with Aggregation

In this section, we adapt our verification technique to handle programs containing aggregations. We focus on programs in classes $\text{Agg}^1$ and $\text{AggPair}^1_{\text{sync}}$ which have a single aggregation operation. For space reasons, we relegate to Appendix G the discussion of handling programs in classes $\text{Agg}^R$ and $\text{Agg}^n$, for which we provide sound techniques for verifying program equivalence by generalizing the technique we use for $\text{Agg}^1$ programs.

Program terms for aggregations. We first extend our notion of (uninterpreted) program terms to reflect the presence of fold operations. The resulting terms are no longer legal terms in first order logic. Thus, we cannot use them directly in formulae. Instead, we extract out of them a set of formulae whose validity, intuitively, amounts to the establishment of an inductive invariant regarding the effect of fold operations.

The construction of the uninterpreted program terms for fold operations is shown in Figure 6. We are using a special operator $[\phi(\mu)]_{i,f}$, where $\phi(\mu)$ is the uninterpreted term pertaining to the RDD being folded, $i$ is the initial value, and $f$ is the fold function. We refer to $[\phi(\mu)]_{i,f}$ as an aggregate term. Intuitively, an aggregate operator indicates that calculating the effect of the fold requires iterating over all the elements of $\mu$. Clearly, the translation of fold cannot be masqueraded as a first-order term.

Verifying equivalence of $\text{Agg}^1$ programs Arguably, the simplest class of programs with aggregations is the class of programs which return a primitive expression which depends on the result of the aggregation operation. Technically, a SparkLite program $P$ is in class $\text{Agg}^1$ if there is a an expression $g$ in Presburger Arithmetic which has a single free variable $x$ such that the uninterpreted program term of $P$ is of the form $g[[\phi(\mu)]_{i,f}/x]$, where $\mu$ is an RDD expression which does not include fold operations. Stated differently, $P$ is an $\text{Agg}^1$ program if $\phi(P)$ can be obtained by substituting $x$ in $g$ with the aggregate term pertaining to the application of a fold operation on $\mu$. In the following, we refer to $g$ as $P$’s top expression. By abuse of notation, we use the functional notation $g(t)$ as a shorthand for $g[t/x]$, the expression obtained by substituting the term $t$ with $g$’s free variable. Similarly, given an expression $e$ with two free variables $x$ and $y$, we write $e(t_1,t_2)$ as a shorthand for $e[t_1/x,t_2/y]$. Frustratingly, Theorem 2, proven
in Appendix D via a reduction from the halting problem for 2-counter machines, shows that verifying equivalence of \( \text{Agg}^1 \) programs is an undecidable problem.

**Theorem 2.** The problem of deciding whether two arbitrary \( \text{Agg}^1 \) SparkLite programs are equivalent is undecidable.

Lemma 2, proven in Appendix E, formalizes the sound method that we used in Section 1.1 to show that \( P3 \) and \( P4 \) (see Figure 2) are equivalent.

**Lemma 2 (Sound method for verifying equivalence of \( \text{Agg}^1 \) programs).**

Let \( P_1 \) and \( P_2 \) be \( \text{Agg}^1 \) programs such that \( \text{FV}(P_1) = \text{FV}(P_2) \). Assume that \( \phi(P_1) = g_1((\phi(\mu_1))_{i_1,f_1}) \) and \( \phi(P_2) = g_2((\phi(\mu_2))_{i_2,f_2}) \), where the definition of \( f_i \) in \( P_i \) is \( f_1 = \lambda x, y, e_1 \) and of \( f_2 \) in \( P_2 \) is \( f_2 = \lambda x, y, e_2 \). \( P_1 \) and \( P_2 \) are equivalent if and the following conditions hold:

\[
\text{RepVarSet}(\phi(\mu_1)) = \text{RepVarSet}(\phi(\mu_2)) \tag{2}
\]

\[
\text{valid}(\forall \text{FV}(P_1), g_1(i_1) = g_2(i_2)) \tag{3}
\]

\[
\text{valid}(\forall \text{FV}(P_1), M_1, M_2, g_1(M_1) = g_2(M_2) \implies g_1(e_1(M_1, \Phi(\mu_1))) = g_2(e_2(M_2, \Phi(\mu_2)))) \tag{4}
\]

Intuitively, Equations (3) and (4) formalize the concept of inductive reasoning described in Section 1.1 for the base of the induction and the induction step, respectively. Recall that \( \text{FV}(P) \) denotes the sequence obtained by replacing every RDD variable \( r \) in \( \text{FV}(P) \) with its representative variable \( x_r \). Equation (2) requires that the free variables of the folded RDD expressions use the same representative variables. The **NoAggEq** algorithm used this check to ensure that the produced RDDs agree on the multiplicities of elements. Here, we use this check for a similar purpose: It ensures that the two fold operations iterate over RDDs of the same size. Note that we do not require that the RDD folded by the two programs be equivalent. However, in Equation (4) we still use the fact that every element in the folded RDD can be produced by instantiating its program terms with elements from the input RDDs.

**Complete verification techniques for subclasses of \( \text{Agg}^1 \)** Lemma 2 provides a sound, but incomplete, verification technique. This means that there are cases in which a pair of equivalent programs does not satisfy one or more of the requirements of Lemma 2. (Note that the requirements of the lemma pertain to both programs being verified.) Luckily, some of these cases can be identified and subsequently have their equivalence verified using other methods.

**Constant folds.** As an appetizer, we consider a simple “corner case”, where the fold operation of the verified \( \text{Agg}^1 \) SparkLite program always returns the initial value. We refer to such programs as **programs with constant folds**. A program might have a constant fold if, for example, the fold UDF function always returns its first argument or if the folded RDD turns out to always be empty. More formally, let \( P_1 \) be an \( \text{Agg}^1 \) program such that \( \phi(P_1) = g_1((\phi(\mu_1))_{i_1,f_1}) \) and \( f_1 = \lambda x, y, e_1 \). We say that \( P_1 \) has a **constant fold** if the formula \( \forall \text{FV}(P_1), (i_1 = e_1)(x, \Phi(\mu_1))/y) \) is valid. Let \( P_2 \) be an \( \text{Agg}^1 \) program such that \( \phi(P_2) = g_2((\phi(\mu_1))_{i_2,f_2}) \) and
$f_2 = \lambda x, y, e_2$ such that $FV(P_1) = FV(P_2)$. Once we determine that both $P_1$ and $P_2$ have a constant fold, verifying their equivalence of $P_1$ and $P_2$ amounts to checking the validity of the formula $\forall FV(P_1). g_1(i_1) = g_2(i_2)$, i.e., that the values of the programs’ top expressions agree when their free variables are bound to their respective fold’s initial elements. (cf. Equation (3) in Lemma 2.)

Verifying equivalence of $AggPair_{sync}^1$ programs. In Section 1.1 we showed that although programs $P5$ and $P6$ do not satisfy the requirements of Lemma 2, we can verify their equivalence using a more specialized verification technique targeting $AggPair_{sync}^1$ programs. We now describe a sound and complete verification technique that can be used to verify if a pair of programs belongs to $AggPair_{sync}^1$, and if so, whether they are equivalent.

We define $AggPair_{sync}^1$ using a decidable semantic property of fold UDFs, aggregate terms, and the initial values, which we refer to as collapsing. Intuitively, the collapsing property states that any value produced by consecutive applications of the fold UDF can be obtained using a single application. For example, if the UDF is $\text{sum} = \lambda x, y. x + y$ and the initial value is 0, then the result obtained by applying $\text{sum}$ consecutively on any two elements $a$ and $b$ can also be obtained by applying $\text{sum}$ once on $a + b$. Note that if a program enjoys the collapsing property, it is possible to collapse any sequence of iterated applications of the fold UDF starting from the initial value, using a single application of the UDF.

Our complete verification technique is applicable for program that can collapse their aggregation in synchrony: Recall that the RDD being folded contains elements which are obtained via a sequence of map and filter operations applied to elements taken out of their program’s input RDDs. Intuitively, two programs collapse in synchrony if it is possible to construct the value used to collapse any two consecutive application of the fold UDF on elements in the folded RDD coming from the same input elements using an element that can be constructed using the same inputs. In the following, we denote by $FV_r(P)$ and $FV_b(P)$ the subsets of $FV(P)$ comprised of RDD, respectively, non-RDD, input formal parameters.

**Definition 1 (The $AggPair_{sync}^1$ class).** Let $P_1$ and $P_2$ be $Agg^1$ programs such that $FV(P_1) = FV(P_2)$. Assume that $\phi(P_1) = g_1([\phi(\mu_1)])_{i_1, f_1}$ and $\phi(P_2) = g_2([\phi(\mu_2)])_{i_2, f_2}$, where the definition of $f_1$ in $P_1$ is $f_1 = \lambda x, y, e_1$ and of $f_2$ in $P_2$ is $f_2 = \lambda x, y, e_2$. We say that the $P_1$ and $P_2$ belong together to $AggPair_{sync}^1$, denoted by $(P_1, P_2) \in AggPair_{sync}^1$, if the following conditions hold:

\[
\forall b, \bar{u}, \bar{v}. e_1(i_1, \Phi(\mu_1))[b/FV_b(P_1), \bar{u}/FV_r(P_1)] = \phi(\mu_1) \\
\land e_2(i_2, \Phi(\mu_2))[b/FV_b(P_2), \bar{u}/FV_r(P_2)] = \phi(\mu_2)
\]

Note that in Equation (6), all applications of the fold UDF functions agree on the values of the non-RDD input formal parameters used to “generate” the accumulated elements. Also note that checking if $(P_1, P_2) \in AggPair_{sync}^1$ involves
determining the validity an additional decidable formula, namely Equation (6).

Theorem 3 shows that verifying the equivalence of a pair of AggPair\textsuperscript{1}\textsubscript{sync} programs effectively reduces to checking that the effect of a single application of the fold UDFs is equal.

**Theorem 3 (Equivalence in AggPair\textsuperscript{1}\textsubscript{sync} is decidable).** Let P\textsubscript{1} and P\textsubscript{2} be Agg\textsuperscript{1} programs as in Lemma 2, such that \((P\textsubscript{1}, P\textsubscript{2}) \in \text{AggPair}^{1}_{\text{sync}}\). P\textsubscript{1} and P\textsubscript{2} are equivalent if and only if the following holds:

\[
\text{valid}(\forall FV(P_1). g_1(i_1) = g_2(i_2))
\]

\[
\text{valid}\left(\forall \vec{v}, \vec{w}, M_1, M_2. (M_1 = e_1(i_1, \Phi(\mu_1)[\vec{v}/FV(P_1)]) \land M_2 = e_2(i_2, \Phi(\mu_2)[\vec{v}/FV(P_1)])) \implies \text{Ind} \right)
\]

where Ind = \((g_1(M_1) = g_2(M_2) \implies g_1(e_1(M_1, \Phi(\mu_1))) = g_2(e_2(M_2, \Phi(\mu_2)))[\vec{w}/FV(P_1)])\]

\[
(7)
\]

4 Prototype Implementation

We developed a prototype implementation verifying the equivalence of Spark programs. The tool is written in Python 2.7 and uses the Z3 Python interface to prove formulas. We ran our experiments on a 64-bit Ubuntu host with a quad core 2.30 GHz Intel Core i5-6200U processor, with 8GB memory.

The tool accepts pairs of Spark program written using the Python interface, determines the class of SparkLite program they belong to, and verifies their equivalence using the appropriate method. The main technical challenge is the symbolic analysis of UDFs, given as pure Python code. For simplicity, we limit the tool to handle programs with up to two aggregations.

A total of 19 test-cases of both equivalent and non-equivalent instances were tested, including all the examples from this paper. The examples, listed in Figure 9 in Appendix H, were inspired by real Spark uses taken from [19, 28] and online resources (e.g., open-source Spark clients). They include join optimizations, different aggregations, and various UDFs. For each instance, the tool either verifies that the given programs are equivalent, or produces a counterexample, that is, an input for which the programs produce different outputs. All examples were checked in less than 0.2 seconds.

5 Conclusion and Future Work

The main conceptual contribution of this paper is that the problem of checking program equivalence of SparkLite programs, which reflect an interesting subset of Spark programs, can be modeled with formulas in a decidable fragment of first-order logic. We showed that while, in general, verifying equivalence of programs with aggregation is an undecidable problem, there are classes of programs where the problem can be decided. We provide a classification of programs with aggregation, and present sound, in certain cases complete, methods
for verifying equivalence. Most notably, we provide a complete verification method for $AggPair_{sync}^1$ SparkLite programs. We believe the foundations laid in this paper will lead to the development of tools that handle formal verification and optimization of clients written in Spark and similar frameworks, by building upon the concepts presented here and extending them to more elaborate structures, such as programs with nested aggregation and unions.
References

A decidable extension of Presburger Arithmetic suitable for SparkLite

Presburger Arithmetic. We consider a fragment of first-order logic (FOL) with equality over the integers, where expressions are written in the rather standard syntax specified in Figure 8. Disregarding the tuple expressions \((pe, \overline{pe})\) and ite, the resulting first-order theory with the usual \(\forall\) and \(\exists\) quantifiers is called the Presburger Arithmetic. The problem of checking whether a sentence in Presburger arithmetic is valid has long been known to be decidable [15, 24], even when combined with Boolean logic [2, 21]. For example, Cooper’s Algorithm [12] is a standard decision procedure for Presburger Arithmetic.

In this paper, we consider a simple extension to this language by adding a tuple constructor \((pe, \overline{pe})\), which allows us to create \(k\)-tuples, for some \(k \geq 1\), of primitive expressions, and a projection operator \(p_i(e)\), which returns the \(i\)-th component of a given tuple expression \(e\). We extend the equality predicate to tuples in a point-wise manner, and call the extended logical language Augmented Presburger Arithmetic (APA). The decidability of Presburger Arithmetic, as well as Cooper’s Algorithm, can be naturally extended to APA. Intuitively, verifying the equivalence of tuple expressions can be done by verifying the equivalence of their corresponding constituents.

**Proposition 1.** The theory of formulas over \(\mathbb{Z}^n\) with terms in the Augmented Presburger Arithmetic is decidable.

**Proof.** Let \(\varphi\) be a quantified formula over \(\bigcup_n \mathbb{Z}^n\) with terms in Augmented Presburger Arithmetic. We shall translate \(\varphi\) to a formula in Presburger Arithmetic. For any atom \(A\colon a = b\), where \(a, b \in \mathbb{Z}^k\) for some \(k > 0\), we build the following formula: \(\bigwedge_{i=1}^k p_i(a) = p_i(b)\) and replace it in place of \(A\). In the resulting formula, we assign new variable names, replacing the projected tuple variables: For \(a \in \mathbb{Z}^k\) we define \(x_{a,i} = p_i(a)\) for \(i \in \{1, \ldots, k\}\). Variable quantification extends naturally, i.e. \(\forall a\) becomes \(\forall x_{a,1}, \ldots, x_{a,k}\), and similarly for \(\exists\).

To be compatible with SparkLite’s requirements, it will be useful to discuss an extension of APA in which terms are allowed to contain two additional constructs: ite expressions, and \(\bot\) values. We denote this extension APA\(^+\), and show how formulas in APA\(^+\) can be converted to APA formulas.

The program terms may contain ite expressions, and \(\bot\) expressions, therefore we need to encode the formulas in APA. We present a translation procedure \(N\) for converting

---

\(^4\) We assume the reader is familiar with FOL, and omit a more formal description.

\(^5\) Originally, Presburger Arithmetic was defined as a theory over natural numbers. However, its extension to integers and booleans is also decidable. (See, e.g., [2].)

\(^6\) We denote infinities as \(+\infty, -\infty\) and extend the underlying domain \(\mathbb{Z}\) to hold elements which represent.

\(^7\) The complexity of Cooper’s algorithm is \(O(2^{2^{2p}})\) for some \(p > 0\) and where \(n\) is the number of symbols in the formula [23].
Arithmetic Expression \( ae := c \mid v \mid ae + ae \mid -ae \mid c \cdot ae \mid ae / c \mid ae \% c \)

Boolean Expression \( be := \text{true} \mid \text{false} \mid b \mid e = e \mid ac < ae \mid \neg be \mid be \land be \mid be \lor be \)

Primitive Expression \( pe := ae \mid be \)

Basic Expression \( e ::= pe \mid v \mid (pe, pe) \mid p_i(e) \mid \text{ite}(be,e,e) \)

c, v, and b denote integer numerals, integer variables, and boolean variables, respectively. % denotes the modulo operator.

Fig. 8. Terms of the Augmented Presburger Arithmetic

APA+ formulas to APA. Let \( \varphi \) be a formula. Following the standard notation of sub-terms, positions, and substitutions in [25], we use \( \varphi[p] \) to denote the sub-term of \( \varphi \) in a specific position \( p \) and by \( \varphi[r]_p \) the substitution of the sub-term in position \( p \) with \( r \). We use this notation to define \( N \). If \( \varphi[p] = \text{ite}(\varphi_1, \varphi_2, \varphi_3) \), then \( \varphi \) is converted to: \( (\varphi_1 \Rightarrow \varphi[p_2]) \land (\neg \varphi_1 \Rightarrow \varphi[p_3]) \). In addition, for every sub-term of the form \( \varphi[p] = f(t_1, \ldots, t_n) \), if some \( t_i \) is equal (syntactically) to \( \bot \), then \( \varphi[p] = \bot \), as there is no meaning to evaluating functions on \( \bot \) symbols, which represent non-existing RDD elements. Finally, we replace \( t_i \) with \( \bot \), \( \bot \) with \( \bot \), and \( \bot \) with \( \bot \), and \( \bot \) with \( \bot \), such that there is an element in the RDD defined by \( p \).

Lemma 1 follows directly from the following lemma. Lemma 3 shows that in two programs without aggregations, different sets of representative variables of the terms imply the existence of input RDDs for which the two program terms evaluate to different bags, thus they are semantically inequivalent.

Lemma 3. Let there be two programs \( P_1, P_2 \in \text{NoAgg} \), over input RDDs \( \mathfrak{r} \) and program terms \( \phi_i(P_i) = t_i \), such that \( \text{RepVarSet}(t_1) \neq \text{RepVarSet}(t_2) \), and \( t_1 \neq \bot \lor t_2 \neq \bot \). Then, \( \exists \mathfrak{r}. \llbracket t_1 \rrbracket(\mathfrak{r}) \neq \llbracket t_2 \rrbracket(\mathfrak{r}) \).

Proof. By symmetry, we assume without loss of generality \( t_1 \neq \bot \). Therefore, there is an element in the RDD defined by \( t_1 \): \( \exists \mathfrak{r}, y. y = t_1(\mathfrak{r}) \land y \neq \bot \). Denoting \( \mathfrak{r} = (x_1, \ldots, x_l) \), we choose input RDDs \( \mathfrak{r} \) such that each input RDD has a single element \( x_i \) of multiplicity \( n_i \): \( r_i = \{ x_i ; n_i \} \), for \( i = 1, \ldots, l \). If \( t_2(\mathfrak{r}) \neq \bot \) then \( \llbracket t_1 \rrbracket(\mathfrak{r}) \neq \llbracket t_2 \rrbracket(\mathfrak{r}) \), as required. Otherwise, the multiplicity of \( y \) in \( t_1 \) is \( \Pi_{x_i, e \in \text{RepVarSet}(t_1)} n_i \), and in \( t_2 \) it is \( \Pi_{x_i, e \in \text{RepVarSet}(t_2)} n_i \). As \( \text{RepVarSet}(t_1) \neq \text{RepVarSet}(t_2) \), there are \( n_i > 1 \) such that \( \Pi_{x_i, e \in \text{RepVarSet}(t_1)} n_i \neq \Pi_{x_i, e \in \text{RepVarSet}(t_2)} n_i \); thus \( \llbracket t_1 \rrbracket(\mathfrak{r}) \neq \llbracket t_2 \rrbracket(\mathfrak{r}) \), as required.

For brevity, we omit the technical details of these standard definitions.
C Proof of Theorem 1

Proof. For non-RDD return types, the proof follows from Proposition 1, as the returned expression is expressible in APA. Therefore, let us assume that the return type is an RDD. For RDD return type, we use the algorithm EqNoAgg in Figure 7, which is a decision procedure, as we shall prove.

We begin with the following lemma:

Lemma 4. Let \( P \) be a NoAgg program with inputs \( R_1, \ldots, R_k, y_1, \ldots, y_m \), returning an RDD \( R \), and \( \text{RepVarSet}(\phi(P)) = x_{R_{j1}}, \ldots, x_{R_{jm}} \). We denote \( \hat{R} = \Pi_{\{j|x_{R_j} \in \text{RepVarSet}(\phi(P))\}} R_j \). By abuse of notation we mark the term of the RDD using \( \Phi \), and identify the program \( P \) with its returned RDD \( R \). Then:

\[
\forall x \in R. R(x) = \sum_{(v_1, \ldots, v_k) \in \hat{R}} \hat{R}(v_1, \ldots, v_k) \tag{9}
\]

\[
(\exists v_1, \ldots, v_k. R(v_1, \ldots, v_k, y_1, \ldots, y_m) = x \land x \neq \bot) \iff x \in R \tag{10}
\]

Proof. We prove by structural induction on the NoAgg program \( P \) after inlining. \( P \) is actually a shorthand for the RDD returned. We apply the induction on all operations except for \texttt{fold}, which is irrelevant to the NoAgg class.

- No operation—return an input RDD (\( P = \texttt{return} R_i \)): We have \( \phi(P) = x_{R_i} \), and \( \hat{R}_i = R_i \).
  
  Equation (9) follows immediately, as \( \hat{R}_i = R_i \):
  \[
  \sum_{v_i \in \hat{R}_i} \hat{R}_i(v_i) = R_i(x)
  \]
  and so does Equation (10).

- Map (\( P = \texttt{map}(R)(f) \)): We have \( \phi(P) = f(\phi(R)) \), and thus \( \hat{P} = \hat{R} \). We know by induction that
  \[
  \forall x \in R. R(x) = \sum_{(v_1, \ldots, v_k) \in \hat{R}. \Phi(R)(v_1, \ldots, v_k, y_1, \ldots, y_m) = x} \hat{R}(v_1, \ldots, v_k)
  \]
  Let \( x' \in \text{map}(R)(f) \). From the semantics of SparkLite, we know that there are elements \( z_1, \ldots, z_l \in R \) such that \( f(z_i) = x' \). Therefore, the multiplicity of \( x' \) in \( P \) is the sum of multiplicities of all \( z_i \) in \( R \). Also, \( \Phi(\text{map}(R)(f))(v_1, \ldots, v_k, y_1, \ldots, y_m) = f(\Phi(R)(v_1, \ldots, v_k, y_1, \ldots, y_m)) = x' \). Then, Equation (9) follows:

  \[
  \text{map}(R)(f)(x') = \sum_{|z_i| = x} R(z_i) = \sum_{|z_i| = x} \sum_{(v_1, \ldots, v_k) \in \hat{R}. \Phi(R)(v_1, \ldots, v_k, y_1, \ldots, y_m) = z_i} \hat{R}(v_1, \ldots, v_k)
  \]

  Equation (10) follows immediately because \texttt{map} can not transform elements to \( \bot \); if \( x \in P \), there is a \( z \in R \) for which \( f(z) = x \), and then by induction we can
As we assumed there are no self products, we can say
\[ \exists \]

To prove Equation (10), we note that if \( \emptyset \) 
we receive:
\[ \sum_{v_1, \ldots, v_k} \Phi \]

Let \( x' \in \text{filter}(R)(f) \). From the semantics of SparkLite, if \( x' \in \text{filter}(R)(f) \), then \( f(x') = tt \). Therefore,
\[ \Phi(\text{filter}(R)(f))(v_1, \ldots, v_k) = \Phi(R)(v_1, \ldots, v_k) \]

The multiplicity of \( x' \) in \( \text{filter}(R)(f) \) is the same as that of \( x' \) in \( R \). Thus, we receive:
\[ \text{filter}(R)(f)(x') = R(x) \]
\[ = \sum_{(v_1, \ldots, v_k) \in R} \Phi(R)(v_1, \ldots, v_k) R(v_1, \ldots, v_k) \]
\[ \sum_{(v_1, \ldots, v_k) \in R} \Phi(\text{filter}(R)(f))(v_1, \ldots, v_k) R(v_1, \ldots, v_k) \]
Let \( x' \in \text{cartesian}(R, R') \). From the semantics of SparkLite, the multiplicity of \( x' = (x_1, x_2) \) is equal to product of the multiplicity of \( x_1 \in R \) and the multiplicity of \( x_2 \in R' \). Therefore,
as required. The proof of Equation (10) follows directly from applying it on each of the constituents in the structural induction and noting that the cartesian product can not make elements equal to \( \perp \) unless one of the constituents is equal to \( \perp \), and also that if one if the constituents is equal to \( \perp \), then the entire resulting pair is also equal to \( \perp \).

We continue with the proof of the correctness of the algorithm.

**Sound:** Need to prove: If \( \text{EqNoAgg}(P_1, P_2) \) returns true, then \( P_1 \) is equivalent to \( P_2 \). We assume towards a contradiction that \( P_1 \) is not equivalent to \( P_2 \). Therefore, there are input RDDs and parameters \( R, y \) such that either:

- Without loss of generality (by symmetry), \( \exists x \in P_1(R, y) \land x \notin P_2(R, y) \): As \( x \in P_1(R, y) \), we can deduce from Equation (10) in Lemma 4 that there are \( \bar{v} \in \bar{R} \) such that \( \Phi(P_1)(\bar{v}, \bar{y}) = x \). We also know that \( \text{EqNoAgg} \) returned true, thus either \( \text{RepVarSet}(\phi(P_1)) \neq \text{RepVarSet}(\phi(P_2)) \) and both program terms are equal to \( \perp \), which is impossible by Equation (10) (because \( \Phi(P_1)(\bar{v}, \bar{y}) = x \) and \( x \neq \perp \) by Equation (10)), or \( \text{RepVarSet}(\phi(P_1)) = \text{RepVarSet}(\phi(P_2)) \) and then \( \forall \bar{v} \Phi(P_1)(\bar{v}) = \Phi(P_2)(\bar{v}) \). But then, \( \Phi(P_2)(\bar{v}, \bar{y}) = x \), so from Equation (10) in Lemma 4, we get a contradiction: \( x \in P_2(R, y) \).

- \( \exists x P_1(R, y)(x) \neq P_2(R, y)(x) \): We can assume that \( x \in P_1(R, y) \land x \in P_2(R, y) \) (otherwise, we return to the case of the previous bullet), thus we can apply Equation (9) in Lemma 4. By the same deduction done in the previous bullet, we must have \( \text{RepVarSet}(\phi(P_1)) = \text{RepVarSet}(\phi(P_2)) \), and that \( \forall \bar{v} \Phi(P_1)(\bar{v}) = \Phi(P_2)(\bar{v}) \). Thus, we can set \( \bar{R} = \prod_{R_j \in \text{RepVarSet}(\phi(P_1))} R_j \), and have that:

  \[
  \sum_{v \in \bar{R} \Phi(P_1)(v, g) = x} \bar{R}(v) \neq \sum_{v \in \bar{R} \Phi(P_2)(v, g) = x} \bar{R}(v)
  \]

Therefore, \( \{ \bar{v} \in \bar{R} \Phi(P_1)(\bar{v}, \bar{y}) = x \} \neq \{ \bar{v} \in \bar{R} \Phi(P_2)(\bar{v}, \bar{y}) = x \} \). But this is a contradiction, because this would mean \( \forall \bar{v} \Phi(P_1)(\bar{v}) = \Phi(P_2)(\bar{v}) \) is invalid, contradicting the assumption that \( \text{EqNoAgg}(P_1, P_2) \) returns true.

**Complete:** Need to prove: If \( P_1 = P_2 \), then \( \text{EqNoAgg}(P_1, P_2) \) returns true. We assume towards a contradiction that \( \text{EqNoAgg}(P_1, P_2) \) returns false. Then, either (1) \( \text{RepVarSet}(\phi(P_1)) = \text{RepVarSet}(\phi(P_2)) \) and \( \exists \bar{v} \Phi(P_1)(\bar{v}, \bar{y}) \neq \Phi(P_2)(\bar{v}, \bar{y}) \), or (2) \( \text{RepVarSet}(\phi(P_1)) \neq \text{RepVarSet}(\phi(P_2)) \) and \( \exists \bar{v} \Phi(P_1)(\bar{v}, \bar{y}) \neq \perp \lor \Phi(P_2)(\bar{v}, \bar{y}) \neq \perp \).

If (1), then we take such a witness \( \bar{v} \), and write it explicitly as \( (v_1, \ldots, v_n) \). For each input RDD that its representative variable belongs to \( \text{RepVarSet}(\phi(P_1)) \), we generate \( R_1 \) such that \( R_1 = \{ v_i : 1 \} \). Otherwise, we pick it arbitrarily. We denote the sequence of RDDs generated as \( \bar{R} \). We assume without loss of generality that \( \Phi(P_1)(\bar{v}, \bar{y}) \neq \perp \). (Otherwise, \( \bar{v} \) is not a witness.) Then we denote \( z = \Phi(P_1)(\bar{v}, \bar{y}) \) and note that by Equation (10) in Lemma 4, \( z \in P_1(R, y) \). Furthermore, as we chose all multiplicities of \( v_i \in R_1 \) to be equal to 1, we can deduce that \( P_1(R, y) = \{ z : 1 \} \), and that \( P_2(R, y) = \{ z' : 1 \} \) for \( z' = \Phi(P_2)(\bar{v}, \bar{y}) \). As \( z \neq \Phi(P_2)(\bar{v}, \bar{y}) \), we can deduce that \( z \neq z' \), thus \( P_1(R, y) \neq P_2(R, y) \), contradicting the assumption that \( P_1 \) and \( P_2 \) are equivalent.
If (2), then we apply Lemma 1, and it immediately follows that $P_1$ and $P_2$ are not equivalent, in contradiction to our assumption.

D Proof of Theorem 2

Theorem 2 is a direct corollary of the following theorem.

**Theorem 4.** The halting problem for 2-counter machines (2CM) reduces to the problem of program equivalence in SparkLite (PE for short).

**Proof.** We show a reduction of the halting problem for 2CM to PE. Given a 2CM machine $\langle \{c_1, c_2\}, L, T \rangle$ where $c_1, c_2$ are counters in $\mathbb{N}$, $L \subset \mathbb{N}$ is a finite set of instruction locations, and $T$ is the transition function of the states, which are 3-tuples of the location, and counter values: $(l, n_{c_1}, n_{c_2})$. We denote by $s_i = (l_i, n_{i,c_1}, n_{i,c_2})$ the initial state of the machine, and $s_h = (l_h, n_{h,c_1}, n_{h,c_2})$ as the halting state of the machine. We generate the following instance of the PE problem:

$$f = \lambda S. x. T(S)$$

$P_9(R: RDD_{int})$: return $\text{fold}(s_i, f)(R) = s_h$

$P_{10}(R: RDD_{int})$: return $tt$

If the two programs are equivalent, then the 2CM never reaches $s_h$, and therefore does not halt. Otherwise, if there is some RDD $R$ such that $P_1$ returns $tt$, then the programs are not equivalent, and the 2CM halts after $|R|$ steps. The size of the input RDD $R$ determines how many steps the 2CM will make when simulated by $P_9$. In addition, as the number of locations in $L$ is finite, and as the allowed instructions in a 2CM are definable in our extended Presburger arithmetics, $T$, and consequently the fold UDF $f$, are also definable in the extended Presburger arithmetics. Thus, $P_9$ and $P_{10}$ are both valid SparkLite programs. Furthermore, $P_9$ belongs to the $Agg^1$ and so can $P_{10}$ (by taking $g = \lambda x. \text{True}$ to act on any aggregated term). Due to this, this is a reduction of the 2CM halting problem to the program equivalence problem in $Agg^1$.

E Proof of Lemma 2

**Proof.** (Lemma 2) First we recall the semantics of the fold operation on some RDD $R$, which is a bag. We choose an arbitrary element $a \in R$ and apply the fold function recursively on $a$ and on $R$ with a single instance of $a$ removed. We then write a sequence of elements in the order they are chosen by fold: $\langle a_1, \ldots, a_n \rangle$, where $n$ is size of the bag $R$. We also know that a requirement of fold UDFs is that they are commutative, so the order of elements chosen does not change the final result. We also remark that we extended the definition of $f_i$ in the underlying theory to $\bot$ arguments by setting $f_i(M, \bot) = M$ ($\bot$ is defined to behave as the neutral element for $f_i$, and cannot appear as the accumulated value argument to $f_i$). The motivation is to avoid updating the
intermediate value when \( f_i \) is applied on elements that were filtered out from the RDD previously. We denote \( R_1 = \mu_1, R_2 = \mu_2 \). To prove \( P1 \) and \( P2 \) are equivalent, we need to show that for every \( \bar{v} \) of assignments to \( \text{FV}(\{P\}) \). To prove \( g_1([\phi(\mu_1)]_{i_1,f_1})(\bar{v}) = g_2([\phi(\mu_2)]_{i_2,f_2})(\bar{v}) \), it is necessary to prove that:

\[
g_1(\text{fold}(i_1,f_1)(R_1))(\bar{v}) = g_2(\text{fold}(i_2,f_2)(R_2))(\bar{v})
\]

We set \( M_{j,0} = i_j \) for \( j = 1,2 \). Each element of \( R_1 \) and \( R_2 \) is expressible by providing a concrete valuation to the free variables of \( \mu_1 \) and \( \mu_2 \), namely, the vector \( \bar{v} \).

We prove the equality by induction on the size of the RDDs \( R_1, R_2 \), denoted \( n \). We choose an arbitrary sequence of \( n \) valuations \( \langle \bar{a}_1, \ldots, \bar{a}_n \rangle \), and plug them into the \text{fold} operation for both \( R_1, R_2 \). The result is two sequences of intermediate values \( \langle M_{1,1}, \ldots, M_{1,n} \rangle \) and \( \langle M_{2,1}, \ldots, M_{2,n} \rangle \). From the semantics of \text{fold}, we have that \( M_{j,i} = e_j(M_{j,i-1}, \Phi(\mu_j))(\bar{a}_i) \) for \( j = 1,2 \). Our goal is to show \( g_1(M_{1,n}) = g_2(M_{2,n}) \) for all \( n \).

Case \( n = 0 \): When \( R_1 = R_2 = \emptyset \), we have \( \text{fold}(i_1,f_1)(R_1) = i_1 \) and \( \text{fold}(i_2,f_2)(R_2) = i_2 \). From Equation (3), \( g_1(i_1) = g_2(i_2) \), as required.

Case \( n = i \), assuming correct for \( n \leq i - 1 \): By assumption, we know that the sequence of intermediate values up to \( i - 1 \) satisfies: \( g_1(M_{1,i-1}) = g_2(M_{2,i-1}) \). We are given the \( i \)'th valuation, denoted \( \bar{a}_i \). We need to show \( M_{1,i} = M_{2,i} \), so we use the formula for calculating the next intermediate value:

\[
M_{1,i} = e_1(M_{1,i-1}, \Phi(\mu_1)) \\
M_{2,i} = e_2(M_{2,i-1}, \Phi(\mu_2))
\]

We use Equation (4), plugging in \( \bar{v} = \bar{a}_i \), \( M_1 = M_{1,i-1} \), and \( M_2 = M_{2,i-1} \). By the induction assumption, \( g_1(M_{1,i-1}) = g_2(M_{2,i-1}) \), therefore \( g_1(M_1) = g_2(M_2) \), so Equation (4) yields:

\[
g_1(e_1(M_1, \Phi(\mu_1))) = g_2(e_2(M_2, \Phi(\mu_2))
\]

By substituting back \( M_j \) and the formula for the next intermediate value, we get: \( g_1(M_{1,i}) = g_2(M_{2,i}) \) as required.

F Proof of Theorem 3

Proof. Sound (if): We prove the equality \( g_1([\phi(\mu_1)]_{i_1,f_1})(\bar{R}, \bar{g}) = g_2([\phi(\mu_2)]_{i_2,f_2})(\bar{R}, \bar{g}) \), by induction on the size of the RDDs \( \mu_1, \mu_2 \), denoted \( n \). It is important to note that not every \( n \) can be a legal size of the RDDs. For example, if \( R_1 = \text{cartesian}(R, R) \), then its size must be quadratic (\( |R|^2 \)). The induction we apply here, is actually stronger than what is required for equivalence, because we prove the equivalence even for subsets of the RDDs which may not be expressible using SparkLite operations. In any case, the soundness argument is valid.

The comment in footnote 9 regarding the validity of the soundness argument, even if \( \mu_i \) can not have size \( n \), is still valid here.
We say that $\mu_2(\bar{r}, \bar{y}) = \emptyset$, thus $[\phi(\mu_2)]_{i_j, f_j} = i_j (j = 1, 2)$, and the equality follows from Equation (7). Assuming for $n$ and proving for $n + 1$: We let a sequence of intermediate values $M_{j,k}$, $(j = 1, 2; k = 1, \ldots, n + 1)$, for which we know in particular that $g_1(M_{1,n}) = g_2(M_{2,n})$, and we need to prove $g_1(M_{1,n+1}) = g_2(M_{2,n+1})$. We denote $M_{1,0} = i_1$, and then we have $M_{j,k} = e_j(M_{j,k-1}; \Phi(\mu_j))$ for some $a_{\bar{y}}$. According to Equation (6): $\forall \mathrm{FV}_1(P_j), \mathrm{FV}_2(P_j).M_{j,2} = e_j(M_{j,1}; \Phi(\mu_j)) = e_j(e_j(i_j, \Phi(\mu_j)), \Phi(\mu_j))$ yields:

$$\exists \bar{a}_2'. \bar{A}_{j=1,2} M_{j,2} = e_j(i_j, \Phi(\mu_j))[a_2'/\mathrm{FV}(P_j)].$$

We can thus use Equation (6) to prove by induction that $\exists \bar{a}_k'. \bar{A}_{j=1,2} M_{j,k} = e_j(i_j, \Phi(\mu_j))[a_k'/\mathrm{FV}(P_j)]$, and in particular $\exists \bar{a}_n'. \bar{A}_{j=1,2} M_{j,n} = e_j(i_j, \Phi(\mu_j))[a_n'/\mathrm{FV}(P_j)]$. By applying Equation (8) for $\bar{v} = a_{n+1}$, $\bar{y} = a_n'$, we get: $(g_1(M_{1,n+1})) = g_2(M_{2,n+1}))$ as required.

**Complete (only if):** Assume towards a contradiction that either Equation (7) or Equation (8) are false. If the requirement of Equation (7) is not satisfied, yet the aggregates are equivalent, i.e.

$$(g_1([\phi(\mu_1)]_{i_1, f_1})) = g_2([\phi(\mu_2)]_{i_1, f_1}) \land g_1(i_1) \neq g_2(i_2)) [a/\mathrm{FV}(P_1)]$$

then we can get a contradiction by choosing all input RDDs to be empty, and choose input parameters according to $\bar{a}$. Thus, for $\bar{R} = \emptyset$, and $\bar{b} = \bar{a}$: $(\forall \phi(\mu_1)[\nu_{i_1, f_1} = 1 \land \phi(\mu_2)[i_1, f_2] = 1 \implies g_1(i_1) = g_2(i_2)) [a/\mathrm{FV}(P_1)]$, which is a contradiction. The conclusion is that Equation (7) is a necessary condition for equivalence. Therefore, we assume just Equation (8) is false. Let there be a counterexamples $\bar{v}, \bar{y}$ to Equation (8), 11 and let:

$$E_j = e_j(e_j(i_j, \Phi(\mu_j))[\bar{v}/\mathrm{FV}_1(P_j)], \Phi(\mu_j))[\bar{y}/\mathrm{FV}_2(P_j)]$$

Then $g_1(E_1) \neq g_2(E_2)$ is satisfiable. By Equation (6) we can write $E_j$ as: $E_j = e_j(i_j, x, \Phi(\mu_j), \bar{w}/\mathrm{FV}_1(P_j))$ for some $\bar{w}$. We take an RDD $R = \{\bar{w}_{\mathrm{rdd}}; 1\}$ where $\bar{w}_{\mathrm{rdd}}$ denotes the RDD variables of $\bar{w}$. We also denote the non-RDD variables of $\bar{w}$ as $\bar{b}$. Then $\mu_j(R) = \{\Phi(\mu_j)[\bar{w}/\mathrm{FV}_1(P_j)]; 1\}$, for which: $[\Phi(\mu_j)]_{i_1, f_1}(R) = E_j$. By the assumption, $g_1([\phi(\mu_1)]_{i_1, f_1})(R, \bar{b}) = g_2([\phi(\mu_2)]_{i_1, f_1})(R, \bar{b})$, but then $g_1(E_1)(R, \bar{b}) = g_2(E_2)(R, \bar{b})$. Contradiction.

### G Additional Classes with Sound Equivalence Verification Methods

A natural extension of the $\text{Agg}^1$ class is to programs that use an aggregated expression in another RDD operation. For example, filtering elements strictly larger than any element in another RDD: $\text{filter}(\lambda x. y > x)( \text{fold}(-\infty, \text{max})(R_1))(R_0)$, for which the program term is $\text{ite}(x_{R_0} > [x_{R_1}]_{-\infty, \text{max}}, x_{R_0}, \bot)$.

**Definition 2 (The $\text{Agg}^1_r$ class).** Let there be a program $P$ with $\phi(P) = \psi$. We say that $P \in \text{Agg}^1_r$ if $\psi$ contains a single aggregate term $[\phi(\mu)]_{i_1, f_1}$, which is

11 Note that the $M_i$ are determined immediately by choosing $\bar{v}$: $M_j = e_j(i_j, \Phi(\mu_j), [\bar{v}/\mathrm{FV}_1(P_j)])$. 

26
denoted \( \gamma \), and in addition, \( \varphi \) has no aggregate terms. We write \( \phi(P) = \psi[M/\gamma] \), where \( M \) is the value of the aggregate sub-term.

**Lemma 5 (Lifting Lemma 2 to \( \text{Agg}^2 \)).** Let two SparkLite programs \( P_1, P_2 \) in \( \text{Agg}^2 \), with terms \( \psi_i \) and aggregate expressions \( \gamma_j = [\phi(\mu_j)]_{i_1,j_1}, \) and \( f_j = \lambda x, y, e_j \) for \( j \in \{1, 2\} \). \( P_1 \) is equivalent to \( P_2 \) if:

\[
\text{RepVarSet}(\phi(\mu_1)) = \text{RepVarSet}(\phi(\mu_2))
\]

(11)

\[
\text{RepVarSet}(\phi(\psi_1)) = \text{RepVarSet}(\phi(\psi_2))
\]

(12)

\[
\forall FV(\psi_1) \cdot \psi_1[i_1/\gamma_1] = \psi_2[i_2/\gamma_2]
\]

(13)

\[
\forall \bar{u}, \bar{v}, M_1, M_2 \cdot (\psi_1[M_1/\gamma_1] = \psi_2[M_2/\gamma_2]) \Rightarrow (\psi_1[e_1(M_1, \Phi(\mu_1))][\bar{u}/\psi(FV(P_1))]/\gamma_1]) = \psi_2[e_2(M_2, \Phi(\mu_2))][\bar{v}/\psi(FV(P_2))]/\gamma_2])
\]

(14)

Proof. The proof follows along the lines of the proof of Lemma 2. We need to prove \( \Phi(P_1) = \Phi(P_2) \), or \( \forall FV(P_1), M_1, M_2, \psi_1[M_1/\gamma_1] = \psi_2[M_2/\gamma_2] \), where \( \gamma_j = [\phi(\mu_j)]_{i_j,j_j} \). We shall prove it by induction on the size of the RDDs \( \mu_1 \) and \( \mu_2 \), generating the underlying terms of \( \gamma_1 \) and \( \gamma_2 \).

For size 0, we have \( M_j = i_j \), and from Equation (13) we have \( \Phi(P_1) = \Phi(P_2) \) as required.

Assuming for size \( n \) and proving for \( n + 1 \): The RDDs \( \mu_1, \mu_2 \) are now generated using \( a_1, \ldots, a_{n+1} \), with intermediate values \( M_{j,1}, \ldots, M_{j,n+1} \) for \( j = 1, 2 \). By assumption, \( \forall FV(P_1) \cdot \psi_1[M_{1,n}/\gamma_1] = \psi_2[M_{2,n}/\gamma_2] \), and we need to prove \( \forall FV(P_1) \cdot \psi_1[M_{1,n+1}/\gamma_1] = \psi_2[M_{2,n+1}/\gamma_2] \). In addition:

\[
M_{j,n+1} = e_j(M_{i,n}, \Phi(\mu_i))[a_{n+1}/FV(P_j)]
\]

(15)

for \( j = 1, 2 \). Let some \( \bar{x} \) and we need to prove for it that:

\[
\psi_1[M_{1,n+1}/\gamma_1][\bar{x}/FV(P_1)] = \psi_2[M_{2,n+1}/\gamma_2][\bar{x}/FV(P_2)]
\]

(16)

We apply Equation (14) with \( \bar{x} \) as \( \bar{u}, \bar{v} = a_{n+1} \), and \( M_{1,n} \) and \( M_{2,n} \) as \( M_1 \) and \( M_2 \) respectively, concluding that:

\[
\psi_1[e_1(M_{1,n}, \Phi(\mu_1))[a_{n+1}/FV(P_1)]][\bar{x}/FV(P_1)] = \psi_2[e_2(M_{2,n}, \Phi(\mu_2))[a_{n+1}/FV(P_2)]][\bar{x}/FV(P_2)]
\]

(17)

Replacing for \( M_{j,n+1} \), we get what had to be proven.

The sound technique can be further generalized to programs with multiple aggregate terms, which are not nested — each aggregate term does not contain an aggregate term in its definition. We denote this class \( \text{Agg}^n \).

**Definition 3 (The \( \text{Agg}^n \) class).** Let there be a program \( P \) with \( \phi(P) = g(t_1, t_2, \ldots, t_n, a_{n}, f_n) \), or \( g(t_1, t_2) \) for short, and \( t_i = \Phi(\mu_i) \). \( P \in \text{Agg}^n \) if \( t_1, \ldots, t_n \) do not contain aggregate terms.

**Lemma 6.** Let \( P_1, P_2 \) be two programs in \( \text{Agg}^n \), such that \( \phi(P_j) = g_j([\phi(\mu_j)]_{i_j,j_j}) \) and \( f_j = \lambda x, y, e_j \) for \( j = 1, 2 \). We have \( g_1([\phi(\mu_1)]_{i_1,j_1}) = g_2([\phi(\mu_2)]_{i_2,j_2}) \) if:

\[
\forall f_1, f_2 \cdot \text{RepVarSet}(\phi(\mu_1, f_1)) = \text{RepVarSet}(\phi(\mu_2, f_2))
\]

(15)

\[
\forall FV(P_1). g_1(t_1) = g_2(t_2)
\]

(16)

\[
\forall FV(P_1), M_1, M_2 \cdot g_1(M_1) = g_2(M_2) \Rightarrow g_1(e_1(M_1, \Phi(\mu_1))) = g_2(e_2(M_2, \Phi(\mu_2)))
\]

(17)
We note that the subset of $Agg^n$ programs that can be handled with Lemma 6 could be extended if we relaxed Equation (15). We show a motivating example for relaxing Equation (15):

**Example 4.** Let two $Agg^n$ programs $P1, P2$ that sum the elements of an input RDD $R_0$. $P2$ will also apply a constant fold on input RDD $R_1$ and return the sum of the aggregations. As the fold on $R_1$ is constant, it will not affect the final result.

$$sum = \lambda A, x. A + x$$

$$zero = \lambda A, x. 0$$

$P11(R_0: RDD_{int}, R_1: RDD_{int})$:

$v = \text{fold}(0, sum)(R_0)$

return $v$

$P12(R_0: RDD_{int}, R_1: RDD_{int})$:

$v' = \text{fold}(0, sum)(R_0)$

$u = \text{fold}(0, zero)(R_1)$

return $v' + u$

We see that as $P12$ has an aggregate term with a set of representative variables equal to $\{x_{R_0}, x_{R_1}\}$ and $P11$ has $\{x_{R_0}\}$, and as a result Lemma 6 returns ‘not equivalent’, while $P11$ and $P12$ are actually equivalent, as $u$ is a constant fold.

In order to analyze such programs, we need to verify equivalence in the case one or more of the fold operations were completed. However, $Agg^n$ contains non-trivial programs, as the below example shows:

**Example 5 (Independent fold).** The below programs return a tuple containing the sum of positive elements in its first element, and the sum of negative elements in the second element. With Lemma 6, we are able to show the equivalence.

$h : (\lambda (P,N), x. \text{ite}(x \geq 0, (P + x, N), (P, N - x)))$

$P13(R: RDD_{int})$:

return $\text{fold}((0, 0), h)(R)$

$P14(R: RDD_{int})$:

$R_P = \text{filter}(\lambda x. x \geq 0)(R)$

$R_N = \text{map}(\lambda x. -x)(\text{filter}(\lambda x. x < 0)(R))$

$p = \text{fold}(0, \lambda A, x. A + x)(R_P)$

$n = -\text{fold}(0, \lambda A, x. A + x)(R_N)$

return $(p, n)$

$$\phi(P13) = [x_R]_{(0,0), h}; \quad \phi(P14) = ([\phi(R_P)]_{0,+}, -[\phi(R_N)]_{0,+})$$

$$\Phi(R_P) = \text{ite}(x_R \geq 0, x_R, \bot); \quad \Phi(R_N) = \text{ite}(x_R < 0, -x_R, \bot)$$

We set $g_1 = g_2 = \lambda (x, y). (x, y)$, and apply Lemma 6 to prove:

$$[x_R]_{(0,0), h} = ([\text{ite}(x_R \geq 0, x_R, \bot)]_{0,+}, -[\text{ite}(x_R < 0, -x_R, \bot)]_{0,+})$$

Equation (15) is satisfied: $\text{RepVarSet}(\phi(P)) = \{x_R\}$ for $i = 13, 14$. Induction base case (Equation (16)) is trivial. Induction step (Equation (17)) can be written simply as:

$$\forall x, A, B, C. p_1(A) = B \land p_2(A) = C \implies p_1(h(A, x)) = B + \text{ite}(x \geq 0, x, 0) \land p_2(h(A, x)) = C + \text{ite}(x < 0, -x, 0)$$
## Details of test-cases

Figure 9 shows a detailed view of all 19 test cases. The first column shows the class to which the program equivalence problem instance belongs, while the second and fourth columns show the programs themselves written concisely. In Figure 10 we specify the UDFs’ definitions.

<table>
<thead>
<tr>
<th>Class</th>
<th>Program 1</th>
<th>=?</th>
<th>Program 2</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>NoAgg</td>
<td>P1 (Section 1.1)</td>
<td>=</td>
<td>P2 (Section 1.1)</td>
<td>Verified</td>
</tr>
<tr>
<td>NoAgg</td>
<td>P1 (Section 1.1)</td>
<td>≠</td>
<td>P2 (Section 1.1)</td>
<td>changed to filter Found CEX elements smaller than 100</td>
</tr>
<tr>
<td>NoAgg</td>
<td>map(m2)(R1 x R2)</td>
<td>=</td>
<td>map((m2))(R1) x map((m2))(R2)</td>
<td>Verified</td>
</tr>
<tr>
<td>NoAgg</td>
<td>map(m2p1)(R)</td>
<td>≠</td>
<td>map((m2p1))(R)</td>
<td>Found CEX</td>
</tr>
<tr>
<td>NoAgg</td>
<td>filter((ba50))(R1 x R2)</td>
<td>=</td>
<td>filter((a50))(R1) x filter((a50))(R2)</td>
<td>Verified</td>
</tr>
<tr>
<td>NoAgg</td>
<td>filter((ea50))(R1 x R2)</td>
<td>≠</td>
<td>filter((a50))(R1) x filter((a50))(R2)</td>
<td>Found CEX</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{fold}(0,\text{count})(\text{filter}(\text{odd})(R)))</td>
<td>=</td>
<td>(\text{fold}(0,\text{sum})(\text{map}(\lambda((x,y),(z,w)).(x,(y,w))))(S1 \times S2))</td>
<td>Verified</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{sync}\ \text{fold}(1000,\text{min})(R))</td>
<td>≠</td>
<td>(-\text{fold}(100,\text{min})(\text{map}(\text{invert})(R)))</td>
<td>Found CEX</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{sync}\ \text{fold}(0,\text{sum})(R))</td>
<td>≥</td>
<td>(-\text{fold}(100,\text{min})(\text{map}(\text{invert})(R)))</td>
<td>Verified</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{sync}\ \text{fold}(0,\text{max})(R))</td>
<td>≠</td>
<td>(-\text{fold}(100,\text{min})(\text{map}(\text{invert})(R)))</td>
<td>Found CEX</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{map}(m2)(S1))</td>
<td>⊖(\triangleright)</td>
<td>(\text{map}(\lambda(((x, y), (z, w)).((x, y), w))(S1 \times S2)))</td>
<td>Verified</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{map}(dV)(S1)) x (\text{map}(dV)(S2))</td>
<td>=</td>
<td>(\text{map}(dV)(S1) \times S2)</td>
<td>Verified</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{map}(dV)(S1)) x (\text{map}(dV)(S2))</td>
<td>≠</td>
<td>(\text{map}(dA)(S1\times S2))</td>
<td>Found CEX</td>
</tr>
<tr>
<td>AggPair (1)</td>
<td>(\text{filter}(\text{odd})(S1)) x (\text{filter}(\text{odd})(S2))</td>
<td>=</td>
<td>(\text{filter}(\text{odd})(S1\times S2))</td>
<td>Verified</td>
</tr>
</tbody>
</table>

Fig. 9. Benchmarks. The \(\triangleq\) column records whether the programs are equivalent. The result column tells whether our tool verified the equivalence or found a counter example. R1, R2 represent RDDs of integer type. S1, S2 represent RDDs of pairs of integers. ‘A \times B’ is a shorthand for cartesian product of RDDs A and B. ‘S1\times S2’ is a shorthand for map(\(\lambda((x, y), (z, w)).((x, y), (z, w)))\((S1 \times S2))\).
\[ m2 = \lambda x. 2 \ast x \]
\[ m2p1 = \lambda x. 2 \ast x + 1 \]
\[ m3 = \lambda x. 3 \ast x \]
\[ \text{invert} = \lambda x. -x \]
\[ a50 = \lambda x. x \geq 50 \]
\[ ba50 = \lambda (x, y). x \geq 50 \land y \geq 50 \]
\[ ea50 = \lambda (x, y). x \geq 50 \lor y \geq 50 \]
\[ \text{min} = \lambda (x, y). \text{ite}(x < y, x, y) \]
\[ \text{max} = \lambda (x, y). \text{ite}(x > y, x, y) \]
\[ \text{dis} = \lambda x. x - 20 \]
\[ \text{sum} = \lambda (x, y). x + y \]
\[ \text{sMod5} = \lambda (x, y). (x + y) \% 5 \]
\[ \text{count} = \lambda (x, y). x + 1 \]
\[ \text{odd} = \lambda x. x \% 2 == 1 \]
\[ \text{oddk} = \lambda (x, y). x \% 2 == 1 \]
\[ \text{dd} = \lambda (x, y). (2 \ast x, 2 \ast y) \]
\[ \text{dV} = \lambda (x, y). (x, 2 \ast y) \]
\[ \text{deV} = \lambda ((x, y), (z, w)). ((x, 2 \ast y), (z, 2 \ast w)) \]
\[ \text{dA} = \lambda (x, (y, z)). (2 \ast x, (2 \ast y, 2 \ast z)) \]

Fig. 10. UDF definitions for Figure 9.