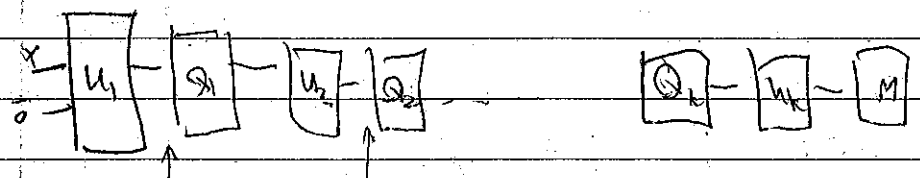


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no of search ... ?

... ?



...  $\varphi^{(0)}, \varphi^{(1)}, \varphi^{(k)}$

$$\varphi^{(k)} = \sum_x \alpha_x^{(k)} |x, \{x_t\}\rangle$$

...  $|\alpha_x^{(k)}|^2$

$$\sum_t \sum_x |\alpha_x^{(k)}|^2 = T$$

$$\sum_t |\alpha_{x_0}^{(k)}|^2 \leq \frac{T}{N}$$

$$\sum_t |\alpha_{x_0}^{(k)}| \leq \sqrt{\sum_t |\alpha_{x_0}^{(k)}|^2} \sqrt{T} \leq \frac{T}{\sqrt{N}}$$

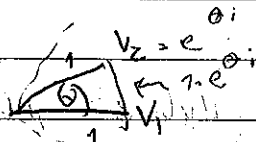
$x_0$  ...  $T \propto \sqrt{N}$

$g(x) = \begin{cases} 1 & x=x_0 \\ 0 & \text{else} \end{cases}$

10 ... (1)



2.  $\vec{v}_1 = v_1 \hat{e}_1$   $\vec{v}_2 = v_2 \hat{e}_2$   $\delta = \|\vec{v}_1 - \vec{v}_2\|$



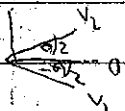
Case 1:  $\theta = 0$

$$\delta = v_1 - v_2$$

$$\delta = \|\vec{v}_1 - \vec{v}_2\| = \sqrt{v_1^2 + v_2^2 - 2v_1v_2\cos\theta}$$

$$\sin\frac{\theta}{2} = \frac{\delta}{2v}$$

Case 2:  $\theta = \pi$



$$\delta = \|\vec{v}_1 - \vec{v}_2\| = \sqrt{v_1^2 + v_2^2 + 2v_1v_2\cos\theta}$$

$$\delta = \begin{pmatrix} 0 & \sin\theta \\ \sin\theta & 0 \end{pmatrix}$$

$$-\lambda^2 = \lambda_1 \lambda_2 = -\sin^2\theta \quad \lambda_1 = \lambda_2 = \pm \sin\theta$$

$$|P_1 - P_2|_{\text{tr}} = |\lambda_1| + |\lambda_2| = 2\sin\theta$$

$$\left( \frac{1}{2} |P_1 - P_2| \right) = \frac{1}{2} |P_1 - P_2|$$

$$\sin\theta = \frac{|P_1 - P_2|}{2}$$

$$|\sin\theta| = \frac{2|\sin\frac{\theta}{2}\cos\frac{\theta}{2}|}{2} = |\sin\frac{\theta}{2}\cos\frac{\theta}{2}| \leq \frac{\delta}{2}$$

Case 3:  $\theta = \pi/2$

$$\frac{\delta}{\sqrt{N}} = \theta$$

$$\Gamma = \theta(\sqrt{N})$$

Case 4:  $\theta = \pi/4$

Case 5:  $\theta = \pi/3$